

## Appendix A: Theorems and Lemmas

This appendix collects the theorems and lemmas needed for the proof of several theorems which have been established in the previous chapter. Each lemma will be denoted by **A.i-j**, where **i** represents the chapter's number and **j** the order of classification in the considered chapter. The references cited in these appendices are given the bibliography section of chapter 1.

**Theorem** (*Kall's theorem, 1966*). For the linear equation

(K1)

$$Ax = b \quad (A \in R^{m \times n}, b \in R^m, n \geq m + 1)$$

where the matrix  $A$  has the first  $m$  independent columns, written  $A_1, \dots, A_m$ , to have a nonnegative solution  $x \in R^n$  for all  $b \in R^m$ , it is necessary and sufficient that there exist

(K2)

$$\mu_j \geq 0, \lambda_j < 0$$

such that

(K3)

$$\sum_{j=m+1}^n \mu_j A_j = \sum_{i=1}^m \lambda_i A_i$$

where  $A_j$  is the  $j$ -th column of the matrix  $A$ .

**Remark 5** In fact, the matrix  $A$  must have more than  $m$  columns, because it is impossible that some  $b = b_0$  and also  $-b_0$  (such situation is possible) be represented as a nonnegative linear combination the same  $m$  independent columns. Hence,  $n \geq m + 1$ .

*Proof.*

a) *Necessity.*

The vectors  $A_1, \dots, A_m$  are independent, then there exist a numbers  $\beta_i$  ( $i = 1, \dots, m$ ) such that

(K4)

$$b = \sum_{i=1}^m \beta_i A_i$$

Then, for any  $x \in R^n$  ( $x_i \geq 0$ ) satisfying (K1) we can write:

$$Ax = \sum_{j=1}^n x_j A_j = \sum_{i=1}^m \beta_i A_i$$

or

$$\sum_{i=1}^m (\beta_i - x_i) A_i = \sum_{j=m+1}^n x_j A_j$$

It is clear that if we want to prove this statement for any  $b \in R^m$  there exist such  $b$  that for the given matrix  $A$  the numbers  $\beta_j$  will be nonpositive and hence we can identify  $\mu_j$  in (K3) with the coefficients  $(\beta_i - x_i)$  of the left side of the last inequality and  $\lambda_j$  in (K3) with the coefficients in the right side, i.e.,

$$\begin{aligned}\mu_j &= \beta_i - x_i \\ \lambda_j &= x_j\end{aligned}$$

So, the necessity is proved.

2) *Sufficiency.*

Taking into account the presentation (K4) and the linear independence of the vectors  $A_1, \dots, A_m$  we can conclude that for any fixed  $b$  the corresponding values  $\beta_j$  are unique. If all of them are nonnegative then the equation (K1) has the solution

$$x_j = \begin{cases} \beta_j & \text{for } j = 1, \dots, m \\ 0 & \text{for } j = m+1, \dots, n \end{cases}$$

Let us now suggest that one at least of the  $\beta_j$  is negative. Notice that the largest of the ratios  $\beta_j/\lambda_j$  ( $j \leq m$ ) is positive, if at least one of the  $\beta_j$  founded above is negative. Let us define  $\gamma_0$  as follows

$$\gamma_0 := \max_j |\beta_j| / |\lambda_j|$$

If relation (K3) is true then the following relation

$$\sum_{j=m+1}^n \gamma_0 \mu_j A_j = \sum_{i=1}^m \gamma_0 \lambda_i A_i$$

is also true, and hence, taking into account the representation (K4) we derive:

$$\begin{aligned}\sum_{i=1}^m (\gamma_0 \lambda_i - \beta_i + \beta_i) A_i &= \sum_{i=1}^m (\gamma_0 \lambda_i - \beta_i) A_i + b = \\ &= \sum_{j=m+1}^n \gamma_0 \mu_j A_j\end{aligned}$$

or

$$\begin{aligned}b &= \sum_{i=1}^m (\gamma_0 |\lambda_i| + \beta_i) A_i + \sum_{j=m+1}^n \gamma_0 \mu_j A_j = \\ &= \sum_{i=1}^m |\lambda_i| \left( \gamma_0 + \frac{\beta_i}{|\lambda_i|} \right) A_i + \sum_{j=m+1}^n \gamma_0 \mu_j A_j\end{aligned}$$

Taking into account that

$$\gamma_j := \gamma_0 + \frac{\beta_j}{|\lambda_j|} \geq 0$$

Finally, we can write

$$\begin{aligned} b &= \sum_{i=1}^m |\lambda_j| \gamma_j A_j + \sum_{j=m+1}^n \gamma_0 \mu_j A_j = \\ &= \sum_{j=1}^n x_j A_j \end{aligned}$$

with

$$x_j = \begin{cases} |\lambda_j| \gamma_j & \text{for } j = 1, \dots, m \\ \gamma_0 \mu_j & \text{for } j = m + 1, \dots, n \end{cases} \geq 0$$

Theorem is proved. ■

**Lemma A.3-1.** Let  $\{\mathcal{F}_n\}$  be a sequence of  $\sigma$ -algebras and  $\eta_n, \theta_n, \lambda_n,$  and  $\nu_n$  are  $\mathcal{F}_n$ -measurable nonnegative random variables such that

1.  $\mathbf{E}(\eta_n) < \infty$
2.  $\sum_{n=1}^{\infty} \mathbf{E}(\theta_n) < \infty$
3.  $\sum_{n=1}^{\infty} \lambda_n \stackrel{a.s.}{=} \infty, \quad \sum_{n=1}^{\infty} \nu_n \stackrel{a.s.}{<} \infty$
4.  $\mathbf{E}(\eta_{n+1}/\mathcal{F}_n) \stackrel{a.s.}{\leq} (1 - \lambda_{n+1} + \nu_{n+1})\eta_n + \theta_n$

Then,

$$\lim_{n \rightarrow \infty} \eta_n \stackrel{a.s.}{=} 0$$

*Proof.*

In view of the assumptions of the previous theorem and Robbins-Siegmund theorem (Robbins and Siegmund, 1971), it follows that

$$\eta_n \stackrel{a.s.}{\rightarrow} \eta^* \quad n \rightarrow \infty$$

and

$$\sum_{n=1}^{\infty} \lambda_{n+1} \eta_n \stackrel{a.s.}{<} \infty$$

As

$$\sum_{n=1}^{\infty} \lambda_n \stackrel{a.s.}{=} \infty$$

Then, a subsequence  $\eta_{n_k}$  which tends to zero with probability 1 exists.

Hence  $\eta^* \stackrel{a.s.}{=} 0$ . ■

**Lemma A.3-2.** Let  $\{u_n\}$  be a sequence of nonnegative random variables  $u_n$  measurable with respect to the  $\sigma$ -algebra  $\mathcal{F}_n$ , for all  $n = 1, 2, \dots$ . If

1.  $\mathbf{E}(u_n/\mathcal{F}_n) \forall n = 1, 2, \dots$  exists
2. the following inequality holds

$$\mathbf{E}(u_{n+1}/\mathcal{F}_n) \leq u_n(1 - \alpha_n) + \beta_n$$

where  $\{\alpha_n\}$  and  $\{\beta_n\}$  are sequences of non random variables such that

$$\alpha_n \in (0, 1], \quad \beta_n \geq 0$$

$$\sum_{n=1}^{\infty} \alpha_n = \infty, \quad \sum_{n=1}^{\infty} \beta_n \nu_n < \infty$$

for some nonnegative sequence  $\{\nu_n\}$  ( $\nu_n > 0$ ,  $n = 1, 2, \dots$ )

3. the limit

$$\lim_{n \rightarrow \infty} \frac{\nu_{n+1} - \nu_n}{\alpha_n \nu_n} := \mu < 1$$

exists,

then,

$$u_n = o_{\omega}\left(\frac{1}{\nu_n}\right) \stackrel{a.s.}{\rightarrow} 0$$

with probability 1 when  $\nu_n \rightarrow \infty$ .

*Proof.*

Let  $\tilde{u}_n$  be the sequence defined as

$$\tilde{u}_n := u_n \nu_n$$

Then, using assumption (2), we obtain

$$\begin{aligned} \mathbf{E}(\tilde{u}_{n+1}/\mathcal{F}_n) &\stackrel{a.s.}{\leq} \tilde{u}_n(1 - \alpha_n)\left(\frac{\nu_{n+1}}{\nu_n}\right) + \nu_{n+1}\beta_n = \\ &= \tilde{u}_n(1 - \alpha_n)\left(\frac{\nu_{n+1} - \nu_n}{\nu_n} - 1\right) + \nu_{n+1}\beta_n \end{aligned}$$

Taking into account assumption (3), we derive

$$\mathbf{E}(\tilde{u}_{n+1}/\mathcal{F}_n) \stackrel{a.s.}{\leq} \tilde{u}_n [1 - \alpha_n(1 - \mu + o(1))] + \nu_{n+1}\beta_n$$

From this inequality and Robbins-Siegmund theorem (Robbins and Siegmund, 1971), we obtain

$$\tilde{u}_n \stackrel{a.s.}{\rightarrow} 0$$

which is equivalent to

$$u_n = o_\omega\left(\frac{1}{\nu_n}\right) \stackrel{a.s.}{\rightarrow} 0$$

Lemma is proved. ■

**Lemma A.3-3** (see ref. 31 of chapter 2). *For the sequence  $\{\gamma_n\}$  where*

$$\gamma_n = \frac{\gamma}{n+a},$$

*the following inequalities are fulfilled*

a) *for  $\gamma \in (0, 1)$  and  $a > \gamma$ , then*

$$\left(\frac{1+a}{n+a-\gamma+1}\right)^\gamma \geq \prod_{k=1}^n (1-\gamma_k) \geq \left(\frac{a-\gamma}{n+a}\right)^\gamma$$

b) *for  $\gamma = 1$  and  $a > 0$ , then*

$$\prod_{k=1}^n (1-\gamma_k) = \frac{a}{n+a}$$

*Proof.*

The proof of assertion a) is evident. Using the convexity property of the function  $x \ln x$ , it follows that

$$(x + \Delta x) \ln(x + \Delta x) - x \ln x \geq \Delta x(1 + x \ln x)$$

Taking into account this inequality, we obtain

$$\begin{aligned} \left(\frac{1+a}{n+a-\gamma+1}\right)^\gamma &= \exp \left\{ \int_1^{n+1} \ln \left(1 - \frac{\gamma}{n+a}\right) dx \right\} \geq \\ &\geq \prod_{k=1}^n (1-\gamma(k)) = \exp \left\{ \sum_{k=1}^n \ln \left(1 - \frac{\gamma}{k+a}\right) dx \right\} \geq \end{aligned}$$

$$\geq \exp \left\{ \int_0^{n+1} \ln \left( 1 - \frac{\gamma}{x+a} \right) dx \right\} = \left( \frac{a-\gamma}{n+a} \right)^\gamma$$

Lemma is proved. ■

**Lemma A.4-1.** Under assumptions (H1) and (H2)

1) the random variables  $\Phi^j(\omega)$  ( $j = 0, \dots, m$ ) are the partial limits of the sequences  $\{\Phi_n^j\}$  ( $j = 0, \dots, m$ ) for almost all  $\omega \in \Omega$  if and only if they can be written in the following form

$$\Phi^0(\omega) = \sum_{i=1}^N v_i^0 p(i) := V_0(p)$$

$$\Phi^j(\omega) = \sum_{i=1}^N v_i^j p(i) := V_j(p), \quad (j = 1, \dots, m)$$

where the random vector  $p = p(\omega) \in S^N$  (defined by equation (4.11)) is a limit point of the vector sequence  $f_n = (f_n(1), \dots, f_n(N))^T$  defined by (equation (4.13)).

2) for almost all  $\omega \in \Omega$

$$\Phi^j(\omega) \in \left[ \min_i v_i^j, \max_i v_i^j \right] \quad (j = 0, \dots, m)$$

*Proof.*

Let us rewrite  $\Phi_n^j$  (equation (4.1)) in the following form

$$\Phi_n^j = \sum_{i=1}^N f_n(i) \bar{\zeta}_n^j(u_n, \omega)$$

where

$$\bar{\zeta}_n^j(u_n, \omega) = \begin{cases} \frac{\sum_{t=1}^n \chi(u_t = u(i)) \zeta_n^j(u(i), \omega)}{\sum_{t=1}^n \chi(u_t = u(i))} & , \sum_{t=1}^n \chi(u_t = u(i)) > 0 \\ 0 & , \sum_{t=1}^n \chi(u_t = u(i)) = 0 \end{cases}$$

are the current average loss functions for  $u_t = u(i)$  ( $i = 1, \dots, N$ ). According to lemma A.12 (Najim and Poznyak, 1994) (see also Ash, 1972), for almost all

$$\omega \in \mathcal{B}_i := \left\{ \omega \mid \sum_{t=1}^n \chi(u_t = u(i)) = \infty \right\}$$

we have

$$\lim_{n \rightarrow \infty} \bar{\zeta}_n^j(u_n, \omega) = v^j$$

For almost all  $\omega \notin \mathcal{B}_i$ , we have:

$$\lim_n \left| \bar{\zeta}_n^j(u_n, \omega) \right| < \infty$$

and

$$\lim_{n \rightarrow \infty} f_n(i) = 0$$

The vector  $f_n$  also belongs to the simplex  $S^N$ . It follows that any partial limit  $\Phi^j(\omega)$  of a sequence  $\{\Phi_n^j\}$  can be expressed in the following form:

$$\Phi^j(\omega) = \sum_{i=1}^N v_i^j p(i) := V_j(p), \quad (j = 0, \dots, m)$$

where  $p$  is a partial limit of the sequence  $\{f_n\}$  and consequently,

$$\Phi^j(\omega) \in \left[ \min_i v_i^j, \max_i v_i^j \right] \quad (j = 0, \dots, m)$$

Lemma is proved. ■

**Lemma A.4-2.** *Let us assume that*

1. *the control strategy  $\{u_n\}$  is stationary, i.e.,*

$$\mathbf{P} \{ \omega : u_n = u(i) | \mathcal{F}_{n-1} \} \stackrel{a.s.}{=} p(i)$$

2. *the random variables  $\zeta_n^j(u(i), \omega)$  ( $j = 0, \dots, m; i = 1, \dots, N$ ) have stationary conditional mathematical expectation and uniformly bounded conditional second moment, i.e.,*

$$\mathbf{E} \{ \zeta_n^j(u(i), \omega) | u_n = u(i) \wedge \mathcal{F}_{n-1} \} \stackrel{a.s.}{=} v_i^j$$

$$\sup_n \mathbf{E} \left\{ \left( \zeta_n^j(u(i), \omega) \right)^2 | u_n = u(i) \wedge \mathcal{F}_{n-1} \right\} \stackrel{a.s.}{<} \infty$$

- 3.

$$\sum_{t=1}^{\infty} \chi(u_t = u(i)) \stackrel{a.s.}{\rightarrow} \infty$$

Then,

$$s_n^{ij} := \frac{\sum_{t=1}^n \zeta_t^j(u(i), \omega) \chi(u_t = u(i))}{\sum_{t=1}^n \chi(u_t = u(i))} - v_i^j \stackrel{a.s.}{\rightarrow} 0$$

*Proof.*

From the recurrent form of  $s_n^{ij}$

$$s_n^{ij} = s_{n-1}^{ij} \left( 1 - \frac{\chi(u_n = u(i))}{\sum_{t=1}^n \chi(u_t = u(i))} \right) + \frac{\chi(u_n = u(i))}{\sum_{t=1}^n \chi(u_t = u(i))} \left( \zeta_n^j(u(i), \omega) - v_i^j \right)$$

we derive

$$\begin{aligned} & \mathbf{E} \left\{ (s_n^{ij})^2 \mid u_n = u(i) \wedge \mathcal{F}_{n-1} \right\} \stackrel{a.s.}{\leq} (s_{n-1}^{ij})^2 \times \\ & \times \left( 1 - \frac{2\chi(u_n = u(i)) + o_\omega(1)}{\sum_{t=1}^n \chi(u_t = u(i))} \right) + \frac{\chi(u_n = u(i))}{\left[ \sum_{t=1}^n \chi(u_t = u(i)) \right]^2} \times \\ & \times \mathbf{E} \left\{ \left( \zeta_n^j(u(i), \omega) \chi(u_n = u(i)) - v_i^j \right)^2 \mid u_n = u(i) \wedge \mathcal{F}_{n-1} \right\} \leq \\ & \leq (s_{n-1}^{ij})^2 \left( 1 - \frac{\chi(u_n = u(i)) (2 + o_\omega(1))}{\sum_{t=1}^n \chi(u_t = u(i))} \right) + \\ & + \frac{\chi(u_n = u(i))}{\left[ \sum_{t=1}^n \chi(u_t = u(i)) \right]^2} \text{Const}(\omega) \end{aligned}$$

where  $o_\omega(1)$  is a random sequence tending to zero with probability one, and  $\text{Const}(\omega)$  is an almost surely bounded and positive random variable .

Observe that

$$\sum_{n=n_0}^{\infty} \frac{\chi(u_n = u(i)) (2 + o_\omega(1))}{\sum_{t=1}^n \chi(u_t = u(i))} \stackrel{a.s.}{=} \infty$$

In view of Robbins-Siegmund theorem (Robbins and Siegmund, 1971) (or Lemma A.9 in Najim and Poznyak, 1994), the previous inequality leads to the desired result. Lemma is proved. ■

The lemma used in chapter 5 is stated and proved in the following.



**Lemma A.5-1** (*the matrix version of the Abel's identity*).

$$\sum_{t=n_0}^n A_t B_t = A_n \sum_{t=n_0}^n B_t - \sum_{t=n_0}^n [A_t - A_{t-1}] \sum_{s=n_0}^{t-1} B_s$$

$$A_t \in R^{m \times k}, \quad B_t \in R^{k \times l}$$

*Proof.*

For  $n = n_0$  we obtain:

$$A_{n_0} B_{n_0} = A_{n_0} B_{n_0} - [A_{n_0} - A_{n_0-1}] \sum_{s=n_0}^{n_0-1} B_s = A_{n_0} B_{n_0}$$

The sum  $\sum_{s=n_0}^{n_0-1} B_s$  in the previous equality is zero by virtue of the fact that the upper limit of this sum is less than the lower limit.

We use induction. We note that the identity (Abel's identity) is true for  $n_0$ . We assume that it is true for  $n$  and prove that it is true for  $n + 1$ :

$$\begin{aligned} \sum_{t=n_0}^{n+1} A_t B_t &= \sum_{t=n_0}^n A_t B_t + A_{n+1} B_{n+1} = \\ &= A_n \sum_{t=n_0}^n B_t - \sum_{t=n_0}^n [A_t - A_{t-1}] \sum_{s=n_0}^{t-1} B_s + A_{n+1} B_{n+1} = \\ &= \left( A_{n+1} \sum_{t=n_0}^n B_t + A_{n+1} B_{n+1} \right) - \\ &- \left( (A_{n+1} - A_n) \sum_{t=n_0}^n B_t + \sum_{t=n_0}^n [A_t - A_{t-1}] \sum_{s=n_0}^{t-1} B_s \right) = \\ &= A_{n+1} \sum_{t=n_0}^{n+1} B_t - \sum_{t=n_0}^{n+1} [A_t - A_{t-1}] \sum_{s=n_0}^{t-1} B_s \end{aligned}$$

The identity (Abel's identity) is proved. ■

## Appendix B: Stochastic Processes

In this appendix we shall review the important definitions and some properties concerning stochastic processes.

A stochastic process,  $\{x_n, n \in N\}$  is a collection (family) of random variables indexed by a real parameter  $n$  and defined on a probability space  $(\Omega, \mathcal{F}, \mathbf{P})$  where  $\Omega$  is the space of elementary events  $\omega$ ,  $\mathcal{F}$  the basic  $\sigma$ -algebra and  $\mathbf{P}$  the probability measure. A  $\sigma$ -algebra  $\mathcal{F}$  is a set of subsets of  $\Omega$  (collection of subsets).  $\mathcal{F}(x_n)$  denotes the  $\sigma$ -algebra generated by the set of random variables  $x_n$ . The  $\sigma$ -algebra represents the knowledge about the process at time  $n$ . A family  $\mathcal{F} = \{\mathcal{F}_n, n \geq 0\}$  of  $\sigma$ -algebras satisfy the standard conditions  $\mathcal{F}_s \leq \mathcal{F}_n \leq \mathcal{F}$  for  $s \leq n$ ,  $\mathcal{F}_0$  is suggested by sets of measure zero of  $\mathcal{F}$ , and  $\mathcal{F}_n = \bigcap_{s \geq n} \mathcal{F}_s$ .

Let  $\{x_n\}$  be a sequence of random variables with distribution function  $\{F_n\}$  we say that:

**Definition 7**  $\{x_n\}$  converges in distribution (law) to a random variable with distribution function  $F$  if the sequence  $\{F_n\}$  converges to  $F$ .

*This is written*

$$x_n \xrightarrow{\text{law}} x$$

**Definition 8**  $\{x_n\}$  converges in probability to a random variable  $x$  if given  $\varepsilon, \delta > 0$ , then there exists  $n_0(\varepsilon, \delta)$  such that  $\forall n > n_0$   $P(|x_n - x| > \varepsilon) < \delta$

*This is written*

$$x_n \xrightarrow{\text{prob}} x$$

**Definition 9**  $\{x_n\}$  converges almost surely (with probability 1) to a random variable  $x$  if given  $\varepsilon, \delta > 0$ , then there exists  $n_0(\varepsilon, \delta)$  such that  $\forall n > n_0$ .  $P(|x_n - x| < \varepsilon \forall n > n_0) > 1 - \delta$

*This is written*

$$x_n \xrightarrow{\text{a.s.}} x$$

**Definition 10**  $\{x_n\}$  converges in quadratic mean to a random variable  $x$  if

$$\lim_{n \rightarrow \infty} \mathbf{E} [(x_n - x)^T (x_n - x)] = 0$$

This is written

$$x_n \xrightarrow{q.m.} x$$

The relationships between these convergence concepts are summarized in the following

1. convergence in probability implies convergence in law.
  2. convergence in quadratic mean implies convergence in probability.
  3. convergence almost surely implies convergence in probability.
- In general, the converse of these statements is false.

Stochastic processes as martingales have extensive applications in stochastic problems. They arise naturally whenever one needs to consider mathematical expectations with respect to increasing information patterns. They will be used to state several theoretical results concerning the convergence and the convergence rate of learning systems.

**Definition 11** A sequence of random variables  $\{x_n\}$  is said to be adapted to a the sequence of increasing  $\sigma$ -algebras  $\{\mathcal{F}_n\}$  if  $x_n$  is  $\mathcal{F}_n$  measurable for every  $n$ .

**Definition 12** A stochastic process  $\{x_n\}$  is a martingale if

$$E \{ |x_n| \} \stackrel{a.s.}{<} \infty$$

and

$$E \{ x_{n+1} / \mathcal{F}_n \} \stackrel{a.s.}{=} x_n$$

**Definition 13** A stochastic process  $\{x_n\}$  is a supermartingale if

$$E \{ x_{n+1} / \mathcal{F}_n \} \stackrel{a.s.}{\leq} x_n$$

**Definition 14** A stochastic process  $\{x_n\}$  is a submartingale if

$$E \{ x_{n+1} / \mathcal{F}_n \} \stackrel{a.s.}{\geq} x_n$$

The following theorems are useful for convergence analysis.

**Theorem (Doob, 1953).** Let  $\{x_n, \mathcal{F}_n\}$  be a nonnegative  $\left(x_n \stackrel{a.s.}{\geq} 0\right)$  supermartingale such that

$$\sup_n E\{x_n\} < \infty.$$

Then there exists a random variable  $x$  (defined on the same probability space) such that

$$E\{x\} < \infty, \quad x_n \xrightarrow{n \rightarrow \infty} x \text{ (a.s.)}.$$

**Theorem (Robbins and Siegmund, 1971).** Let  $\{\mathcal{F}_n\}$  be a sequence of  $\sigma$ -algebras and  $x_n, \alpha_n, \beta_n$  and  $\xi_n$  are  $\mathcal{F}_n$ -measurable nonnegative random variables such that for all  $n = 1, 2, \dots$  there exists  $E\{x_{n+1}/\mathcal{F}_n\}$  and the following inequality is verified

$$E\{x_{n+1}/\mathcal{F}_n\} \leq x_n(1 + \alpha_n) + \beta_n - \xi_n$$

with probability one.

Then, for all  $\omega \in \Omega_0$  where

$$\Omega_0 := \left\{ \omega \in \Omega \mid \sum_{n=1}^{\infty} \alpha_n < \infty, \sum_{n=1}^{\infty} \beta_n < \infty \right\}$$

the limit

$$\lim_{n \rightarrow \infty} x_n = x^*(\omega)$$

exists, and the sum

$$\sum_{n=1}^{\infty} \xi_n < \infty$$

converges.

Since the literature on stochastic processes is extensive we refer the reader to the books written respectively by Doob (1953) and Neveu (1975).

# Index

## A

Abel's identity, 172, 199  
Accuracy, 23, 43, 46, 85, 93  
Adaptive, 27, 29, 31  
Algebra, 30, 48, 167

## B

Binary, 36, 120  
Borel-Cantelli, 71, 81, 87, 174  
Bush-Mosteller, 33, 51, 75, 95, 108,  
121, 139, 167, 176, 186

## C

Caratheodory theorem, 14, 16  
Cauchy distribution, 162  
Cauchy-Bounyakovskii, 54, 60, 65  
Chance constraint, 7  
Chance constraints, 110  
Changing number of actions, 91,  
94  
Constraints, 4, 108, 132  
Continuous, 32, 93, 166  
Convergence, 29, 57, 62, 68, 79,  
90, 145, 183  
Convergence rate, 123, 129, 146  
Convexity, 44, 108  
Correction factor, 30, 46, 63, 68,  
76, 89, 167, 176, 179  
Cost function, 108

## E

Euclidean, 111  
Environment, 3, 28, 30, 47, 74,  
164, 167  
Expectation, 6, 30, 109, 126, 128,  
144, 165, 167, 171  
Expediency, 28, 165

## G

Gaussian, 162–163  
Gradient, 4, 33, 107, 113

## H

Hessian, 134  
Hierarchical, 28, 34–35, 165

## I

Inaction, 27

## J

Jensen's inequality, 73

## K

Kall's theorem, 17, 191  
Kiefer-Wolfowitz, 33

## L

Lagrange, 66, 88, 108, 112–114,  
116, 121, 127, 138, 152,  
183  
Law of large numbers, 50, 73, 110  
Learning automata, 3, 27, 32, 43,  
118, 165  
Lipschitzian, 20, 44, 108, 116, 138  
Loss function, 30, 47, 74, 76, 99,  
110, 167, 170, 173, 177,  
179, 182  
Lyapunov, 109  
Lyapunov function, 29, 50, 52, 58,  
61, 63–64, 81, 180, 183

## M

Markovian, 165, 168  
Martingale, 29, 112  
Matrix inversion lemma, 134  
Minmax problem, 112  
Multi-teacher, 24, 28, 31, 119, 139,  
164–165  
Multimodal, 43–44, 94, 173

## N

Najim, 28, 91, 173

Nonstationary, 28, 31, 50, 161–162, 164–165, 167, 182, 185, 187

Normalization, 35, 69, 79, 91, 109, 121, 165, 173, 178, 181

## O

Objective function, 4

Observation, 6, 44, 70, 162

## P

Penalty, 28, 31, 33, 108, 164–165

Penalty function, 108, 132, 153

Poznyak, 28, 91, 173

Probability, 3, 30, 33, 50, 74, 145, 165, 176

Probability measure, 9, 30, 35, 46, 120

Programming problem, 3–4, 4, 10, 48, 132, 135

Projection, 36–37, 47, 136, 142

## Q

Quantification, 44

## R

Reinforcement scheme, 29–30, 52, 58, 64, 120, 167, 183, 186, 176

Reward, 27, 33, 164

Robbins-Siegmund, 56, 72, 84, 128, 144, 175, 185

## S

S-model environment, 29, 31, 91, 120, 166, 97

Saddle-point, 112, 114, 116, 108, 124

Shapiro-Narendra, 33, 57, 75, 80, 95, 167, 179, 186

Simplex, 36, 38, 47, 49, 108, 111

Slack variables, 132

Slater' condition, 10

Slater's condition, 5, 133, 136

Stationary, 28, 31, 47, 63, 68, 112, 161, 168, 177, 179

Stochastic, 3, 6, 9, 108, 164

Stochastic approximation, 8, 43, 108

## T

Taylor series, 61

Toeplitz, 178, 181, 185

## V

Varshavskii-Vorontsova, 33, 63, 75, 85, 95, 167, 182, 186

# Lecture Notes in Control and Information Sciences

---

Edited by M. Thoma

## 1993–1996 Published Titles:

- Vol. 186:** Sreenath, N.  
Systems Representation of Global Climate Change Models. Foundation for a Systems Science Approach.  
288 pp. 1993 [3-540-19824-5]
- Vol. 187:** Morecki, A.; Bianchi, G.; Jaworeck, K. (Eds)  
RoManSy 9: Proceedings of the Ninth CISM-IFTOMM Symposium on Theory and Practice of Robots and Manipulators.  
476 pp. 1993 [3-540-19834-2]
- Vol. 188:** Naidu, D. Subbaram  
Aeroassisted Orbital Transfer: Guidance and Control Strategies  
192 pp. 1993 [3-540-19819-9]
- Vol. 189:** Ilchmann, A.  
Non-Identifier-Based High-Gain Adaptive Control  
220 pp. 1993 [3-540-19845-8]
- Vol. 190:** Chatila, R.; Hirlinger, G. (Eds)  
Experimental Robotics II: The 2nd International Symposium, Toulouse, France, June 25-27 1991  
580 pp. 1993 [3-540-19851-2]
- Vol. 191:** Blondel, V.  
Simultaneous Stabilization of Linear Systems  
212 pp. 1993 [3-540-19862-8]
- Vol. 192:** Smith, R.S.; Dahleh, M. (Eds)  
The Modeling of Uncertainty in Control Systems  
412 pp. 1993 [3-540-19870-9]
- Vol. 193:** Zinober, A.S.I. (Ed.)  
Variable Structure and Lyapunov Control  
428 pp. 1993 [3-540-19869-5]
- Vol. 194:** Cao, Xi-Ren  
Realization Probabilities: The Dynamics of Queuing Systems  
336 pp. 1993 [3-540-19872-5]
- Vol. 195:** Liu, D.; Michel, A.N.  
Dynamical Systems with Saturation Nonlinearities: Analysis and Design  
212 pp. 1994 [3-540-19888-1]
- Vol. 196:** Battilotti, S.  
Noninteracting Control with Stability for Nonlinear Systems  
196 pp. 1994 [3-540-19891-1]
- Vol. 197:** Henry, J.; Yvon, J.P. (Eds)  
System Modelling and Optimization  
975 pp approx. 1994 [3-540-19893-8]
- Vol. 198:** Winter, H.; Nüßer, H.-G. (Eds)  
Advanced Technologies for Air Traffic Flow Management  
225 pp approx. 1994 [3-540-19895-4]
- Vol. 199:** Cohen, G.; Quadrat, J.-P. (Eds)  
11th International Conference on Analysis and Optimization of Systems – Discrete Event Systems: Sophia-Antipolis, June 15–16–17, 1994  
648 pp. 1994 [3-540-19896-2]
- Vol. 200:** Yoshikawa, T.; Miyazaki, F. (Eds)  
Experimental Robotics III: The 3rd International Symposium, Kyoto, Japan, October 28-30, 1993  
624 pp. 1994 [3-540-19905-5]
- Vol. 201:** Kogan, J.  
Robust Stability and Convexity  
192 pp. 1994 [3-540-19919-5]
- Vol. 202:** Francis, B.A.; Tannenbaum, A.R. (Eds)  
Feedback Control, Nonlinear Systems, and Complexity  
288 pp. 1995 [3-540-19943-8]
- Vol. 203:** Popkov, Y.S.  
Macrosystems Theory and its Applications: Equilibrium Models  
344 pp. 1995 [3-540-19955-1]

**Vol. 204:** Takahashi, S.; Takahara, Y.  
Logical Approach to Systems Theory  
192 pp. 1995 [3-540-19956-X]

**Vol. 205:** Kotta, U.  
Inversion Method in the Discrete-time  
Nonlinear Control Systems Synthesis  
Problems  
168 pp. 1995 [3-540-19966-7]

**Vol. 206:** Aganovic, Z.; Gajic, Z.  
Linear Optimal Control of Bilinear Systems  
with Applications to Singular Perturbations  
and Weak Coupling  
133 pp. 1995 [3-540-19976-4]

**Vol. 207:** Gabasov, R.; Kirillova, F.M.;  
Prischepova, S.V.  
Optimal Feedback Control  
224 pp. 1995 [3-540-19991-8]

**Vol. 208:** Khalil, H.K.; Chow, J.H.;  
Ioannou, P.A. (Eds)  
Proceedings of Workshop on Advances  
in Control and its Applications  
300 pp. 1995 [3-540-19993-4]

**Vol. 209:** Foias, C.; Özbay, H.;  
Tannenbaum, A.  
Robust Control of Infinite Dimensional  
Systems: Frequency Domain Methods  
230 pp. 1995 [3-540-19994-2]

**Vol. 210:** De Wilde, P.  
Neural Network Models: An Analysis  
164 pp. 1996 [3-540-19995-0]

**Vol. 211:** Gawronski, W.  
Balanced Control of Flexible Structures  
280 pp. 1996 [3-540-76017-2]

**Vol. 212:** Sanchez, A.  
Formal Specification and Synthesis of  
Procedural Controllers for Process Systems  
248 pp. 1996 [3-540-76021-0]

**Vol. 213:** Patra, A.; Rao, G.P.  
General Hybrid Orthogonal Functions and  
their Applications in Systems and Control  
144 pp. 1996 [3-540-76039-3]

**Vol. 214:** Yin, G.; Zhang, Q. (Eds)  
Recent Advances in Control and Optimization  
of Manufacturing Systems.  
240 pp. 1996 [3-540-76055-5]

**Vol. 215:** Bonivento, C.; Marro, G.;  
Zanasi, R. (Eds)  
Colloquium on Automatic Control  
240 pp. 1996 [3-540-76060-1]

**Vol. 216:** Kulhavý, R.  
Recursive Nonlinear Estimation: A Geometric  
Approach  
244 pp. 1996 [3-540-76063-6]

**Vol. 217:** Garofalo, F.; Glielmo, L. (Eds)  
Robust Control via Variable Structure and  
Lyapunov Techniques  
336 pp. 1996 [3-540-76067-9]

**Vol. 218:** van der Schaft, A.  
 $L_2$  Gain and Passivity Techniques in Nonlinear  
Control  
176 pp. 1996 [3-540-76074-1]

**Vol. 219:** Berger, M.-O.; Deriche, R.;  
Herlin, I.; Jaffré, J.; Morel, J.-M. (Eds)  
ICAOS '96: 12th International Conference on  
Analysis and Optimization of Systems -  
Images, Wavelets and PDEs:  
Paris, June 26-28 1996  
378 pp. 1996 [3-540-76076-8]

**Vol. 220:** Brogliato, B.  
Nonsmooth Impact Mechanics: Models,  
Dynamics and Control  
420 pp. 1996 [3-540-76079-2]

**Vol. 221:** Kelkar, A.; Joshi, S.  
Control of Nonlinear Multibody Flexible Space  
Structures  
160 pp. 1996 [3-540-76093-8]

**Vol. 222:** Morse, A.S.  
Control Using Logic-Based Switching  
288 pp. 1997 [3-540-76097-0]

**Vol. 223:** Khatib, O.; Salisbury, J.K.  
Experimental Robotics IV: The 4th International  
Symposium, Stanford, California,  
June 30 - July 2, 1995  
596 pp. 1997 [3-540-76133-0]



**Vol. 224:** Magni, J.-F.; Bennani, S.;  
Terlouw, J. (Eds)  
Robust Flight Control: A Design Challenge  
664 pp. 1997 [3-540-76151-9]