
INDEX

A

- AI, 12, 215
- Adaptive control, 9, 88
- After-processing, 1
- Application-specific shell, 269
- Armijo algorithm, 78, 185
- Artificial intelligence, 12, 215, 265
- Artificial neural network, 245
 - activation function, 250
 - application, 254
 - data preparation, 256
 - feedforward –, 249
 - learning paradigm, 251
 - backpropagation, 251
 - backward pass, 253
 - conjugated gradient method, 254
 - forward pass, 253
 - generalized decent algorithm, 253, 259
 - learning rate, 253
 - neurons, 249, 250
 - training (see learning paradigm)
 - weights, 249, 250

B

- Base, 229
 - data, 217
 - dynamic facts, 229
 - knowledge, 217
 - method, 229
 - optimization, 229
 - static facts, 229
- Basis weight, 7, 98
 - dry, 8, 49
 - ream, 256
 - reel, 49, 92
 - total, 8
- Bilinear decoupling control, 125
 - arbitrary pole assignment, 127
 - application, 129
- Bilinear observer, 136
 - application, 141
 - Minimal-order observer, 137
 - asymptotically stable, 137
 - state and disturbance composite observer, 137
- Bilinear suboptimal control, 146
 - application, 150

C

- CAD, 215
- Calenders, 4
- Computer-aided design, 215
- Conceptual design, 222
- Conflict resolution, 217
- Coupling, 91
- Coupling system, 218
- Cross machine direction control, 9
- CVD, current value data base, 268
- Cylinder-mould paper machine, 89,103
 - forming cylinder, 89
 - vat, 89

D

- DCS, 265, 266
- Decoupling control, 114, 125
 - bilinear, 125
 - feedforward, 114
- Drive, 5
- Drying section, 4
 - air borne dryer, 256
 - control, 150, 185
 - predryer, 256
 - steam-heated cylinder, 4, 40
- Dynamic programming, 198

E

- Emergency support, 274, 278
- Expert system, 215, 265
 - developing procedures of, 216

F

- fault detection, 162,278
 - Bayes' rule, 164
 - failure detection scheme, 165, 166
 - failure hypothesis, 163, 165
 - probability, 164, 167
 - probability density, 164
- Fault propagation, 282
- Fault-reasoning, 284
- Fault-tolerance analysis, 176
 - definition, 176
 - fault degree, 175
 - fault mode, 175
 - influence matrix, 176
- Fault-tolerant control, 157
 - application, 168
 - system reorganization, 170
- Fault-tolerance design, 181
 - application, 185
 - gradient based algorithm, 181
- Finishing end, 5
- Fourdrinier paper machine, 2, 103
- Function modeling, 281
- Function module, 226, 271
- Fuzzy optimal control, 193
 - application, 199
 - fuzzy cost, 198
 - fuzzy model, 197
 - fuzzy rule, 198
- Fuzzy set, 195
 - membership value of, 195
 - strict normalized, 196

- universe discourse, 195, 196
 - generic element of, 196
 - membership function of, 196
- Fuzzy-precise combined control, 204
 - algorithm, 207
 - application, 208
 - appropriate control principle, 204
 - model, 205

G

- General function modules, 271
- General information module, 272

H

- HDB, historical data base, 268
- Headbox 3, 5, 19, 30, 129, 168
 - basis weight valve, 255
 - control, 64, 129, 168
 - fan pump, 159
 - modeling, 19, 30
 - open-, 30, 129
 - pressurized- 19, 159, 255
 - rectifier, 159
 - rush/drag ratio, 160
 - state estimation, 84
 - total head, 160
- Heuristic, 225
 - knowledge, 225, 278
 - reasoning, 218
- Hierarchical decomposition, 282
- Hypertext, 272

I

- Identification, 96, 108
- IDIDS, 215, 221
- IDIS, 219
- Impulse response model, 105
- Inference engine, 229
- Integrated distributed intelligent system, 219, 221
- IOMCS, 265, 268

K

- Kalman filter, 71
 - adaptive fading-, 71
 - application, 84
 - forgetting factor, 74, 75, 79, 80
 - optimality, 75
 - stability, 80
- k-incremental predictor, 93

L

- Lagrange multiplier, 56
- Linearization, 246

M

- Machine optimization, 10
- Matrix
 - left singular vector of, 181
 - right singular vector of, 181
- Matrix simulator, 273, 275
- Meta-COOP, 286
- Meta-system, 230, 231
- Model algorithmic control, 102

- application, 114
- feedforward decoupling, 114
- impulse response model, 105
- optimality criterion, 106
- prediction
 - closed-loop, 107
 - open-loop, 107
- reference trajectory, 106, 107
- Modeling, 17
 - drying section, 39
 - equivalent dryer, 47
 - simulated by electricity network, 46
 - headbox
 - open-, 30
 - pressurized-, 19
 - wire and press, 35
- Moisture content, 7, 39, 97, 199
- MOPS, 266
- Multiple knowledge representation, 269
- N**
- Neural network (see artificial neural network)
- O**
- Object-oriented programming, 226
- Observer (see bilinear observer)
- Off-line system, 220
- On-line closed loop system, 221
- On-line monitoring and control, 265
- On-line supervisory system, 220
- Open architecture, 269
- Operation optimization, 274
- Optimal control
 - bilinear-, 146
 - fault-tolerance design of, 174
 - fuzzy-, 193
 - performance criterion, 174
 - specified degree of stability, 174
- P**
- Paper machine
 - cylinder-mould-, 89, 103
 - Fourdrinier-, 2, 17, 103
- Parameter estimation, 96, 108
- PCET, 233
- Polynomial
 - characteristic polynomial, 63
 - least common factor, 55
 - monic minimal, 54
 - stable, 54
 - unstable, 55
- Predictive control, 71, 88, 102
 - application, 97
 - k-incremental predictor, 93
- Press section, 3
 - press loading, 257
- Process generality, 269
- Pulping, 1
- Q**
- Quality Prediction, 246, 273

R

Reasoning, 219, 284

Robust control, 53

 application, 64

 regulation, 54

 simultaneous dominance, 55

 simultaneous stabilization, 58

 stability, 55

S

Self-tuning controller, 92

State transformation, 137

Stock preparation, 1

Structural modeling, 281

Symbolic reasoning, 217

T

Time delay, 89, 246

W

Weighting factor, 249, 253

Wire section, 3, 35