

## REFERENCES

AHMED H.M. and MORF M.

- 1982 VLSI array architectures for matrix factorization, in Outils et modeles mathematiques pour l'automatique, l'analyse de systemes et le traitement du signal, Ed.CNRS, Paris, vol.2, pp. 691-704.

BARRET J.F.

- 1963 The use of functionals in the analysis of nonlinear physical systems, *J.Electr.Contr.*, vol.15, pp.567-615.

BOSE A.G.

- 1958 A theory of nonlinear systems, Techn.Rept., MIT.

CAMERON R.H. and MARTIN W.T

- 1947 The orthogonal development of nonlinear functionals in series of Fourier-Hermite functionals, *Ann.Math.*, vol.48, pp. 385-392.

DELSARTE P., GENIN Y. and KAMP Y.

- 1979 a Schur parametrization of positive definite block-Toeplitz matrices, *SIAM J.Appl.Math.*, vol.36, pp.33-46.
- 1979 b The Nevanlinna-Pick problem for matrix-valued functions, *SIAM J.Appl.Math.*, vol.36, pp.47-61.
- 1983 Generalized Schur positivity test and Levinson recursion, *Proc.ECCTD'83*, Stuttgart.

DELOSME J.M. and MORF M.

- 1982 Fast algorithms for finite shift-rank processes : geometric approach, in Outils et modeles mathematiques pour l'automatique, l'analyse de systemes et le traitement du signal, Ed.CNRS, Paris, vol.2, pp.499-529.

DEPRETTERE E.

- 1981 Orthogonal filters, Ph.D. Thesis, Delft Univ. Techn.
- 1982 Mixed form time-variant lattice recursions, in Outils et modeles mathematiques pour l'automatique, l'analyse de systemes et le traitement du signal, Ed.CNRS, Paris, vol.2, pp.545-562.
- 1983 a Synthesis and fixed-point implementation of pipelined true orthogonal filters, *Proc.ICASSP'83*, Boston.
- 1983 b CORDIC-10: An expandable VLSI implementable orthogonal filter module, *Proc.EUSIPCO'83*, Erlangen.

DEPRETTERE E. and DEWILDE P.

- 1979 Generalized orthogonal filters for stochastic prediction and modeling, in Digital signal processing, Ed.V.Capellini, Acad. Press, N.Y.

DEPRETTERE E., DEWILDE P., and UDO R.

- 1984 Pipelined CORDIC architectures for fast VLSI filtering and array processing, Proc.ICASSP'84.

DEPRETTERE E. and JAINANDUNSING K.

- 1984 Design and VLSI implementation of a concurrent solver for N coupled systems of linear equations, Techn.Rept., Delft Univ. Techn.

DEPRETTERE E. and LIE S.C.

- 1980 Generalized Schur-Darlington algorithms for lattice-structured matrix inversion and stochastic modeling, Techn.Rept., Delft Univ. Techn.

DEWILDE P.

- 1982 Stochastic modeling with orthogonal filters, in Outils et modes mathematiques pour l'automatique, l'analyse de systemes et le traitement du signal, Ed.CNRS, Paris, vol.2, pp.331-398.
- 1983 Orthogonal filters: Pipelining and VLSI implementation, Proc. ECCTD'83, Stuttgart.
- 1984a Spectral approximation and estimation with scattering functions, in Mathematical Theory of Networks and Systems, Lecture Notes in Control and Information Sciences, vol.48, Ed.P.A.Fuhrmann, Springer-Verlag, pp.234-252.
- 1984b Orthogonal filters: A numerical approach to filtering theory, *ibid.*, pp.253-267.

DEWILDE P. and BULTHEEL A.

- 1979 Orthogonal functions related to the Nevanlinna-Pick problem, in Mathematical Theory of Networks and Systems, Ed.P.Dewilde, vol.3, Delft, pp.207-212.

DEWILDE P., DEPRETTERE E. and NOUTA R.

- 1984 Parallel and pipelined VLSI implementations of signal processing algorithms, in VLSI and signal processing, Ed.S.Y. Kung.

DEWILDE P. and DYM H.

- 1981a Schur recursions, error formulas and convergence of rational estimator for stationary stochastic processes, IEEE Trans. on IT-27, pp.446-461.

- 1981b Lossless chain scattering matrices and optimum linear prediction: The vector case, *Circuit Theory and Appl.*, vol.9, pp.135-175.
- 1984 Lossless inverse scattering with rational networks: Theory and applications, *IEEE Trans. on IT-30*.

DEWILDE P., VIEIRA A.C. and KAILATH T.

- 1978 On a generalized Szegő-Levinson realization algorithm for optimal linear predictors based on a network synthesis approach, *IEEE Trans. on CAS-25*, pp.663-675.

FRECHET M.

- 1910 Sur les fonctionelles continues, *Ann. de l'Ecole Norm. Sup. 3-me, Ser.V.27*.

ITO K.

- 1951 Multiple Wiener Integral, *J.Math.Soc., Japan*, vol.13, nr 1, pp.157-169.

KAILATH T.

- 1974 A view of three decades in linear filtering theory, *IEEE Trans. on IT-20*, pp.146-181.
- 1982 Time-variant and time-invariant lattice filters for nonstationary processes, in Outils et modeles mathematiques pour l'automatique, l'analyse de systemes et le traitement du signal, Ed.CNRS, Paris, vol.2, pp.417-464.

LEE D.T.L., MORF M. and FRIEDLANDER B.

- 1981 Recursive least-squares ladder-estimation algorithms, *IEEE Trans. on CAS-28*, pp.467-481.

LEV-ARI H.

- 1982 Parametrization and modeling of nonstationary processes, Ph.D.Thesis, Stanford Univ.
- 1983 Modular architectures for adaptive multichannel lattice algorithms, *Proc.ICASSP'83*.

LEV-ARI H. and KAILATH T.

- 1982 Lattice filter parametrization and modeling of nonstationary processes, *Techn.Rept.*, Stanford Univ.

LEVINSON N.

- 1947 The Wiener RMS error criterium in filter design and prediction, *J.Math.Phys.*, vol.25, pp.261-278.

MORF M., VIEIRA A.C., LEE D.T.L. and KAILATH T.

1978 Recursive multichannel maximum entropy spectral estimation, IEEE Trans. on GE-16, pp.85-94.

OGURA H.

1972 Orthogonal functionals for the Poisson process, IEEE Trans. on IT-18, pp.473-481.

PIEKARSKI M.S.

1971 Reciprocal Darlington section suitable for an integrated circuit, Electron.Lett., vol.7, pp.475-477.

1974 A minimal grounded cascade synthesis for integrated circuits, Proc.ECCTD'74, London.

PIEKARSKI M.S., SAEED K.

1980 A test for positive real function, Proc.ECCTD'80, Warsaw.

PIEKARSKI M.S. and URUSKI M.

1984 Interpolation with positive real matrices, Proc.ISYNT'84, Sarajevo.

PRABHAKARA RAO C.V.K. and HELMOND J.

1983 On the theory of AR spectral approximation for processes containing deterministic signals, Proc.ECCTD'83, Stuttgart.

SEGALL A. and KAILATH T.

1976 Orthogonal functionals of independent-increment processes, IEEE Trans. on IT-22, pp.287-298.

SCHETZEN M.

1980 Volterra-Wiener theories of nonlinear systems, Wiley, N.Y.

SCHUR J.

1917 Uber potenzreihen, die in innern des einheitskreises beschränkt sind, J.Reine Ang.Math., vol.147, pp.205-232.

STEINHAUS H. and KACZMARZ S.

1935 Theorie der orthogonalreihen, Warsaw.

TUSZYNSKI A.A.

1980 A CORDIC arithmetic processor chip, IEEE Trans. on C-29, pp.68-79.

VICTOR J. and KNIGHT B.

1979 Nonlinear analysis with arbitrary stimulus ensemble, Quart.Appl.Math., vol.XXXVII, pp.115-136.

VOLTERRA V.

1959 Theory of functionals and of integral and integro-differential equations, Dover Publ.

WIDYA I.

1982 Continuous-time stochastic modeling with lossless structures, Ph.D.Thesis, Delft Univ,Techn.

WIENER N.

1938 The homogeous chaos, Amer.J.Math., vol.60, pp.897-936.

1958 Nonlinear problems in random theory, MIT Press - Wiley N.Y.

WOLDER P.

1959 The CORDIC trigonometric computing technique, IRE Trans. on EC-8, pp.330-334.

YASUI S.

1979 Stochastic functional Fourier series, Volterra series and nonlinear system analysis, IEEE Trans. on AC-21, pp. 230-242.

ZARZYCKI J.

1983 Nonlinear Levinson prediction filter for higher-order random sequences, Proc.ECCTD'83, Stuttgart.

1984a Nonlinear prediction of higher-order random sequences, submitted for publication.

1984b Generalized ladder-filters for nonlinear prediction of higher-order random sequences, submitted for publication.

1984c Fast algorithms for the least-squares nonlinear prediction, submitted for publication.

1984d Adaptive properties of nonlinear ladder-filters, submitted for publication

1984e Nonlinear ladder-filters for the least-squares AR prediction of higher-order random sequences, Proc.ISCAS'84, Montreal.

1985a Nonlinear Levinson algorithm: A geometric approach, Proc.ECCTD'85, Prague.

1985b Orthogonal ladder-form representations of nonlinear prediction filters of the Volterra-Wiener class, in Mathematical Theory of Networks and Systems, to be published.

ZARZYCKI J. and DEWILDE P.

- 1983a        Nonlinear least-squares prediction of higher-order random sequences, submitted for publication.
- 1983b        The Levinson-type filters for fast nonlinear AR prediction, Techn.Rept., Wroclaw Univ.Techn.

APPENDIX 1

MULTI-INDEXED MATRICES AND GENERALIZED MATRIX THEORY

Let  $I$  denote a contiguous subset of integers, let  $\mathbb{R}$  be the set of real numbers. We define a  $m$ -indexed matrix  ${}^m A$  as a map

$${}^m A: {}^m I \rightarrow \mathbb{R} \tag{A.1}$$

where  ${}^m I = I \times \dots \times I$  ( $m$ -copies). According to (A.1), the index-set  ${}^m I$  can be called the domain of the  $m$ -indexed matrix  ${}^m A$ . This domain will be denoted as  $D^m A$ . Let us introduce the index-sets

$$L_n^{\circ} \triangleq (j)_o^n = \{0, 1, \dots, n\} \tag{A.2}$$

$${}^m L_n^{\circ} \triangleq L_n^{\circ} \times \dots \times L_n^{\circ} = \{(j_1, \dots, j_m) : j_k \in L_n^{\circ}, k=1, \dots, m\} \tag{A.3}$$

$m$

A  $m$ -indexed matrix  ${}^m \underline{A}_n$  will be called the  $n$ -th order matrix if

$$D^m \underline{A}_n = {}^m L_n^{\circ} \tag{A.4a}$$

This matrix can be equivalently expressed in terms of its  $m$ -indexed entries as follows

$${}^m \underline{A}_n = [ a_{j_1 \dots j_m} ]_{(j_1, \dots, j_m) \in {}^m L_n^{\circ}} \tag{A.4b}$$

We will consider here some properties of multi-indexed matrices, and introduce operations on those matrices. We will usually drop, for simplicity, the order and domain of the matrices, assuming that all matrices are of the type (A.4), unless otherwise stated.

Symmetric matrix

A  $m$ -indexed matrix will be called symmetric if for any permutation  $\pi_1, \dots, \pi_m$  of integers  $1, \dots, m$  we shall have

$$a_{j_{\pi_1} \dots j_{\pi_m}} = a_{j_1 \dots j_m} \quad (\text{A.5a})$$

Consequently, it is sufficient to consider  $\binom{m+n}{m}$  'different' entries of the symmetric matrix instead of  $n^m$  entries of non-symmetric matrix. Now let  $\gamma_{j_1 \dots j_m}$  denote the number of equal elements of the symmetric matrix, corresponding to the sequence  $(j_1, \dots, j_m)$ . We shall denote the 'symmetric part' of a  $m$ -indexed matrix  ${}^m A_n$  by  ${}^m A$ , where

$${}^m A_n = [ a_{j_1 \dots j_m} ] \quad (j_1, \dots, j_m) \in \text{sym}^m L_n^o \quad (\text{A.5b})$$

with  $\text{sym}^m L_n^o$  denoting the 'symmetric part' of the  $m$ -variate index-set, obtained according to lexicographic or anti-lexicographic ordering. The entries  $a_{j_1 \dots j_m}$  of  ${}^m A_n$  can then be expressed in terms of the entries  $\bar{a}_{j_1 \dots j_m}$  of the symmetric matrix  ${}^m \bar{A}_n$  as

$$a_{j_1 \dots j_m} = \gamma_{j_1 \dots j_m} \bar{a}_{j_1 \dots j_m} \quad (\text{A.5c})$$

Transpose matrix

Let  $\pi$  be a permutation of the index-set  $\{(j_1, \dots, j_m) \in {}^m L_n^o\}$ .  $\pi$  may be represented by a map

$$\left( \begin{array}{c} 1, 2, \dots, m \\ \pi_1, \pi_2, \dots, \pi_m \end{array} \right) \quad (\text{A.6a})$$



where  $(\pi_1, \pi_2, \dots, \pi_m)$  is a permutation of  $\{1, 2, \dots, m\}$ . Then, a  $m$ -indexed matrix  ${}^m A'_\pi$  will be called the transpose matrix due to the permutation  $\pi$  if

$$({}^m A'_\pi)_{j_1 \dots j_m} = ({}^m A)_\pi(j_1, \dots, j_m) \quad (\text{A.6b})$$

### Zero-matrix

A  $m$ -indexed matrix will be called a zero-matrix if for each sequence of indices  $(j_1, \dots, j_m) \in D^m A$  we have  $a_{j_1 \dots j_m} = 0$ . This matrix will be denoted by

$${}^m O_n = [0_{j_1 \dots j_m}]_{(j_1, \dots, j_m) \in D^m O_n} \quad (\text{A.7})$$

where  $0_{j_1 \dots j_m}$  will be the zero-entry with 'coordinates'  $(j_1, \dots, j_m)$ .

### Unit-matrix

A  $2m$ -indexed matrix will be called the unit-matrix if for each  $(j_1, \dots, j_m)$  and  $(k_1, \dots, k_m) \in D^{2m} A_n$  we have

$$a_{j_1 \dots j_m k_1 \dots k_m} = \delta_{j_1 \dots j_m; k_1 \dots k_m} \quad (\text{A.8a})$$

where

$$\delta_{j_1 \dots j_m; k_1 \dots k_m} = \begin{cases} 1 & \text{if } j_1 = k_1, \dots, j_m = k_m \\ 0 & \text{otherwise} \end{cases} \quad (\text{A.8b})$$

This matrix will be denoted as

$${}^{2m}\mathbf{1}_n = [\delta_{j_1 \dots j_m; k_1 \dots k_m}] \quad (j_1, \dots, j_m, k_1, \dots, k_m) \in D^{2m}\mathbf{1}_n \quad (\text{A.8c})$$

### Block-matrices

A block-matrix whose block-entries are  $m$ -indexed,  $n$ -th order matrices

$$\{M\}A_n = [{}^m A_n]_{m=1, \dots, M} \quad (\text{A.9a})$$

will be called a  $M$ -block (row),  $m$ -indexed,  $n$ -th order matrix. Its block-row domain  $D^{\{M\}}A_n$  will be a vector of simple domains

$$D^{\{M\}}A_n = [D^m A_n]_{m=1, \dots, M} \quad (\text{A.9b})$$

Similarly, a block-matrix

$$\{M\}B_n = \text{col} [{}^m B_n]_{m=1, \dots, M} \quad (\text{A.10a})$$

will be called a  $M$ -block (column),  $m$ -indexed,  $n$ -th order matrix with the block-column domain

$$D^{\{M\}}B_n = \text{col} [D^m B_n]_{m=1, \dots, M} \quad (\text{A.10b})$$

Finally, a block-matrix

$$\{M \times M\}H_n = [{}^{m \oplus u} H_n]_{m, u=1, \dots, M} \quad (\text{A.11a})$$

whose block-entries are  $(m+u)$ -indexed matrices

$${}^{m \oplus u}H_n = [h_{j_1 \dots j_m k_1 \dots k_u}] \quad (j_1, \dots, j_m, k_1, \dots, k_u) \in D^{m \oplus u}H_n \quad (\text{A.11b})$$

will be called a  $(M \times M)$ -block (square),  $(m+u)$ -indexed,  $n$ -th order matrix. Its block-square domain  $D^{\{M \times M\}}H_n$  is given by

$$D^{\{M \times M\}}H_n = [D^{m \oplus u}H_n]_{m, u=1, \dots, M} \quad (\text{A.11c})$$

Let us observe that the matrix (A.11) can be described in a generalized 'block-column' form. To do that, let us suppose that  $D^{m \oplus u}H_n = D^m H_n \times D^u H_n$ , where  $(j_1, \dots, j_m) \in D^m H_n$  and  $(k_1, \dots, k_u) \in D^u H_n$ . Then we can write

$$\{M \times M\}H_n = [\{M\} \times u H_n]_{u=1, \dots, M} \quad (\text{A.12a})$$

where

$$\{M\} \times u H_n = \text{col} [{}^{m \oplus u}H_n]_{m=1, \dots, M} \quad (\text{A.12b})$$

or, equivalently,

$$\{M\} \times u H_n = [{}^{\{M\}}H_n; k_1 \dots k_u]_{(k_1, \dots, k_u) \in D^u H_n} \quad (\text{A.12c})$$

with

$${}^{\{M\}}H_n; k_1 \dots k_u = [h_{j_1 \dots j_m k_1 \dots k_u}]_{(j_1, \dots, j_m) \in D^m H_n} \quad (\text{A.12d})$$

### Equal matrices

Two  $m$ -indexed matrices

$${}^m A = [a_{j_1 \dots j_m}]_{(j_1, \dots, j_m) \in D^m A} ; \quad {}^m B = [b_{j_1 \dots j_m}]_{(j_1, \dots, j_m) \in D^m B} \quad (\text{A.13})$$

will be called equal matrices if  $D^m A = D^m B$ , and if for each sequence of indices  $(j_1, \dots, j_m) \in D^m A$

$$a_{j_1 \dots j_m} = b_{j_1 \dots j_m} \quad (\text{A.14})$$

### Sum of multi-indexed matrices

Given the matrices (A.13), we shall say that the  $m$ -indexed matrix

$${}^m G = [g_{j_1 \dots j_m}]_{(j_1, \dots, j_m) \in D^m G} \quad (\text{A.15a})$$

is the sum

$${}^m G = {}^m A + {}^m B \quad (\text{A.15b})$$

if  $D^m G = D^m A = D^m B$ , and if for each  $(j_1, \dots, j_m) \in D^m A$

$$g_{j_1 \dots j_m} \stackrel{\Delta}{=} a_{j_1 \dots j_m} + b_{j_1 \dots j_m} \quad (\text{A.15c})$$

### Sum of block, multi-indexed matrices

Given two  $M$ -block (row),  $m$ -indexed matrices

$$\{M\}_A = [{}^m A]_{m=1, \dots, M} \quad ; \quad \{M\}_B = [{}^m B]_{m=1, \dots, M} \quad (\text{A.16a})$$

we shall say that the  $M$ -block (row),  $m$ -indexed matrix

$$\{M\}_G = [{}^m G]_{m=1, \dots, M} \quad (\text{A.16b})$$

where  ${}^m G$  is given by (A.15a), is the sum

$$\{M\}_G = \{M\}_A + \{M\}_B \quad (\text{A.16d})$$

if for  $m=1,\dots,M$  we have  $D^m A = D^m B = D^m G$ , and if for each sequence of indices  $(j_1, \dots, j_m) \in D^m A$  the entries  $g_{j_1 \dots j_m}$  are expressed by (A.15c).

### Product of a scalar and a m-indexed matrix

Given a scalar  $c \in \mathbb{R}$  and a m-indexed matrix  ${}^m A$  (A.13), we shall say that the m-indexed matrix  ${}^m G$  (A.15a) is the product of the scalar and the m-indexed matrix

$${}^m G = c \cdot {}^m A \quad (\text{A.17a})$$

if for each  $(j_1, \dots, j_m) \in D^m G$  (where  $D^m G = D^m A$ ) we have

$$g_{j_1 \dots j_m} \stackrel{\Delta}{=} c \cdot a_{j_1 \dots j_m} \quad (\text{A.17b})$$

### Product of multi-indexed matrices

Let  ${}^m A$  be given by (A.13), and let  ${}^s B$  be given by (A.13) with  $m$  replaced by  $s$ , where  $m \leq s$ . Let  $\nu, \mu, \nu$  be some given integers, satisfying

$$\nu + \mu = m \quad ; \quad \mu + \nu = s \quad (\text{A.18a})$$

and moreover let  $r = (\nu + \nu)$ . Partitioning the  $m$  indices of the  ${}^m A$ , and the  $s$  indices of the  ${}^s B$  in accordance with (A.18a), and assu-

ming that  $D^m A = D^u A \times D^\mu A$  and  $D^s B = D^\mu B \times D^v B$ , we can write

$$m_A = [a_{k_1 \dots k_u j_1 \dots j_\mu}] \quad (k_1, \dots, k_u) \in D^u A ; (j_1, \dots, j_\mu) \in D^\mu A \quad (\text{A.18b})$$

$$s_B = [b_{j_1 \dots j_\mu i_1 \dots i_v}] \quad (j_1, \dots, j_\mu) \in D^\mu B ; (i_1, \dots, i_v) \in D^v B \quad (\text{A.18c})$$

We shall say that the  $r = (u + v)$ -indexed matrix

$$r_{(u+v)G} = [g_{k_1 \dots k_u i_1 \dots i_v}] \quad (k_1, \dots, k_u) \in D^u A ; (i_1, \dots, i_v) \in D^v B \quad (\text{A.18d})$$

whose domain is  $D^r G = D^u A \times D^v B$ , is the  $\mu$ -product of the matrices (A.18b,c)

$$r_G = m_A \cdot s_B = {}^{u\oplus\mu} A \cdot {}^{\mu\oplus v} B \quad (\text{A.18e})$$

if  $D^\mu A = D^\mu B = {}^\mu D$ , and if for each  $(k_1, \dots, k_u) \in D^u A$ , and for each  $(i_1, \dots, i_v) \in D^v B$

$$g_{k_1 \dots k_u i_1 \dots i_v} \stackrel{\Delta}{=} \sum_{\mu_D} a_{k_1 \dots k_u j_1 \dots j_\mu} b_{j_1 \dots j_\mu i_1 \dots i_v} \quad (\text{A.18f})$$

where the sum in (A.18f) denotes the  $\mu$ -fold summation with respect to  $(j_1, \dots, j_\mu)$  over the  $\mu$ -variate index-set  ${}^\mu D$ .

### Product of block, multi-indexed matrices

Given the  $M$ -block (row) matrix  $\{M\}_A$  (A.9), and the  $(M \times M)$ -block square-matrix  $\{M \times M\}_H$  (A.11), we shall say that the  $M$ -block (row),  $u$ -indexed matrix

$$\{M\}_G = [{}^u G]_{u=1, \dots, M} \quad ; \quad {}^u G = [g_{k_1, \dots, k_u}]_{(k_1, \dots, k_u) \in D^u G} \quad (\text{A.19a})$$

(where for  $u=1, \dots, M$  we have  $D^u G = D^u H$ , with  $D^{m \oplus u} H = D^m H \times D^u H$ )  
 is the block  $m$ -product of the matrices  $\{M\}_A$  and  $\{M \times M\}_H$

$$\{M\}_G = \{M\}_A \cdot \{M \times M\}_H \quad (\text{A.19b})$$

if for  $u=1, \dots, M$

$${}^u G \triangleq \sum_{m=1}^M m_A \cdot m^{\oplus u} H \quad (\text{A.19c})$$

with  $\cdot$  denoting the product (A.18e). Using (A.18) with  $\nu=0$ ,  $\mu=m$  and  $\nu=u$ , we can rewrite (A.19) as

$$g_{k_1 \dots k_u} = \sum_{m=1}^M \sum_{m_D} a_{j_1 \dots j_m} h_{j_1 \dots j_m k_1 \dots k_u} \quad (\text{A.19d})$$

where  $m_D = D^m A = D^m H$  and  $(k_1, \dots, k_u) \in D^u G$ . Equivalently, using (A.12d), we can write

$$g_{k_1 \dots k_u} = \{M\}_A \cdot \{M\}_H k_{k_1 \dots k_u} \quad (\text{A.19e})$$

### 'Outer' or Kronecker product of multi-indexed matrices

Let  ${}^m A$  be given by (A.13), and let  ${}^s B$  be expressed by (A.13) with  $m$  replaced by  $s$ . We shall say that the  $(m+s)$ -indexed matrix

$${}^{m \oplus s} G = [g_{j_1 \dots j_m k_1 \dots k_s}]_{(j_1, \dots, j_m) \in D^m A ; (k_1, \dots, k_s) \in D^s B} \quad (\text{A.20a})$$

(whose domain is  $D^{m \oplus s} G = D^m A \times D^s B$ ) is the 'outer' (or Kronecker)

product of the matrices  ${}^m A$  and  ${}^s B$

$${}^{m \oplus s} G = {}^m A \otimes {}^s B \quad (\text{A.20b})$$

if for each  $(j_1, \dots, j_m) \in D^m A$  and  $(k_1, \dots, k_s) \in D^s B$  we have

$$g_{j_1 \dots j_m k_1 \dots k_s} \stackrel{\Delta}{=} a_{j_1 \dots j_m} b_{k_1 \dots k_s} \quad (\text{A.20c})$$

From (A.20) it follows that if

$${}^1 Y = [y_j]_{j \in D^1 Y} \quad (\text{A.21a})$$

then

$${}^m Y = \otimes^m {}^1 Y = [y_{j_1 \dots j_m}]_{(j_1, \dots, j_m) \in D^m Y} \quad (\text{A.21b})$$

where

$$D^m Y = \underbrace{D^1 Y \times \dots \times D^1 Y}_m \quad (\text{A.21c})$$

### 'Outer' product of block, multi-indexed matrices

Let

$$\{M\} Y = [{}^m Y]_{m=1, \dots, M} \quad (\text{A.22a})$$

where  ${}^m Y$  is given by (A.21), and moreover let

$$\{M \times M\} G = [{}^{m \oplus u} G]_{m, u=1, \dots, M} \quad (\text{A.22b})$$



with

$$m^{\oplus u}_G = [\mathbb{g}_{j_1 \dots j_m k_1 \dots k_u}] \quad (j_1, \dots, j_m) \in D^{m_Y} ; (k_1, \dots, k_u) \in D^{u_Y} \quad (\text{A.22c})$$

We shall say that the matrix  $\{M \times M\}_G$  is the block, outer-product

$$\{M \times M\}_G = \{M\}_Y \otimes \{M\}_Y \quad (\text{A.22d})$$

if for  $m, u=1, \dots, M$

$$m^{\oplus u}_G \stackrel{\Delta}{=} m_Y \otimes u_Y \quad (\text{A.22e})$$

or, equivalently, if for each  $(j_1, \dots, j_m) \in D^{m_Y}$  and  $(k_1, \dots, k_u) \in D^{u_Y}$

$$\mathbb{g}_{j_1 \dots j_m k_1 \dots k_u} = y_{j_1} \dots y_{j_m} y_{k_1} \dots y_{k_u} \quad (\text{A.22f})$$

APPENDIX 2

MULTI-VARIATE INDEX-SET RECURSIONS

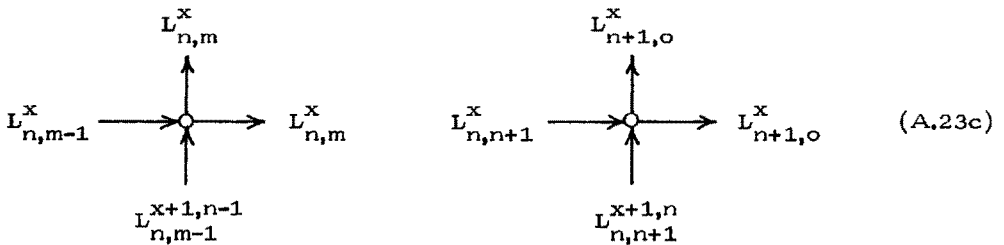
LB-recursions: 'local' order-updates for the 'bi-variate' part of the L-forward index-set, and for the 'uni-variate' part of the B-backward index-sets; i.e., for  $m=2,\dots,n+1$

$$L_{n,m}^x = L_{n,m-1}^x \cup L_{n,m-1}^{x+1,n-1} = \underbrace{\{x\} \cup L_{n,m-2}^{x+1,n-1}}_{L_{n,m-1}^x} \cup \overbrace{\{x+n+3-m, x+n+1\}}^{L_{n,m-1}^{x+1,n-1}} \quad (\text{A.23a})$$

and for  $m=n+2$

$$L_{n+1,o}^x = L_{n,n+1}^x \cup L_{n,n+1}^{x+1,n} = \underbrace{\{x\} \cup L_{n,n}^{x+1,n-1}}_{L_{n,n+1}^x} \cup \overbrace{\{x+1, x+n+1\}}^{L_{n,n+1}^{x+1,n}} \quad (\text{A.23b})$$

These recursions can be schematically described as the LB index-set sections



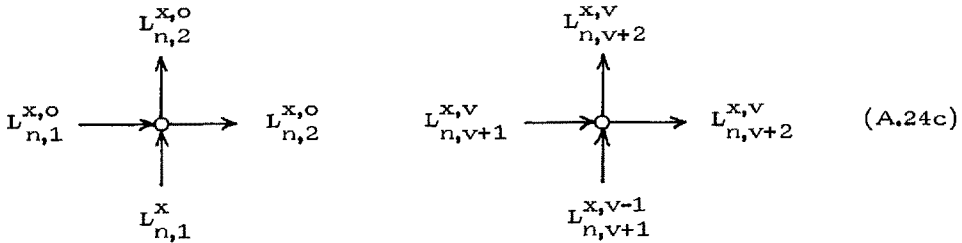
BL-recursions: 'local' order-updates for the 'uni-variate' part of the B-forward index-sets, and for the 'bi-variate' part of the L-backward index-set; i.e., for  $v=0$

$$L_{n,2}^{x,0} = L_{n,1}^{x,0} \cup L_{n,1}^x = \underbrace{\{x,x\}}_{L_{n,1}^{x,0}} \cup \overbrace{L_{n,0}^x \cup \{x+n+1\}}^{L_{n,1}^x} \quad (A.24a)$$

and for  $v=1,\dots,n$

$$L_{n,v+2}^{x,v} = L_{n,v+1}^{x,v} \cup L_{n,v+1}^{x,v-1} = \underbrace{\{x,x+v\}}_{L_{n,v+1}^{x,v}} \cup \overbrace{L_{n,v}^{x,v-1} \cup \{x+n+1\}}^{L_{n,v+1}^{x,v-1}} \quad (A.24b)$$

These recursions will be interpreted as the BL index-set sections



BB-recursions: 'local' order-updates for the 'bi-variate' parts of the B-forward and B-backward index-sets; i.e., for  $v=0$  and  $m=3,\dots,n+3$

$$L_{n,m}^{x,o} = L_{n,m-1}^{x,o} \cup L_{n,m-1}^x = \underbrace{\{x,x\} \cup L_{n,m-2}^x}_{L_{n,m-1}^{x,o}} \cup \overbrace{\{x+n+4-m, x+n+1\}}^{L_{n,m-1}^x} \quad (\text{A.25a})$$

and for  $v=1, \dots, n$  and  $m=v+3, \dots, v+n+3$

$$L_{n,m}^{x,v} = L_{n,m-1}^{x,v} \cup L_{n,m-1}^{x,v-1} = \underbrace{\{x, x+v\} \cup L_{n,m-2}^{x,v-1}}_{L_{n,m-1}^{x,v}} \cup \overbrace{\{x+n+4+v-m, x+n+1\}}^{L_{n,m-1}^{x,v-1}} \quad (\text{A.25b})$$

These recursions will result in the BB index-set sections

$$\begin{array}{ccc}
 L_{n,m-1}^{x,o} & \xrightarrow{\quad} & L_{n,m}^{x,o} \\
 \uparrow & \circ & \downarrow \\
 L_{n,m-1}^x & & L_{n,m}^{x,o}
 \end{array}
 \qquad
 \begin{array}{ccc}
 L_{n,m-1}^{x,v} & \xrightarrow{\quad} & L_{n,m}^{x,v} \\
 \uparrow & \circ & \downarrow \\
 L_{n,m-1}^{x,v-1} & & L_{n,m}^{x,v}
 \end{array}
 \quad (\text{A.25c})$$

## 'LOCAL' ORDER-UPDATE RECURSIONS

LB-recursions: for  $m=2,\dots,n+1$ 

$$\begin{bmatrix} A_{n,m}^x(z) \\ B_{n,m}^x(z) \end{bmatrix} = \theta_{n,m}^x \begin{bmatrix} A_{n,m-1}^x(z) \\ z \cdot B_{n,m-1}^{x+1,n-1}(z) \end{bmatrix} \quad (\text{A.26a})$$

$$\rho_{n,m}^x = (A_{n,m}^x(z), z \cdot B_{n,m-1}^{x+1,n-1}(z))_{\mathbf{Z}} \quad (\text{A.26b})$$

and for  $m=n+2$ 

$$\begin{bmatrix} A_{n+1,o}^x(z) \\ B_{n+1,o}^x(z) \end{bmatrix} = \theta_{n+1,o}^x \begin{bmatrix} A_{n,n+1}^x(z) \\ z \cdot B_{n,n+1}^{x+1,n}(z) \end{bmatrix} \quad (\text{A.26c})$$

$$\rho_{n+1,o}^x = (A_{n,n+1}^x(z), z \cdot B_{n,n+1}^{x+1,n}(z))_{\mathbf{Z}} \quad (\text{A.26d})$$

BL-recursions: for  $v=0$ 

$$\begin{bmatrix} A_{n,2}^{x,o}(z) \\ B_{n,2}^{x,o}(z) \end{bmatrix} = \theta_{n,2}^{x,o} \begin{bmatrix} A_{n,1}^{x,o}(z) \\ B_{n,1}^x(z) \end{bmatrix} \quad (\text{A.27a})$$

$$\rho_{n,2}^{x,o} = (A_{n,1}^{x,o}(z), B_{n,1}^x(z))_{\mathbf{Z}} \quad (\text{A.27b})$$

for  $v=1, \dots, n$

$$\begin{bmatrix} A_{n,v+2}^{x,v}(Z) \\ B_{n,v+2}^{x,v}(Z) \end{bmatrix} = \theta_{n,v+2}^{x,v} \begin{bmatrix} A_{n,v+1}^{x,v}(Z) \\ B_{n,v+1}^{x,v-1}(Z) \end{bmatrix} \quad (\text{A.27c})$$

$$\rho_{n,m}^{x,o} = (A_{n,v+1}^{x,o}(Z), B_{n,v+1}^{x,v-1}(Z))_{\mathbf{Z}} \quad (\text{A.27d})$$

BB-recursions: for  $v=0$  and  $m=3, \dots, n+3$

$$\begin{bmatrix} A_{n,m}^{x,o}(Z) \\ B_{n,m}^{x,o}(Z) \end{bmatrix} = \theta_{n,m}^{x,o} \begin{bmatrix} A_{n,m-1}^{x,o}(Z) \\ B_{n,m-1}^x(Z) \end{bmatrix} \quad (\text{A.28a})$$

$$\rho_{n,m}^{x,o} = (A_{n,m-1}^{x,o}(Z), B_{n,m-1}^x(Z))_{\mathbf{Z}} \quad (\text{A.28b})$$

for  $v=1, \dots, n$  and  $m=v+3, \dots, v+n+3$

$$\begin{bmatrix} A_{n,m}^{x,v}(Z) \\ B_{n,m}^{x,v}(Z) \end{bmatrix} = \theta_{n,m}^{x,v} \begin{bmatrix} A_{n,m-1}^{x,v}(Z) \\ B_{n,m-1}^{x,v-1}(Z) \end{bmatrix} \quad (\text{A.28c})$$

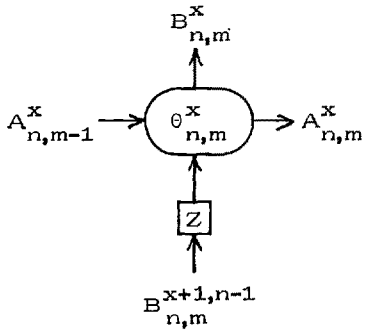
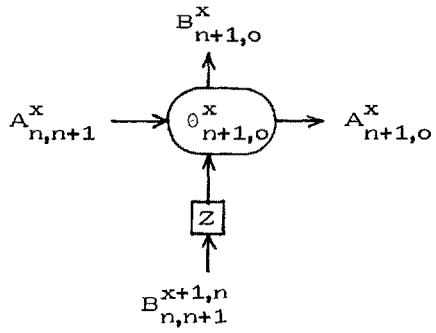
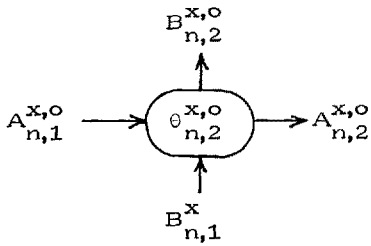
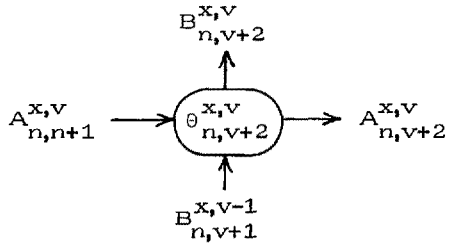
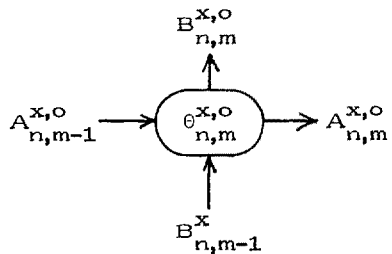
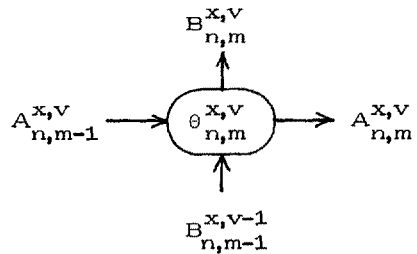
$$\rho_{n,m}^{x,v} = (A_{n,m-1}^{x,v}(Z), B_{n,m-1}^{x,v-1}(Z))_{\mathbf{Z}} \quad (\text{A.28d})$$

where

$$\theta_{n,m}^x = (1 - [\rho_{n,m}^x]^2)^{-\frac{1}{2}} \begin{bmatrix} 1 & -\rho_{n,m}^x \\ -\rho_{n,m}^x & 1 \end{bmatrix} \quad (\text{A.29a})$$

$$\theta_{n,m}^{x,v} = (1 - [\rho_{n,m}^{x,v}]^2)^{-\frac{1}{2}} \begin{bmatrix} 1 & -\rho_{n,m}^{x,v} \\ -\rho_{n,m}^{x,v} & 1 \end{bmatrix} \quad (\text{A.29b})$$

## 'LOCAL' FILTER SECTIONS

LB-sections:for  $m=2, \dots, n+1$ for  $m=n+2$ BL-sections:for  $v=0$ for  $v=1, \dots, n$ BB-sections:for  $v=0$  and  $m=3, \dots, n+3$ for  $v=1, \dots, n$  and  $m=v+3, \dots, v+n+3$