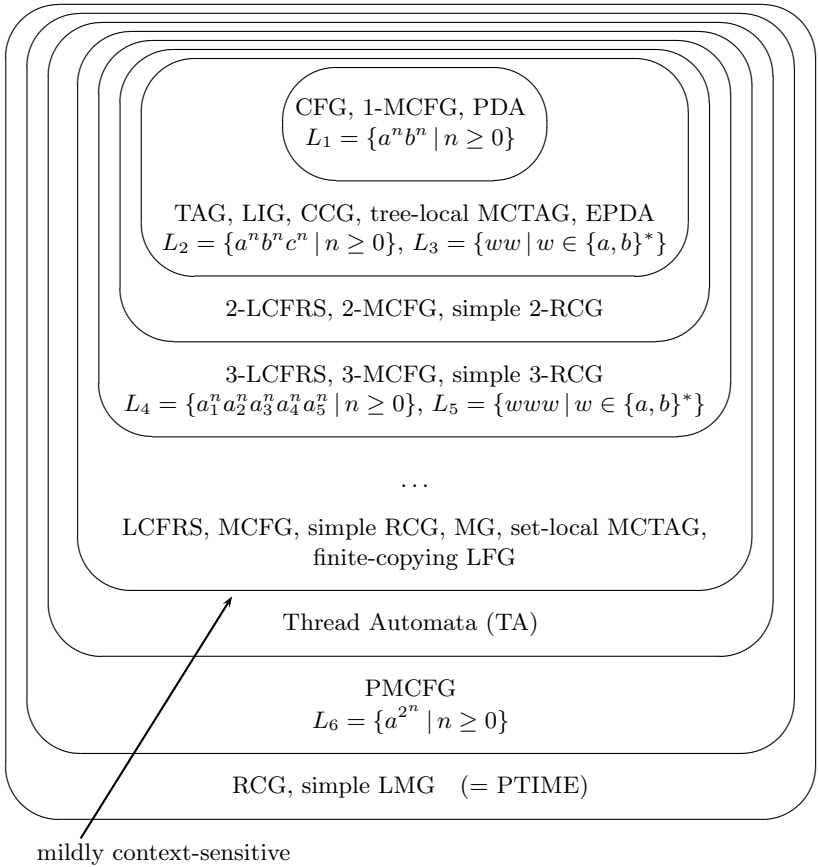

Appendix A: Hierarchy of Grammar Formalisms

The following figure recalls the language hierarchy that we have developed in the course of the book.



For each class the different formalisms and automata that generate/accept exactly the string languages contained in this class are listed. Furthermore, examples of typical languages for this class are added, i.e., of languages that belong to this class while not belonging to the next smaller class in our hierarchy. The inclusions are all proper inclusions, except for the relation between LCFRS and Thread Automata (TA). Here, we do not know whether the inclusion is a proper one. It is possible that both devices yield the same class of languages.

Appendix B: List of Acronyms

The following table lists all acronyms that occur in this book.

(2,2)-BRCG	Binary bottom-up non-erasing RCG with at most two variables per left-hand side argument
2-SA	Two-Stack Automaton
ACG	Abstract Categorical Grammar
AFL	Abstract Family of Languages
CCG	Combinatory Categorical Grammar
CFG	Context-Free Grammar
CNF	Chomsky Normal Form
EPDA	Extended Push-Down Automaton
FSA	Finite State Automaton
GCFG	Generalized Context-Free Grammar
GNF	Greibach Normal Form
HPSG	Head-Driven Phrase Structure Grammar
IG	Indexed Grammar
LCFRS	Linear Context-Free Rewriting System
LFG	Lexical Functional Grammar
LIG	Linear Indexed Grammar
LTAG	Lexicalized TAG
LMG	Literal Movement Grammar
MCFG	Multiple Context-Free Grammar
MCTAG	Multicomponent Tree Adjoining Grammar
MG	Minimalist Grammar
NRCG	Negative Range Concatenation Grammar
NPDA	Nested Push-Down Automaton
PDA	Push-Down Automaton
PMCFG	Parallel Multiple Context-Free Grammar
PRCG	Positive Range Concatenation Grammar
RCG	Range Concatenation Grammar
SD-2SA	Strongly-Driven Two-Stack Automaton

SNMCTAG	tree-local MCTAG with shared nodes
SRCG	Simple Range Concatenation Grammar
TA	Thread Automaton
TAG	Tree Adjoining Grammar
TSG	Tree Substitution Grammar
TT-MCTAG	Tree-Tuple MCTAG with Shared Nodes
V-TAG	Vector-TAG

Solutions

Problems of Chapter 2

2.1 $L_2 := \{a^n b^n \mid n \geq 0\}$

1. $G = \langle N, T, P, S \rangle$ with $N = \{S\}$, $T = \{a, b\}$, start symbol S and productions $S \rightarrow aSb$, $S \rightarrow \varepsilon$.
2. Assume that such a CFG exists. Its productions are then all of the form $X \rightarrow \alpha\alpha\beta b\gamma$ with $X \in N$, $\alpha, \beta, \gamma \in N^*$ such that if such a production is applied when generating a string $a_1 \dots a_n b_1 \dots b_n$, then the a and b of the production necessarily end up at positions i and $n+i$ for some i , $1 \leq i \leq n$. Then replacing each of these productions $X \rightarrow \alpha\alpha\beta b\gamma$ with $X \rightarrow \alpha\alpha\beta a\gamma$ and $X \rightarrow \alpha b\beta b\gamma$ leads to a CFG generating the copy language. This contradicts the fact that the copy language is not context-free. \square

2.2 A first homomorphism can be the homomorphism f from (Shieber, 1985).

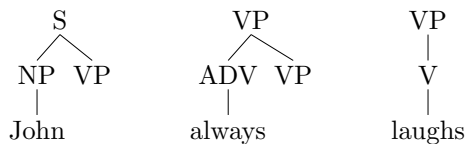
After having applied f to Swiss German, we intersect with the regular language $w\{a, b\}^*x\{c, d\}^*y$, which leads to $\{wv_1xv_2y \mid v_1 \in \{a, b\}^*, v_2 \in \{c, d\}^* \text{ such that } |v_1| = |v_2| \text{ and for all } i, 1 \leq i \leq |v_1|, \text{ if the } i\text{th symbol in } v_1 \text{ is an } a \text{ (a } b), \text{ the } i\text{th symbol in } v_2 \text{ is a } c \text{ (a } d)\}$.

Finally we apply a second homomorphism g to the result of the intersection with $g(w) := g(x) := g(y) := \varepsilon, g(a) := g(c) := a, g(b) := g(d) := b$.

This leads to the copy language.

2.3

There are several possibilities. The simplest one:



Linguistically, this is unsatisfying since the S node comes with the lexical item *John* even though it is the maximal projection of the verb. A lexicalized TSG for the given CFG where the S node comes with the verb is not possible.

2.4

1. The copy language $L := \{ww \mid w \in T^*\}$ is letter equivalent to $L' := \{ww^R \mid w \in T^* \text{ and } w^R \text{ is } w \text{ in reverse order}\}$, which is a CFL: It is generated by the CFG with productions $S \rightarrow \varepsilon$ and $S \rightarrow xSx$ for all $x \in T$. Consequently (with Parikh's theorem) L' and also L are semilinear. \square
2. Assume that $\{a^{2^n} \mid n \geq 0\}$ satisfies the constant growth property with c_0 and C . Then take a $w = a^{2^m}$ with $|w| = 2^m > \max(\{c_0\} \cup C)$. Then, according to the definition of constant growth, for $w' = a^{2^{m+1}}$ there must be a $w'' = a^{2^k}$ with $|w'| = |w''| + c$ for some $c \in C$. I.e., $2^{m+1} = 2^k + c$. Consequently (since $k \leq m$) $c \geq 2^m$. Contradiction. \square

Problems of Chapter 3

3.1

The items can have the form $[\bullet A, i, -]$, $0 \leq i \leq n$ (for predicted categories) and $[A\bullet, i, j]$, $0 \leq i < j \leq n$ (for completed categories). The goal item is $[S\bullet, 0, n]$. We need the following deduction rules:

1. An operation *scan-predict* that, starting from a predicted A -item, predicts a B -item, based on the existence of a production $A \rightarrow aB$:

$$\frac{[\bullet A, i, -]}{[\bullet B, i + 1, -]} \quad \text{there is a production } A \rightarrow aB \in P \text{ with } w_{i+1} = a.$$

2. An operation *scan* that turns a predicted A into a completed A based on the existence of a production $A \rightarrow a$:

$$\frac{[\bullet A, i, -]}{[A\bullet, i, i + 1]} \quad \text{there is a production } A \rightarrow a \in P \text{ with } w_{i+1} = a.$$

3. An operation *complete* that turns a predicted A into a completed A based on the existence of a completed B and a production $A \rightarrow aB$:

$$\frac{[\bullet A, i, -][B\bullet, i + 1, j]}{[A\bullet, i, j]} \quad \text{there is a production } A \rightarrow aB \in P \text{ with } w_{i+1} = a.$$

3.2

To show: If $[A \rightarrow \alpha \bullet \beta, i, j]$ then $S \xRightarrow{*} w_1 \cdots w_i A \gamma \Rightarrow w_1 \cdots w_i \alpha \beta \gamma \xRightarrow{*} w_1 \cdots w_j \beta \gamma$ for some $\gamma \in (N \cup T)^*$.

We show this by an induction on the deduction rules:

- Axioms: $\frac{}{[S \rightarrow \bullet \alpha, 0, 0]} \quad S \rightarrow \alpha \in P$

Trivially, if $[S \rightarrow \bullet \alpha, 0, 0]$ is obtained by this rule, then $S \xRightarrow{*} \varepsilon S \Rightarrow \varepsilon \alpha$.

- Predict: $\frac{[A \rightarrow \alpha \bullet B\beta, i, j]}{[B \rightarrow \bullet \gamma, j, j]} \quad B \rightarrow \gamma \in P$

We assume that the claim holds for the antecedent item. We then obtain (because of the production $B \rightarrow \gamma$) $S \xRightarrow{*} w_1 \cdots w_i A \gamma' \Rightarrow w_1 \cdots w_i \alpha B \beta \gamma' \xRightarrow{*} w_1 \cdots w_j B \beta \gamma' \Rightarrow w_1 \cdots w_j \gamma \gamma'$.

- Scan: $\frac{[A \rightarrow \alpha \bullet a\beta, i, j]}{[A \rightarrow \alpha a \bullet \beta, i, j + 1]} \quad w_{j+1} = a$

Since the claim holds for the antecedent item, with the side condition, it holds immediately for the consequent item.

- Complete: $\frac{[A \rightarrow \alpha \bullet B\beta, i, j], [B \rightarrow \gamma \bullet, j, k]}{[A \rightarrow \alpha B \bullet \beta, i, k]}$

Since the induction claim holds for the antecedent items, we have in particular $B \xRightarrow{*} w_{j+1} \cdots w_k$. With this and the claim for the antecedent A -item, we obtain $S \xRightarrow{*} w_1 \cdots w_i A \gamma' \Rightarrow w_1 \cdots w_i \alpha B \beta \gamma' \xRightarrow{*} w_1 \cdots w_j B \beta \gamma' \Rightarrow w_1 \cdots w_k \beta \gamma'$.

The algorithm is sound since, as a special case, we obtain for the goal items that $[S \rightarrow \alpha \bullet, 0, n]$ implies $S \Rightarrow \alpha \xRightarrow{*} w_1 \cdots w_n$.

3.3

The space complexity of the CYK algorithm is determined by the memory requirement for the chart. Since this is an $|N| \times n \times n$ table, we obtain a space complexity $\mathcal{O}(n^2)$.

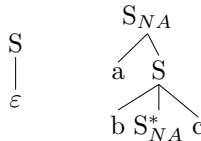
3.4

The most complex rule is **complete** with three indices ranging from 0 to n and with $|P|^2$ possible productions and $l_{rhs} = \max_{A \rightarrow \alpha \in P} (|\alpha| + 1)$ possible positions for the dot in the antecedent A -items. Note that, once the A -production is fixed, the position of the dot determines the left-hand side symbol of the second production. Let $m_{rhs} = \max_{A \in N} |\{A \rightarrow \alpha \in P\}|$. Then we have $\leq l_{rhs} \cdot |P| \cdot m_{rhs} (n + 1)^3$ possible different applications of **complete**. Consequently, as in the CYK case, the time complexity of the fixed recognition problem is $\mathcal{O}(n^3)$.

Problems of Chapter 4

4.1

1. TAG for L_3 :



2. Assume that a TAG G for L_3 without adjunction constraints exists. Assume without loss of generality that G contains no substitution nodes. G has at least one auxiliary tree β with leaves labeled with terminals. β must contain equal numbers of as , bs and cs . (Otherwise one could derive a word with different numbers of as , bs and cs .) One can adjoin β at its root, which leads to a derived auxiliary β' . If the yield of β is $a^i b^i c^i$ ($i \geq 1$), there are the following possibilities for the foot node:

- a) The foot node is left of all as or right of all $cs \Rightarrow$ using β' a word with substring $a^i b^i c^i a^i b^i c^i$ can be derived. Contradiction.
- b) The foot node is right of the k th a for some k , $1 \leq k \leq i \Rightarrow$ using β' a word with substring $a^{i-k} b^i c^i a^{i-k} b^i c^i$ can be derived. Contradiction.
- c) The foot node is right of the k th b for some k , $1 \leq k \leq i \Rightarrow$ using β' a word with substrings $a^i b^k a^i b^k$ and $b^{i-k} c^i b^{i-k} c^i$ can be derived. Contradiction.
- d) The foot node is left of the k th c for some k , $1 \leq k \leq i \Rightarrow$ using β' a word with substring $a^i b^i c^{k-1} a^i b^i c^{k-1}$ can be derived. Contradiction.

Consequently, there is no TAG without adjunction constraints for L_3 . \square

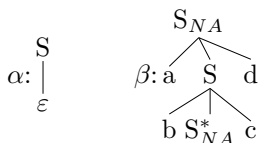
4.2 L_3 is a TAL \Rightarrow with closure under concatenation $\{w_1 w_2 \mid w_1, w_2 \in L_3\} = \{a^n b^n c^n a^m b^m c^m \mid n, m \geq 0\}$ is a TAL. \square

4.3 The copy language is a TAL and $a^* b^* a^* b^*$ is a regular language \Rightarrow with closure under intersection with regular languages, $\{uw \mid w \in \{a, b\}^*\} \cap a^* b^* a^* b^* = \{a^i b^j a^i b^j \mid i, j \geq 0\}$ is a TAL. \square

4.4 Assume that L is a TAL. Then the weak pumping lemma holds for some constant c . \Rightarrow For each word $w \in L$ with $|w| \geq c$ there is a $w' \in L$ with $|w'| \leq |w| + c$. This is a contradiction since for all $w \in L$ with $|w| > c$ this is not the case (for each $w \in L$ the $w' \in L$ following it wrt word length has twice its length). \square

4.5

1. TAG for L_4 :



2. Assume that L_5 is a TAL and satisfies the weak pumping lemma with some constant c . Take $w = a^{c+1} b^{c+1} c^{c+1} d^{c+1} e^{c+1}$. According to the pumping lemma one can find w_1, \dots, w_4 , at least one of them not empty, such that they can be inserted repeatedly at four positions into w yielding a new word in L_5 . At least one of the w_1, \dots, w_4 must contain two different terminal symbols since they altogether must contain equal numbers of as , bs , cs , ds and es . Then, when doing a second insertion of the w_1, \dots, w_4 ,

4.9

$$\begin{array}{ll}
S_0 \rightarrow S[\#] & \\
S[..\] \rightarrow aS_x[..]d & S_x[..\] \rightarrow S[x..\] \\
S \rightarrow T & T[x..\] \rightarrow bT[..\]c \\
T[\#] \rightarrow \varepsilon &
\end{array}$$

Problems of Chapter 5

5.1 Replace the deduction rules **move-unary** and **move-binary** with a single new rule **move-up**:

$$\frac{[\gamma, (p \cdot 1)_\top, i_0, f_{11}, f_{12}, i_1], \dots, [\gamma, (p \cdot m)_\top, i_{m-1}, f_{m1}, f_{m2}, i_m]}{[\gamma, p_\perp, i_0, f_{11} \oplus \dots \oplus f_{m1}, f_{12} \oplus \dots \oplus f_{m2}, i_m]}$$

As a side condition, we require that the node address $p \cdot (m + 1)$ does not exist in γ .

5.2

We keep the items $[\gamma, p_t, i, f_1, f_2, j]$ we had before (passive items) and add new active items $[\gamma, p, k, i, f_1, f_2, j]$ with

- γ an elementary tree, p a node position in γ , k the number of daughters of the node at p in γ that we have already seen;
- i, f_1, f_2, j as before.

The rules **move-unary** and **move-binary** are replaced with the following new rules:

1. A rule **left-corner predict** that, once we have seen the first daughter of a node, predicts the appropriate active item for its mother with $k = 1$.

$$\text{Left-corner predict: } \frac{[\gamma, (p \cdot 1)_\top, i, f_1, f_2, j]}{[\gamma, p, 1, i, f_1, f_2, j]}$$

2. A rule **complete** that, from an item telling us that we have seen the first k daughters of a node and another item telling us that we have the passive item of the $(k + 1)$ th daughter, deduces the active item telling us that we have seen the $k + 1$ daughters of the mother.

$$\text{Complete: } \frac{[\gamma, p, k, i_1, f_1, f_2, i_2][\gamma, (p \cdot (k + 1))_\top, i_2, f_3, f_4, i_3]}{[\gamma, p, k + 1, i_1, f_1 \oplus f_3, f_2 \oplus f_4, i_3]}$$

3. A rule **convert** that converts an active item where we have seen all the daughters into a passive item.

$$\text{Convert: } \frac{[\gamma, p, k, i, f_1, f_2, j]}{[\gamma, p_\perp, i, f_1, f_2, j]} \quad \text{address } p \cdot (k + 1) \text{ not defined in } \gamma$$

Anything else remains as before.

5.3

In our items we have only three indices, i, j, k , where i and k delimit the total span of the relevant part of the tree (these were i and l in the original algorithm). j gives the start position of the part below the foot node for left auxiliary trees.

The *Scan* and *Predict* rules remain more or less the same except for the reduced number of indices:

$$\text{ScanTerm} \frac{[\alpha, p, la, i, j, k, 0]}{[\alpha, p, ra, i, j, k + 1, 0]} \quad \alpha(p) = w_{k+1}$$

$$\text{Scan-}\varepsilon \frac{[\alpha, p, la, i, j, k, 0]}{[\alpha, p, ra, i, j, k, 0]} \quad \alpha(p) = \varepsilon$$

$$\text{PredictAdjoinable} \frac{[\alpha, p, la, i, j, k, 0]}{[\beta, 0, la, k, -, k, 0]} \quad \beta \in f_{SA}(\alpha, p)$$

$$\text{PredictNoAdj} \frac{[\alpha, p, la, i, j, k, 0]}{[\alpha, p, lb, k, -, k, 0]} \quad f_{OA}(\alpha, p) = 0$$

$$\text{PredictAdjoined} \frac{[\beta, p, lb, k, -, k, 0]}{[\delta, p', lb, k, -, k, 0]} \quad p = \text{foot}(\beta), \beta \in f_{SA}(\delta, p')$$

For the *Complete* rule, we obtain the following:

Complete

$$\frac{[\alpha, p, rb, i, j, k, 1][\beta, p', lb, i, -, i, 0]}{[\beta, p', rb, i, i, k, 0]} \quad p' = \text{foot}(\beta), \beta \in f_{SA}(\alpha, p)$$

Complete2 (remains the same)

$$\frac{[\beta, p, rb, i, j, k, \text{sat?}][\beta, p, la, h, -, i, 0]}{[\beta, p, ra, h, j, k, 0]} \quad \beta(p) \in N$$

For the *Adjoin* rule, we obtain the following:

Adjoin

$$\frac{[\beta, 0, ra, i, j, k, 0][\alpha, p, rb, j, l, k, 0]}{[\alpha, p, rb, i, l, k, 1]} \quad \beta \in f_{SA}(\alpha, p)$$

The *Move* rules and also the *Initialize* rule and the goal item remain the same, except for the reduced number of indices.

5.4

PredictSubstituted:

$$\frac{[\gamma, p, la, \sim, \sim, \sim, \sim, i, 0]}{[\alpha, \varepsilon, la, i, i, -, -, i, 0]} \quad \begin{array}{l} \alpha \in I, \gamma(p) \text{ substitution node,} \\ l(\gamma, p) = l(\alpha, \varepsilon) \end{array}$$

Substitute:

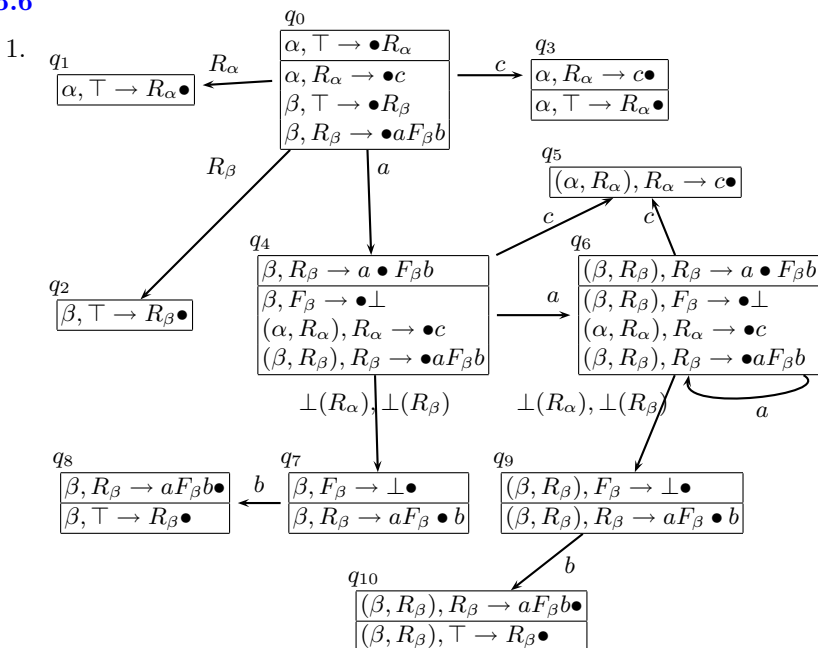
$$\frac{[\gamma, p, la, \sim, \sim, \sim, \sim, i, 0], [\alpha, \varepsilon, ra, i, i, -, -, j, 0]}{[\gamma, p, rb, \sim, i, -, -, j, 0]} \quad \begin{array}{l} \alpha \in I, \gamma(p) \text{ substitution node,} \\ l(\gamma, p) = l(\alpha, \varepsilon) \end{array}$$

Note that adjunction is not allowed at substitution nodes; therefore the adjunction flag 0 in the consequent item does not cause any problems.

5.5

Multiple adjunctions are avoided since *reduce_subtree* is applied only if $X_1 \dots X_m \in CS^+(N)$, i.e., if the stack contains a cross-section of the node N that is not N itself. After having traversed the tree adjoined at N and having returned to the node N by applying *reduce_aux_tree*, it is the node N itself that is on the stack.

5.6



2.

Stack	remaining input	operation
q_0	$aacbb$	<i>shift</i>
q_0aq_4	$acbb$	<i>shift</i>
$q_0aq_4aq_6$	cb	<i>shift</i>
$q_0aq_4aq_6cq_5$	bb	<i>reduce_subtree</i>
$q_0aq_4aq_6(\perp[R_\alpha])q_9$	bb	<i>shift</i>
$q_0aq_4aq_6(\perp[R_\alpha])q_9bq_{10}$	b	<i>reduce_subtree</i>
$q_0aq_4(\perp, [R_\beta, R_\alpha])q_7$	b	<i>shift</i>
$q_0aq_4(\perp, [R_\beta, R_\alpha])q_7bq_8$	ϵ	<i>reduce_aux_tree</i>
$q_0(R_\beta, [R_\alpha])q_2$	ϵ	<i>reduce_aux_tree</i>
$q_0R_\alpha q_1$	ϵ	<i>accept</i>

Problems of Chapter 6

6.1 There are of course different possibilities, for instance the following two MCFGs:

1. Rewriting rules: $S \rightarrow f_1[A] \quad A \rightarrow f_2[A] \quad A \rightarrow f_3[]$

Operations:

$$f_1[\langle X, Y, Z, U \rangle] = \langle XYZU \rangle$$

$$f_2[\langle X, Y, Z, U \rangle] = \langle aX, bY, cZ, dU \rangle$$

$$f_3[] = \langle a, b, c, d \rangle$$

2. Rewriting rules: $S \rightarrow f_1[A] \quad A \rightarrow f_2[A] \quad A \rightarrow f_3[]$

Operations:

$$f_1[\langle X, Y \rangle] = \langle XY \rangle$$

$$f_2[\langle X, Y \rangle] = \langle aXb, cYd \rangle$$

$$f_3[] = \langle ab, cd \rangle$$

6.2

Clauses:

$$S\langle XYZ \rangle \rightarrow A\langle Y \rangle B\langle X, Z \rangle$$

$$A\langle aX \rangle \rightarrow A\langle X \rangle \quad A\langle a \rangle \rightarrow \varepsilon$$

$$B\langle bX, bYb \rangle \rightarrow B\langle X, Y \rangle \quad B\langle \varepsilon, \varepsilon \rangle \rightarrow \varepsilon$$

- $yield(A) = \{ \langle a^n \rangle \mid n \geq 1 \}$
 $yield(B) = \{ \langle b^n, (bb)^n \rangle \mid n \geq 0 \}$.
- $\{ b^m a^n (bb)^m \mid n \geq 1, m \geq 0 \}$.
- For $w = abbb$,
 $r\text{-}yield(B) = \{ (\langle i, i \rangle, \langle j, j \rangle) \mid 0 \leq i, j \leq 4 \} \cup \{ (\langle 1, 2 \rangle, \langle 2, 4 \rangle), (\langle 3, 4 \rangle, \langle 1, 3 \rangle) \}$.

6.3

- $\{ a^n b^n c^m d^m a^n b^n c^m d^m \mid n, m \geq 0 \}$
- $\{ w_1 w_2 \mid w_1 \in \{ a, b \}^*, w_2 \text{ is the image of } w_1 \text{ under the homomorphism } f \text{ with } f(a) = b, f(b) = a \}$

6.4

1. Instantiations of $A\langle aX, bY \rangle \rightarrow A\langle X, Y \rangle$:

$$A\langle (0, 1), \langle 1, 2 \rangle \rangle \rightarrow A\langle \langle 1, 1 \rangle, \langle 2, 2 \rangle \rangle$$

$$A\langle (0, 1), \langle 2, 3 \rangle \rangle \rightarrow A\langle \langle 1, 1 \rangle, \langle 3, 3 \rangle \rangle$$

$$A\langle (0, 2), \langle 2, 4 \rangle \rangle \rightarrow A\langle \langle 1, 2 \rangle, \langle 3, 4 \rangle \rangle$$

$$A\langle (3, 4), \langle 1, 2 \rangle \rangle \rightarrow A\langle \langle 4, 4 \rangle, \langle 2, 2 \rangle \rangle$$

$$A\langle (3, 4), \langle 2, 3 \rangle \rangle \rightarrow A\langle \langle 4, 4 \rangle, \langle 3, 3 \rangle \rangle$$

2. Derivation of $abba$:

$$S\langle (0, 4) \rangle \Rightarrow A\langle (0, 2), \langle 2, 4 \rangle \rangle$$

$$\Rightarrow A\langle \langle 1, 2 \rangle, \langle 3, 4 \rangle \rangle$$

$$\Rightarrow A\langle \langle 3, 4 \rangle, \langle 1, 2 \rangle \rangle$$

$$\Rightarrow A\langle \langle 4, 4 \rangle, \langle 2, 2 \rangle \rangle$$

$$\Rightarrow \varepsilon$$

6.5 Let $k > 0$ be fixed.

We assume that the language $L = \{ w^{2k+1} \mid w \in \{ a, b \}^* \}$ is a k -MCFL.

Then its intersection with the regular language $(a^+ b^+)^{2k+1}$ must be a k -MCFL as well. This intersection yields $L' = \{ (a^n b^m)^{2k+1} \mid n, m > 0 \}$.

Complete:

$$\frac{[A \rightarrow g[\mathbf{B}]; (\Phi_1, R_j = \alpha \bullet B_k^{(i)} x, \Phi_2); \mathbf{\Gamma}], \quad [B_k \rightarrow f[\mathbf{C}]; (\Psi, R_l = \langle l_l, r_l \rangle \bullet, \Psi_1, y, \Psi_2); \mathbf{\Gamma}']}{[B_k \rightarrow f[\mathbf{C}]; (\Psi, R_l = \langle l_l, r_l \rangle, R_i = \langle m, m \rangle \bullet y, \Psi_1, \Psi_2); \mathbf{\Gamma}']}$$

y is the i th element
in the range constraint
vector of $B_k \rightarrow f[\mathbf{C}]$,
 m is the greatest range
boundary in α

The other operations and the goal item are the same as in the incremental algorithm with unconstrained prediction.

7.2

$$\begin{array}{ll} S(XYZU) \rightarrow A(X, Z)B(U, Y) & S(XYZ) \rightarrow A(X, Z)C(Y) \\ A(aX, aZ) \rightarrow A(X, Z) & A(\varepsilon, c) \rightarrow \varepsilon \\ B(Xb, Yb) \rightarrow B(X, Y) & B(\varepsilon, c) \rightarrow \varepsilon \\ C(aXY) \rightarrow D(X)C(Y) & D(d) \rightarrow \varepsilon \end{array}$$

1. Simplifying the grammar:

- a) Transform the grammar into an ordered simple RCG. (If the superscript is the identity, we omit it.)

The only problematic rule is $S(XYZU) \rightarrow A(X, Z)B(U, Y)$. It transforms into $S(XYZU) \rightarrow A(X, Z)B^{(2,1)}(Y, U)$.

Add $B^{(2,1)}(Yb, Xb) \rightarrow B(X, Y)$ and $B^{(2,1)}(c, \varepsilon) \rightarrow \varepsilon$.

Then, $B^{(2,1)}(Yb, Xb) \rightarrow B(X, Y)$ transforms into $B^{(2,1)}(Yb, Xb) \rightarrow B^{(2,1)}(Y, X)$.

In the following, for reasons of readability, we replace $B^{(2,1)}$ with a new symbol E .

Result:

$$\begin{array}{ll} S(XYZU) \rightarrow A(X, Z)E(Y, U) & S(XYZ) \rightarrow A(X, Z)C(Y) \\ A(aX, aZ) \rightarrow A(X, Z) & A(\varepsilon, c) \rightarrow \varepsilon \\ B(Xb, Yb) \rightarrow B(X, Y) & B(\varepsilon, c) \rightarrow \varepsilon \\ E(Yb, Xb) \rightarrow E(Y, X) & E(c, \varepsilon) \rightarrow \varepsilon \\ C(aXY) \rightarrow D(X)C(Y) & D(d) \rightarrow \varepsilon \end{array}$$

- b) Remove useless rules.

- $N_T = \{A, B, E, D, S\}$.

Consequently, remove $S(XYZ) \rightarrow A(X, Z)C(Y)$ and $C(aXY) \rightarrow D(X)C(Y)$.

- In the result, $N_S = \{S, A, E\}$.

Consequently, remove also $D(d) \rightarrow \varepsilon$, $B(Xb, Yb) \rightarrow B(X, Y)$ and $B(\varepsilon, c) \rightarrow \varepsilon$.

Result:

$$\begin{array}{ll} S(XYZU) \rightarrow A(X, Z)E(Y, U) & \\ A(aX, aZ) \rightarrow A(X, Z) & A(\varepsilon, c) \rightarrow \varepsilon \\ E(Yb, Xb) \rightarrow E(Y, X) & E(c, \varepsilon) \rightarrow \varepsilon \end{array}$$

- c) Remove ε -rules.

$$N_\varepsilon = \{A^{01}, A^{11}, E^{10}, E^{11}, S^1\}.$$

Resulting productions:

$$\begin{array}{l}
 S^1(XYZU) \rightarrow A^{11}(X, Z)E^{11}(Y, U) \quad S^1(YZU) \rightarrow A^{01}(Z)E^{11}(Y, U) \\
 S^1(XYZ) \rightarrow A^{11}(X, Z)E^{10}(Y) \quad S^1(YZ) \rightarrow A^{01}(Z)E^{10}(Y) \\
 A^{11}(aX, aZ) \rightarrow A^{11}(X, Z) \quad A^{11}(a, aZ) \rightarrow A^{01}(Z) \\
 A^{01}(c) \rightarrow \varepsilon \\
 E^{11}(Yb, Xb) \rightarrow E^{11}(Y, X) \quad E^{11}(Yb, b) \rightarrow E^{10}(Y) \\
 E^{10}(c) \rightarrow \varepsilon
 \end{array}$$

2. The string language generated by this grammar is

$$\{a^n cb^m a^n cb^m \mid n, m \geq 0\}.$$

7.3

We have to consider the maximal number of possible applications of the complete rule.

Complete:
$$\frac{[B, \rho_B], [C, \rho_C]}{[A, \rho_A]} \quad \begin{array}{l} A(\rho_A) \rightarrow B(\rho_B)C(\rho_C) \\ \text{is an instantiation of a } c \in P \text{ wrt. } w \end{array}$$

Since the maximal arity is k , we have maximal $2k$ range boundaries in each of the antecedent items of this rule. For variables X_1, X_2 being in the same left-hand side argument of the clause c , X_1 left of X_2 and no other variables in between, the right boundary of X_1 gives us immediately the left boundary of X_2 . In the worst case, A, B, C all have arity k and each left-hand side argument contains only two variables. This leads to $3k$ independent range boundaries and consequently a time complexity of $\mathcal{O}(n^{3k})$ for the entire algorithm.

7.4

The antecedent of the **Suspend** operation

$$\frac{[B(\psi) \rightarrow \Psi, pos', \langle i, j \rangle, \rho_B], [A(\phi) \rightarrow \dots B(\xi) \dots, pos, \langle k, l \rangle, \rho_A]}{[A(\phi) \rightarrow \dots B(\xi) \dots, pos', \langle k, l + 1 \rangle, \rho]}$$

contains two active items, the A -item and B -item.

Since our grammar is ε -free, all daughters (here the B -item) have yields with non-empty components. Therefore the position of the B -item is greater than the one of the A -item, $pos' > pos$, in a **suspend** operation. Consequently, the A -item is always added first to the chart and it is therefore sufficient to trigger **suspend** operations by the B -items.

Problems of Chapter 8

8.1 Clauses:

$$\begin{array}{ll}
 S(XY) \rightarrow A(X, Y)B(X, Y) & \\
 A(aX, aY) \rightarrow A(X, Y) & B(bX, bY) \rightarrow B(X, Y) \\
 A(bX, Y) \rightarrow A(X, Y) & B(aX, Y) \rightarrow B(X, Y) \\
 A(X, bY) \rightarrow A(X, Y) & B(X, aY) \rightarrow B(X, Y) \\
 A(\varepsilon, \varepsilon) \rightarrow \varepsilon & B(\varepsilon, \varepsilon) \rightarrow \varepsilon
 \end{array}$$

Input: $w = abba$

Instantiated clauses used:

instantiation	clause
1. $S(\langle 0, 4 \rangle) \rightarrow A(\langle 0, 2 \rangle, \langle 2, 4 \rangle)B(\langle 0, 2 \rangle, \langle 2, 4 \rangle)$	$S(XY) \rightarrow A(X, Y)B(X, Y)$
2. $A(\langle 0, 2 \rangle, \langle 2, 4 \rangle) \rightarrow A(\langle 0, 2 \rangle, \langle 3, 4 \rangle)$	$A(X, bY) \rightarrow A(X, Y)$
3. $A(\langle 0, 2 \rangle, \langle 3, 4 \rangle) \rightarrow A(\langle 1, 2 \rangle, \langle 4, 4 \rangle)$	$A(aX, aY) \rightarrow A(X, Y)$
4. $A(\langle 1, 2 \rangle, \langle 4, 4 \rangle) \rightarrow A(\langle 2, 2 \rangle, \langle 4, 4 \rangle)$	$A(bX, Y) \rightarrow A(X, Y)$
5. $A(\langle 2, 2 \rangle, \langle 4, 4 \rangle) \rightarrow \varepsilon$	$A(\varepsilon, \varepsilon) \rightarrow \varepsilon$
6. $B(\langle 0, 2 \rangle, \langle 2, 4 \rangle) \rightarrow B(\langle 1, 2 \rangle, \langle 2, 4 \rangle)$	$B(aX, Y) \rightarrow B(X, Y)$
7. $B(\langle 1, 2 \rangle, \langle 2, 4 \rangle) \rightarrow B(\langle 2, 2 \rangle, \langle 3, 4 \rangle)$	$B(bX, bY) \rightarrow B(X, Y)$
8. $B(\langle 2, 2 \rangle, \langle 3, 4 \rangle) \rightarrow B(\langle 2, 2 \rangle, \langle 4, 4 \rangle)$	$B(X, aY) \rightarrow B(X, Y)$
9. $B(\langle 2, 2 \rangle, \langle 4, 4 \rangle) \rightarrow \varepsilon$	$B(\varepsilon, \varepsilon) \rightarrow \varepsilon$

Derivation:

$$\begin{aligned}
S(\langle 0, 6 \rangle) &\Rightarrow A(\langle 0, 2 \rangle, \langle 2, 4 \rangle)B(\langle 0, 2 \rangle, \langle 2, 4 \rangle) && \text{(with 1.)} \\
&\Rightarrow A(\langle 0, 2 \rangle, \langle 3, 4 \rangle)B(\langle 0, 2 \rangle, \langle 2, 4 \rangle) && \text{(with 2.)} \\
&\Rightarrow A(\langle 1, 2 \rangle, \langle 4, 4 \rangle)B(\langle 0, 2 \rangle, \langle 2, 4 \rangle) && \text{(with 3.)} \\
&\Rightarrow A(\langle 2, 2 \rangle, \langle 4, 4 \rangle)B(\langle 0, 2 \rangle, \langle 2, 4 \rangle) && \text{(with 4.)} \\
&\Rightarrow B(\langle 0, 2 \rangle, \langle 2, 4 \rangle) && \text{(with 5.)} \\
&\Rightarrow B(\langle 1, 2 \rangle, \langle 2, 4 \rangle) && \text{(with 6.)} \\
&\Rightarrow B(\langle 2, 2 \rangle, \langle 3, 4 \rangle) && \text{(with 7.)} \\
&\Rightarrow B(\langle 2, 2 \rangle, \langle 4, 4 \rangle) && \text{(with 8.)} \\
&\Rightarrow \varepsilon && \text{(with 9.)}
\end{aligned}$$

8.2

- G_1 is simple since in all clauses, RHS arguments are single variables and each variable occurring in the clause occurs exactly once in its LHS and exactly once in its RHS.

$$L(G_1) = \{ca^{2n}b^kca^{2n}b^kca^{2n} \mid n > 0, k \geq 0\}.$$

- G_2 is a non-simple RCG, since the variable X is used twice in the RHS of $S(X) \rightarrow S_1(X)S_2(X)$ and therefore the grammar is not linear.

$$L(G_2) = \{a^n b^n c^k \mid n \geq 0, k \geq 1\} \cap \{a^k b^n c^n \mid k \geq 1, n \geq 0\} = \{a^n b^n c^n \mid n \geq 1\}$$

8.3

- L_1 can be generated by a simple RCG G_1 :

$G_1 = \{\{S, A\}, \{c, d\}, \{X, Y, U, V\}, S, P\}$ with P the following set of clauses:

$$\begin{aligned}
S(XYUV) &\rightarrow A(X, Y, U, V) \\
A(cX, cY, cU, cV) &\rightarrow A(X, Y, U, V) \\
A(dX, dY, dU, dV) &\rightarrow A(X, Y, U, V) \\
A(\varepsilon, \varepsilon, \varepsilon, \varepsilon) &\rightarrow \varepsilon
\end{aligned}$$

- L_2 can only be generated by a non-simple RCG G_2 .

$G_2 = \{\{S, eq\}, \{a\}, \{X, Y, Z\}, S, P\}$ with P the following set of clauses:

$$\begin{aligned}
S(XYZ) &\rightarrow S(X)eq(X, Y, Z) \\
S(a) &\rightarrow \varepsilon \\
eq(aX, aY, aZ) &\rightarrow A(X, Y, Z) \\
eq(a, a, a) &\rightarrow \varepsilon
\end{aligned}$$

8.4

1. L_1 can be generated by a linear non-erasing simple LMG G_3 containing the same clauses as the simple RCG for the same language.
2. L_2 can be generated by the following simple LMG G_4 .

$G_4 = \langle \{S\}, \{a\}, \{X\}, S, P \rangle$ with P the following set of clauses:

$$S(XXX) \rightarrow S(X)$$

$$S(a) \rightarrow \varepsilon$$

8.5

Equivalent simple 2-RCG:

$$S(X) \rightarrow \langle \alpha \rangle (X)$$

$$\langle \alpha \rangle (LR) \rightarrow \langle adj, \alpha, \varepsilon \rangle (L, R)$$

$$\langle \beta \rangle (aLb, cRd) \rightarrow \langle adj, \beta, 2 \rangle (L, R)$$

$$\langle adj, \alpha, \varepsilon \rangle (L, R) \rightarrow \langle \beta \rangle (L, R)$$

$$\langle adj, \beta, 2 \rangle (L, R) \rightarrow \langle \beta \rangle (L, R)$$

$$\langle adj, \alpha, \varepsilon \rangle (\varepsilon, \varepsilon) \rightarrow \varepsilon$$

$$\langle adj, \beta, 2 \rangle (\varepsilon, \varepsilon) \rightarrow \varepsilon$$

Problems of Chapter 9

9.1

Assume that we have a k -RCG.

For binarized RCGs, the **complete** rule amounts to the following:

$$\text{Complete: } \frac{[A_1, \rho_1], [A_2, \rho_2]}{[A_0, \rho]} \quad A_0(\rho_0) \rightarrow A_1(\rho_1)A_k(\rho_2) \text{ an instantiated clause}$$

In contrast to simple RCG, we cannot assume that the variables in the left-hand side occur also in the right-hand side. Therefore, in the worst case, there is no relation at all between these variables. We then obtain for the left-hand side that we have ≤ 3 range boundaries per argument and $\leq 3k$ range boundaries per clause. For the right-hand side, we get ≤ 2 range boundaries per argument and therefore $\leq 2 \cdot 2k$ range boundaries per clause. Consequently, we have a total of $\leq 3k + 4k = 7k$ range boundaries per clause that can have values between 0 and n .

Therefore, parsing with this algorithm for the restricted type of RCG considered here is $\mathcal{O}(n^{7k})$.

9.2

Clause $A(aX, Ya, \varepsilon) \rightarrow C(XY)$.

Range constraint vector $\langle \mathbf{r}, C \rangle$ with

- $\mathbf{r} = (\langle r_1, r_2 \rangle, \langle r_3, r_4 \rangle, \langle r_5, r_6 \rangle, \langle r_7, r_8 \rangle, \langle r_9, r_{10} \rangle)$,

- $C = \{r_1 \leq r_2, \dots, r_9 \leq r_{10},$
 $r_1 + 1 = r_2, r_7 + 1 = r_8,$
 $r_2 = r_3, r_4 = r_5, r_6 = r_7,$
 $r_9 = r_{10}\}$

9.3

Clauses of the RCG G :

$$S(XY) \rightarrow A(X, X)B(Y, Y)$$

$$A(aX, bY) \rightarrow A(X, Y) \quad B(cX, dY) \rightarrow B(X, Y)$$

$$A(bX, Y) \rightarrow A(X, Y) \quad B(dX, Y) \rightarrow B(X, Y)$$

$$A(X, aY) \rightarrow A(X, Y) \quad B(X, cY) \rightarrow B(X, Y)$$

$$A(\varepsilon, \varepsilon) \rightarrow \varepsilon \quad B(\varepsilon, \varepsilon) \rightarrow \varepsilon$$

1. $L(G) = \{w_1w_2 \mid w_1 \in \{a, b\}^* \text{ with } |w_1|_a = |w_1|_b \text{ and } w_2 \in \{c, d\}^* \text{ with } |w_2|_c = |w_2|_d\}$.
2. $First(A, 1) = First(A, 2) = \{a, b, \varepsilon\}$,
 $First(B, 1) = First(B, 2) = \{c, d, \varepsilon\}$.
3. Possible filters:
 - The components of A belong to $\{a, b\}^*$ while the components of B belong to $\{c, d\}^*$.
 - For every range vector $(\langle l_1, r_1 \rangle, \langle l_2, r_2 \rangle)$ in the yield of A or B , it holds that $r_1 = r_2$.

Problems of Chapter 10

10.1

Let $M = \langle Q, \Sigma, \Gamma, \delta, q_0, Q_F, Z_0 \rangle$ be the original EPDA.

$M' = \langle Q \cup \{q'_0, q_f\}, \Sigma, \Gamma \cup \{Z'_0\}, \delta', q'_0, \{q_f\}, Z'_0 \rangle$ with

- $q'_0 \neq q_f, q'_0, q_f \notin Q, Z'_0 \notin \Gamma$;
- δ' extends δ as follows:
 $\delta'(q'_0, \varepsilon, Z'_0) = \{(q_0, \varepsilon, Z'_0, \dagger\#\}$
 $\delta'(q_f, \varepsilon, Z'_0) = \{(q_f, \varepsilon, Z'_0, \varepsilon)\}$

In all other cases, δ' is defined as the original δ .

10.2

$M = \langle \{q_0, q_1, q_2, q_3\}, \{a, b\}, \{\#, A, B\}, \delta, q_0, \{q_3\}, \# \rangle$ with

$$\delta(q_0, \varepsilon, \#) = \{(q_3, \varepsilon, \varepsilon, \varepsilon), (q_1, \varepsilon, \#, \varepsilon)\}$$

$$\delta(q_1, a, X) = \{(q_1, \varepsilon, XA, \varepsilon)\}$$

$$\delta(q_1, b, X) = \{(q_1, \varepsilon, XB, \varepsilon)\}$$

$$\delta(q_1, \varepsilon, X) = \{(q_2, \varepsilon, X, \varepsilon)\}$$

$$\delta(q_2, \varepsilon, A) = \{(q_2, \dagger A, \varepsilon, \varepsilon)\}$$

$$\delta(q_2, \varepsilon, B) = \{(q_2, \dagger B, \varepsilon, \varepsilon)\}$$

$$\delta(q_2, \varepsilon, \#) = \{(q_3, \varepsilon, \varepsilon, \varepsilon)\}$$

$$\delta(q_3, a, A) = \{(q_3, \varepsilon, \varepsilon, \varepsilon)\}$$

$$\delta(q_3, b, B) = \{(q_3, \varepsilon, \varepsilon, \varepsilon)\}$$

where $X \in \Gamma$

10.3

1. The language is $\{ww^R \mid w \in \{a, b\}^+\}$.
2. Successful configurations for $w = abba$:

thread set	remaining input	operation
$\varepsilon : \mathbf{S}$	abba	
$\varepsilon : S, \mathbf{1} : \mathbf{S}'$	abba	$S \longrightarrow [S]S'$
$\varepsilon : S, \mathbf{1} : \mathbf{S}_A$	bba	$S \xrightarrow{a} S_A$
$\varepsilon : S, \mathbf{1} : S_A, \mathbf{11} : \mathbf{S}'$	bba	$S_A \longrightarrow [S_A]S'$
$\varepsilon : S, \mathbf{1} : S_A, \mathbf{11} : \mathbf{B}_2$	ba	$S' \xrightarrow{b} B_2$
$\varepsilon : S, \mathbf{1} : S_A, \mathbf{11} : \mathbf{ret}$	a	$B_2 \xrightarrow{b} \mathit{ret}$
$\varepsilon : S, \mathbf{1} : \mathbf{A}_2$	a	$[S_A]\mathit{ret} \longrightarrow A_2$
$\varepsilon : S, \mathbf{1} : \mathbf{ret}$	ε	$A_2 \xrightarrow{a} \mathit{ret}$

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