

SUBJECT INDEX

AC/AC controlled power conversion 323
 Accuracy 80
 AC/DC controlled power conversion 323
 Activated sludge process 148
 ADA language 395
 Adaptive control 286,396
 Admittance measurement bridge 174
 AMD 9511 processor 87
 Analog-to-digital conversion 66
 Analysis μ P-based system 193
 Angle of advance for firing 339
 Anthropomorphic robot 351
 Applications of μ Ps 5
 Architectural convergence 227
 Armature current limiting 300
 Array system 168
 Assembly robot 363
 Asymmetric system 168
 Asynchronous firing control 334,338
 Automation 367
 Availability 370

 Backward difference method 51, 242
 Bandwidth 77
 Bilinear transformation method 54,241
 Bleach sequence optimization 400
 Bleaching chemicals 404
 Block pulse functions 125
 Bulk storage 105

 Cache memory 84
 Calibration 382
 Capabilities of μ Ps 4
 Car-speed control 418

 Cascade decomposition 61
 Causticization kiln 403
 Centralized analog control 394
 Centralized approach 371
 Chemical constraints 372
 Circuit-node algorithm 215
 Circuit-node architecture 215
 Classical controllers 241
 Closed-loop controller 207
 Column solver 214,217
 Common-bus systems 167
 Communication bus 36
 Commutation overlap 339
 Comparator functions 173
 Compensators 242
 Compliant motion 363
 Computational characteristics of μ Ps 239
 Computation frequency 355
 Computer-aided design 55
 Continuous conduction mode 305,310
 Continuous-path robots 349
 Continuous-time model 302
 Context switching 24
 Controlled rectifiers 323
 Controller:33
 -high level language 223
 - P-aided implementation 245
 -with observer 265
 Control interval limits 315
 Control list 210
 Control room displays 200
 Conversion error 80
 Converter blanking 340,342
 Co-processor 117
 Cromenco CS-3 computer 77
 Cross-bar system 167
 Cross-checking 383
 Current-rate control 293
 Cursor 87
 Cycloid 6

 Data acquisition 34,207,369

- Data base 85
- Data collection station 198
- Data Concentration 207
- Data highway 393
- Data processing 34
- Data-ready line 38
- Data transmission 170
- Data transfer 86
- DC drive system 292
- DC-motor control 284
- DC-servo μ Controller 268
- Dead-time compensation 396
- Debugging support 26
- Decentralized approach 371
- Difference map 203
- Digester control systems 399
- Digital-analog conversion 67
- Digital controllers 231,250, 314
- Digital filter
 - implementation 65
 - program 67
 - realization 58
- Digital firing control 332
- Digital frequency transformation 55
- Digital processing 100,103
- Digital protection relay 373
- DMA controller 26
- Direct form decomposition 60
- Direct list-execution 218
- Direct view oscilloscope 75
- Discrete-time observer 124
- Discretization:
 - backward difference 242
 - Tustin method 242
 - Z transform 241
- Discontinuous-conduction mode 307,312
- Distance protection 367
- Distance relay 373
- Distortion 80
- Distributed:
 - architecture 398
 - control 392,395
- Distribution of intelligence 394
- Disturbance torque input 301
- Drum timers 210
- Dual-data bus 220
- Dynamic shift registers 84
- Effective bits 84
- Eigenvalue controller 262
- Electrical constraints 371
- Electric traction 426
- Electron beam tube 83
- Energy management 407
- Energy saving train operation 421
- Environmental monitoring 407
- Error 77
- Evaluation μ P-based system 193
- Evaporators 401
- Executive programs 212
- Extended Kalman filter 146
- Factory floor 210
- Fail safe computer system 433
- Fault diagnostics 210
- Feedforward control 396
- Finite impulse response 47,56
- Finite word length effect 63
- Firing angle:325
 - limitations 315
 - sequence 304
- Firing control:
 - asynchronous 334,338
 - digital control 332
 - for multi-phase converter 323
 - natural sampling 335
 - regular sampling 335,336
 - synchronous 326,335
- Firing execution:
 - individual timer control 337
 - shared timer control 337
- Firing point determination 335
- FIR filter 56
- Floppy disc unit 85
- Fourier transform 77,88
- Frame transfer device 115
- Frequency:
 - sampling method 46,57

- warping phenomenon 54
- Functional modularity 356
- Graphic:
 - ladder diagram 210
 - programming languages 207
- General purpose algorithms 90
- Ground wood process 405
- Handshake control 85
- Hanford N reactor 190
- Hanning window function 91
- Hardware
 - functions 213
 - overview 107
 - realization 33
 - software tradeoff 19,185
- Harmonic control method 426
- Harvard architecture 210,211
- Heavy buses 381
- Hierarchical configuration 207
- High-level language controller 223,226
- High resolution 115
- High-speed data processing 200
- Hydraulic actuators 348
- Image:
 - chain analysis 101
 - conversion 10,101
 - display 100,106
 - enhancement 103
 - interactive processing 99, 103,107
 - processing software 110
 - processing system 100,107, 112, 114, 117, 201
 - reconstruction 103
 - restoration 103
- Implicit programming 364
- Impulse invariance method 48
- In-circuit emulator 27
- Induction motor drive 294,424
- Infinite impulse response 47, 48
- Input/output ports 36
- Insulation conditioning 375
- Intelligence distribution 394
- Intelligent sensors 394
- Integrated
 - approach 371
 - paper mill 390
- Intel 2920 processor 71
- Interaction decoupling 396
- Interactive computation 13
- Interface 34
- Interlocking system 431
- Interprocessor communication 377
- Inventory control 407
- I-P control 289
- Kamyr digester 387,399
- Kalman-Bucy filter 145,396
- Kinematic algorithm (robot) 358
- Landsat scene 105
- Light buses 381
- Lime kiln 403
- Linear interpolation 80
- Linear phase FIR filter 58
- Linear-quadratic controller 261
- Logic array 228
- Logic control 207
- Loosely coupled systems 28
- Man-machine interface 372
- Marshalling yard 419
- Matrix Riccati equation 145
- Mean execution time 13
- Measurement:
 - functions 171
 - systems 161
- Mechanical circuit 302
- Megatest Q-8000 180,181
- Microcontrollers 232,233
- Microprocessor:
 - advantages 163
 - architectures 211
 - based PWM inverter
 - based systems 164
 - filter implementation 156

- measurement functions 162
- overview 235
- Mill-wide hierarchy 389
- MIMO Controllers 257
- Minimum settling time control 284
- Minimum variance controllers 253,266
- Modern control theory 287
- Monitoring systems 411,412, 413,414
- Model-following controller 267
- Model-matching controller 264
- Model reference control 284
- Motor control system 285, 302
- Motor drive 283
- Motor reversal 317
- Multi-bus system
- Multilevel controllers 271
- Multiprocessing structure 383
- Multispectral:
 - imaging 114
 - system 112

- Natural commutation 323
- Natural sampling, firing control 335
- Noise contaminated outputs 129
- Nominal setting 381
- Nonlinear filters 146
- Nonlinear observers 131
- Nonrecursive realization 58
- Non-servo controlled robots 349
- N Reactor 190
- Nuclear plant data 189
- Nyquist:
 - plot 6
 - sampling theorem 80

- Observer implementation 121, 124
- Observer simulation 133
- On-line identification 396

- Operation menu 88
- Operator interface 359
- Operator system communication 174
- Optimal controller 271
- Output current control loop 340
- Overlap angle 339

- Paper machines 387,396
- Parallel:
 - form decomposition 62
 - organized controllers 234
 - processing 77
 - transformers 378
- Peripheral controller 19
- Phase control 332,333
- Phase controlled converters 326,327,328
- Phase controlled cycloconverters 323,328,329
- PH-control process 153
- Physical modularity 357
- Pick-and-place manipulators 348
- Picture elements 101
- PID controllers 8,244,246
- PIKKY program 110
- Pipe-line 376
- PLL-control 284,286,287
- Pneumatic actuators 348
- Pole-zero mapping 54
- Point-to-point robots 349
- Positioning accuracy 351
- Post-fault switching 369
- Power boilers 403
- Power converters 323
- Power map enlargement 202
- Power substation automation 367
- Precision specifications 308
- Princeton architecture 210, 211
- Processed TWFm trace 196
- Processing hardware 14
- Processing time limit 104
- Programmable controllers 212,221
- Programs:

- Digital transfer function 7
- Optimal control program 8
- PID DDC program 8
- Quality control 407
- Quantization error 39,79
- Quantization level 39
- Quantum efficiency 101
- Radial transformers 378
- Railway:
 - control 411
 - signalling systems 430
- Raw water 404
- Reaction time 218
- Reactor instrumentation 191
- Real-Time applications 13
- Recovery angle for thyristor 339
- Recovery boiler 402
- Recursive realization 58,59
- Reference signal:
 - DC 325, 326
 - time-varying 329-334
- Refiner process 405
- Regular firing 325
- Regular sampling 336
- Regulation schemes 378
- Reliability 370
- Remote sensing 99,112,114
- Revolute joint 354
- Robot:
 - degrees of freedom 347
 - equation of motion 352
- Robot programming:
 - lead through 350
 - plug-in 350
 - walk through 350
- Robust control 291
- Roll handling 407
- Root locus 243
- Round-off-error 285
- Route control 420
- Run-time support 23
- Sample command line 38
- Sampling rate 77
- SCADA (supervisory control and acquisition) 368
- Scheduler 383
- SCR firing angle limits 316
- SCR controlled machines 299
- Security 370
- Self-calibration 383
- Self-checking 383
- Self-diagnosis 383
- Self-selecting controller 269
- Self-tuned controllers 253, 258,269
- Sensitivity analysis 101,381
- Sensory systems 361
- Sentinel system 182
- Sequential controls 210
- Serial-parallel conversion 81
- Serve controlled robots 349
- Signal conditioning 80,375
- Signal processing:
 - algorithms 89
 - microprocessors 72
 - spectrum measurement 93
- Small deviation analysis 309
- Software:110
 - aspects 41
 - development 42
 - functions 213
 - implementation 395
- Solid state detectors 101
- Sorting sidings 419
- Special purpose algorithms 93
- Speed control:283,285,287, 307
 - with observer 290
- Standard development system 186
- State:
 - estimation 122,143
 - feedback controllers 260
 - observers 121,122,144,289
 - reconstruction 143
- Steady-state speed 300
- Step-invariance method 50
- Structural assembler 21
- Substation:
 - control 369
 - operation 369
 - protection 369

- Summation (integral) loop 309, 313
- Successive approximation 81
- Surge disturbances 371
- Surge protected input 381
- Synchronization points of thyristor firing 326,335
- Synchronous inverters 323
- Synchronous motor drive 295
- System interface 175
- System testing 177
- Tap changing power transformer 367
- Tap position 382
- Teaching box 350
- Teaching control systems 6
- Telecontrol 382
- Thermomechanical pulping 405
- Thyristor:
 - converter 292
 - firing execution 337
 - firing point determination 335
 - firing signal generation 338
 - synchronization points 326, 335
- Tightly coupled systems 28
- Time-shared basis 36
- Time window 79
- Timer 34
- Timing 33, 38
- Timing waves:
 - cosinusoidal 332,336
 - linear ramp 326,329,335
- Traffic control 415
- Train scheduling 416
- Train monitoring 411
- Train trajectory 422
- Transmission line protection 367,373
- Transient overvoltages 372
- Trip output 374
- TWFM systems 194
- Twin secondary transformers 368
- Unit delay 58
- Universal thyristor switch 424
- Vector addressing 226
- Vectored interrupt 18
- Vector table 111
- Virtual machine 24
- Voltage regulation systems 367
- Washing 401
- Waste water treatment 404
- Waveform memory 425
- Welding robot 362
- Windowing technique 47, 56
- Wood handling 404