

# Kinematic Design

*A. Wingert, M.D. Lichter, and S. Dubowsky*

On the kinematics of parallel mechanisms with bi-stable polymer actuators

*K. Al-Widyan and J. Angeles*

The kinetostatic design of a Schönflies-motion generator

*F. Majou, P. Wenger, and D. Chablat*

Design of 2-DOF parallel mechanisms for machining applications

*E. Peisach*

Kinematically equivalent spatial mechanisms with revolute pair at input and prismatic pair at output

*A.M. Hay and J.A. Snyman*

The optimal synthesis of parallel manipulators for desired workspaces

*J. Hesselbach, M.B. Helm, and S. Soetebier*

Connecting assembly modes for workspace enlargement

*L. Baron, X. Wang, and G. Cloutier*

The isotropic conditions of parallel manipulators of Delta topology