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# Ulam–Hyers–Mittag-Leffler stability for $\psi$ -Hilfer fractional-order delay differential equations

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## Abstract

In this paper, we present results on the existence, uniqueness, and Ulam–Hyers–Mittag-Leffler stability of solutions to a class of  $\psi$ -Hilfer fractional-order delay differential equations. We use the Picard operator method and a generalized Gronwall inequality involved in a  $\psi$ -Riemann–Liouville fractional integral. Finally, we give two examples to illustrate our main theorems.

**Keywords:**  $\psi$ -Hilfer fractional-order delay differential equations; Solutions; Existence; Stability

## 1 Introduction

Fractional-order differential equations are important since their nonlocal property is suitable to characterize memory phenomena in economic, control, and materials sciences. Existence, stability, and control theory to fractional differential equations was investigated in [1–21]. In particular, the Ulam-type stability of delay differential equations was investigated in [22–30]. In [22], results for a delay differential equation were obtained using the Picard operator method, and in [23] the authors adopted a similar approach to establish the existence and uniqueness results for a Caputo-type fractional-order delay differential equation. In [31, 32], the authors gave stability and numerical schemes for two classes of fractional equations. Sousa and Oliveira [33] proposed the  $\psi$ -Hilfer fractional differentiation operator and established  $\psi$ -Hilfer fractional differential equations. In [24] the authors studied the Ulam–Hyers stability and the Ulam–Hyers–Rassias stability of  $\psi$ -Hilfer fractional integro-differential equations via the Banach fixed point method, and in [28] the author discussed the existence and uniqueness of solutions and Ulam–Hyers and Ulam–Hyers–Rassias stabilities for  $\psi$ -Hilfer nonlinear fractional differential equations via a generalized Gronwall inequality (see [34]).

Motivated by [23, 24, 28], we consider the  $\psi$ -Hilfer fractional differential equation

$$\begin{cases} {}^H\mathbb{D}_{0^+}^{\alpha,\beta;\psi} x(\tau) = f(\tau, x(\tau), x(g(\tau))), & \tau \in I = (0, d), \\ I_{0^+}^{1-\gamma;\psi} x(0^+) = x_0 \in \mathbb{R}, \\ x(\tau) = \varphi(\tau), & \tau \in [-h, 0], \end{cases} \quad (1)$$

where  ${}^H\mathbb{D}_{0^+}^{\alpha,\beta;\psi}(\cdot)$  is the  $\psi$ -Hilfer fractional derivative (see Definition 2.1) of order  $0 < \alpha \leq 1$  and type  $0 \leq \beta \leq 1$ ,  $I_{0^+}^{1-\gamma;\psi}(\cdot)$  is the Riemann–Liouville fractional integral of order  $1 - \gamma$ ,  $\gamma = \alpha + \beta(1 - \alpha)$  with respect to the function  $\psi$  (see [2]), and  $f : I \times \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$  is a given function.

We establish the existence and uniqueness of solutions for (1) using the Picard operator approach in a weight function space. We also introduce and present Ulam–Hyers–Mittag-Leffler stability of solutions to (1).

## 2 Preliminaries

We collect the basic definitions of the  $\psi$ -Riemann–Liouville fractional integral, the  $\psi$ -Hilfer fractional derivative, and the standard Picard operator and an abstract Gronwall lemma.

Let  $[c, d]$  ( $0 < c < d < \infty$ ) be a finite interval on  $\mathbb{R}^+$ , and let  $C[c, d]$  be the space of continuous function  $g : [c, d] \rightarrow \mathbb{R}$  with norm

$$\|g\|_{C[c,d]} = \max_{c \leq x \leq d} |g(x)|.$$

The weighted space  $C_{1-\gamma;\psi}[c, d]$  of continuous  $g$  on  $(c, d]$  is defined by (see [24])

$$C_{1-\gamma;\psi}[c, d] = \{g : (c, d] \rightarrow \mathbb{R}; (\psi(x) - \psi(c))^{1-\gamma} g(x) \in C[c, d]\}, \quad 0 \leq \gamma < 1,$$

with norm

$$\|g\|_{C_{1-\gamma;\psi}[c,d]} = \max_{x \in [c,d]} |(\psi(x) - \psi(c))^{1-\gamma} g(x)|$$

or

$$\|g\|_B := \max_{\tau \in [c,d]} |(\psi(\tau) - \psi(c))^{1-\gamma} g(\tau)| e^{-\theta(\psi(\tau) - \psi(c))}, \quad \theta > 0.$$

**Definition 2.1** (see [33]) Let  $(c, d)$  ( $-\infty \leq c < d \leq \infty$ ) be a finite or infinite interval of the real line  $\mathbb{R}$ , and let  $\alpha > 0$ . In addition, let  $\psi(x)$  be an increasing and positive monotone function on  $(c, d]$  having a continuous derivative  $\psi'(x)$  on  $(c, d)$ . The left- and right-sided fractional integrals of a function  $g$  with respect to a function  $\psi$  on  $[c, d]$  are defined by

$$I_{c^+}^{\alpha;\psi} g(x) = \frac{1}{\Gamma(\alpha)} \int_c^x \psi'(\tau) (\psi(x) - \psi(\tau))^{\alpha-1} g(\tau) dt,$$

$$I_{d^-}^{\alpha;\psi} g(x) = \frac{1}{\Gamma(\alpha)} \int_x^d \psi'(\tau) (\psi(\tau) - \psi(x))^{\alpha-1} g(\tau) dt,$$

respectively; here  $\Gamma$  is the gamma function.

**Definition 2.2** (see [33]) Let  $n - 1 < \alpha < n$  with  $n \in \mathbb{N}$ , and let  $f, \psi \in C^n[c, d]$  be two functions such that  $\psi$  is increasing and  $\psi'(x) \neq 0$  for all  $x \in [c, d]$ . The left-side  $\psi$ -Hilfer fractional derivative  ${}^H\mathbb{D}_{c^+}^{\alpha,\beta;\psi}(\cdot)$  of a function  $g$  of order  $\alpha$  and type  $0 \leq \beta \leq 1$  is defined by

$${}^H\mathbb{D}_{c^+}^{\alpha,\beta;\psi} g(x) = I_{c^+}^{\beta(n-\alpha);\psi} \left( \frac{1}{\psi'(x)} \frac{d}{dx} \right)^n I_{c^+}^{(1-\beta)(n-\alpha);\psi} g(x).$$

The right-sided  $\psi$ -Hilfer fractional derivative is defined in an analogous way.

**Theorem 2.3** (see [33]) *If  $g \in C^1[c, d]$ ,  $0 < c < 1$ , and  $0 \leq \beta \leq 1$ , then*

$${}^H\mathbb{D}_{c^+}^{\alpha, \beta; \psi} I_{c^+}^{\alpha; \psi} g(x) = g(x).$$

**Theorem 2.4** (see [33]) *If  $g \in C^1[c, d]$ ,  $0 < c < 1$ , and  $0 \leq \beta \leq 1$ , then*

$$I_{c^+}^{\alpha; \psi} {}^H\mathbb{D}_{c^+}^{\alpha, \beta; \psi} g(x) = g(x) - \frac{(\psi(x) - \psi(c))^{\gamma-1}}{\Gamma(\gamma)} I_{c^+}^{(1-\beta)(1-\alpha); \psi} g(c).$$

Let  $I = [c, d]$ . For  $f \in C(I \times \mathbb{R}^2, \mathbb{R})$  and  $\varepsilon > 0$ , we consider the equations

$${}^H\mathbb{D}_{0^+}^{\alpha, \beta; \psi} x(\tau) = f(\tau, x(\tau), x(g(\tau))), \quad \tau \in (0, d], \tag{2}$$

$$I_{0^+}^{1-\gamma; \psi} x(0^+) = x_0, \tag{3}$$

$$x(\tau) = \varphi(\tau), \quad \tau \in [-h, 0], \tag{4}$$

and the inequality

$$|{}^H\mathbb{D}_{0^+}^{\alpha, \beta; \psi} x(\tau) - f(\tau, x(\tau), x(g(\tau)))| \leq \varepsilon \mathbb{E}_\alpha((\psi(\tau) - \psi(0))^\alpha), \quad \tau \in (0, d], \tag{5}$$

where  $\mathbb{E}_\alpha$  is the Mittag-Leffler function [2] defined by

$$\mathbb{E}_\alpha(x) := \sum_{i=0}^{\infty} \frac{x^i}{\Gamma(i\alpha + 1)}, \quad x \in \mathbb{C}, \Re(\alpha) > 0. \tag{6}$$

Motivated by [23, Lemma 2.4], we introduce the following concept.

**Definition 2.5** Equation (2) is Ulam–Hyers–Mittag-Leffler stable with respect to  $\mathbb{E}_\alpha((\psi(\tau) - \psi(0))^\alpha)$  if there exists  $c_{\mathbb{E}_\alpha} > 0$  such that, for each  $\varepsilon > 0$  and each solution  $y \in C([-h, d], \mathbb{R})$  to (5), there exists a solution  $x \in C([-h, d], \mathbb{R})$  to (2) with

$$|y(\tau) - x(\tau)| \leq c_{\mathbb{E}_\alpha} \varepsilon \mathbb{E}_\alpha((\psi(\tau) - \psi(0))^\alpha), \quad \tau \in [-h, d].$$

*Remark 2.6* A function  $x \in C([-h, d], \mathbb{R})$  is a solution of inequality (5) if and only if there exists a function  $\tilde{h} \in C([-h, d], \mathbb{R})$  (which depends on  $x$ ) such that

- (i)  $|\tilde{h}(\tau)| \leq \varepsilon \mathbb{E}_\alpha((\psi(\tau) - \psi(0))^\alpha), \tau \in [-h, d]$ ,
- (ii)  ${}^H\mathbb{D}_{0^+}^{\alpha, \beta; \psi} x(\tau) = f(\tau, x(\tau), x(g(\tau))) + \tilde{h}(\tau), \tau \in (0, d]$ .

**Definition 2.7** (see Definition 3.1 of [23]) Let  $(Y, \rho)$  be a metric space. Now  $T : Y \rightarrow Y$  is a Picard operator if there exists  $y^* \in Y$  such that

- (i)  $F_T = y^*$  where  $F_T = \{y \in Y : T(y) = y\}$  is the fixed point set of  $T$ ;
- (ii) the sequence  $(T^n(y_0))_{n \in \mathbb{N}}$  converges to  $y^*$  for all  $y_0 \in Y$ .

**Lemma 2.8** (see Lemma 3.2 of [23]) *Let  $(Y, \rho, \leq)$  be an ordered metric space, and let  $T : Y \rightarrow Y$  be an increasing Picard operator with  $F_T = \{y_T^*\}$ . Then for  $y \in Y, y \leq T(y)$  implies  $y \leq y_T^*$ .*

From Theorems 2.3 and 2.4 we have the following:

**Lemma 2.9** (see [24]) *Let  $f : I \times \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$  be a continuous function. Then (2) is equivalent to*

$$x(\tau) = \frac{(\psi(\tau) - \psi(0))^{\gamma-1}}{\Gamma(\gamma)} x_0 + \frac{1}{\Gamma(\alpha)} \int_0^\tau \psi'(s) (\psi(\tau) - \psi(s))^{\alpha-1} f(s, x(s), x(g(s))) ds. \tag{7}$$

*Remark 2.10* Let  $y \in C(I, \mathbb{R})$  be a solution of inequality (5). Then  $y$  is a solution of the following integral inequality:

$$\begin{aligned} & \left| y(\tau) - \frac{(\psi(\tau) - \psi(0))^{\gamma-1}}{\Gamma(\gamma)} y_0 - \frac{1}{\Gamma(\alpha)} \int_0^\tau \psi'(s) (\psi(\tau) - \psi(s))^{\alpha-1} f(s, y(s), y(g(s))) ds \right| \\ & \leq \frac{\varepsilon}{\Gamma(\alpha)} \int_0^\tau \psi'(s) (\psi(\tau) - \psi(s))^{\alpha-1} \mathbb{E}_\alpha((\psi(s) - \psi(0))^\alpha) ds \\ & = \frac{\varepsilon}{\Gamma(\alpha)} \int_0^\tau \psi'(s) (\psi(\tau) - \psi(s))^{\alpha-1} \sum_{k=0}^\infty \frac{(\psi(s) - \psi(0))^{k\alpha}}{\Gamma(k\alpha + 1)} ds \\ & = \frac{\varepsilon}{\Gamma(\alpha)} \sum_{k=0}^\infty \frac{1}{\Gamma(k\alpha + 1)} \int_0^\tau (\psi(\tau) - \psi(s))^{\alpha-1} (\psi(s) - \psi(0))^{k\alpha} d\psi(s) \\ & = \frac{\varepsilon}{\Gamma(\alpha)} \sum_{k=0}^\infty \frac{1}{\Gamma(k\alpha + 1)} \int_0^{\psi(\tau) - \psi(0)} (\psi(\tau) - \psi(0) - u)^{\alpha-1} u^{k\alpha} du \\ & \quad (\text{let } u = \psi(s) - \psi(0)) \\ & = \frac{\varepsilon}{\Gamma(\alpha)} \sum_{k=0}^\infty \frac{1}{\Gamma(k\alpha + 1)} (\psi(\tau) - \psi(0))^{\alpha-1} \int_0^{\psi(\tau) - \psi(0)} \left(1 - \frac{u}{\psi(\tau) - \psi(0)}\right)^{\alpha-1} u^{k\alpha} du \\ & = \frac{\varepsilon}{\Gamma(\alpha)} \sum_{k=0}^\infty \frac{1}{\Gamma(k\alpha + 1)} (\psi(\tau) - \psi(0))^{(k+1)\alpha} \int_0^1 (1 - \nu)^{\alpha-1} \nu^{k\alpha} d\nu \\ & \quad \left(\text{let } \nu = \frac{u}{\psi(\tau) - \psi(0)}\right) \\ & = \frac{\varepsilon}{\Gamma(\alpha)} \sum_{k=0}^\infty \frac{1}{\Gamma(k\alpha + 1)} (\psi(\tau) - \psi(0))^{(k+1)\alpha} \frac{\Gamma(k\alpha + 1)\Gamma(\alpha)}{\Gamma((k+1)\alpha + 1)} \\ & \leq \varepsilon \sum_{n=0}^\infty \frac{(\psi(\tau) - \psi(0))^{n\alpha}}{\Gamma(n\alpha + 1)} \\ & = \varepsilon \mathbb{E}_\alpha((\psi(\tau) - \psi(0))^\alpha). \end{aligned}$$

**Lemma 2.11** (see [34]) *Let  $\alpha > 0$ , and let  $\psi \in C^1((0, d], \mathbb{R})$  be a function such that  $\psi$  is increasing and  $\psi'(\tau) \neq 0$  for all  $\tau \in (0, d]$ . Suppose that  $d \geq 0$ ,  $z$  is a nonnegative function locally integrable on  $(0, d]$ , and  $w$  is nonnegative and locally integrable on  $(0, d]$  with*

$$w(\tau) \leq z(\tau) + k \int_0^\tau \psi'(s) (\psi(\tau) - \psi(s))^{\alpha-1} w(s) ds, \quad \tau \in (0, d].$$

*Then*

$$w(\tau) \leq z(\tau) + \int_0^\tau \sum_{n=1}^\infty \frac{[k\Gamma(\alpha)]^n}{\Gamma(n\alpha)} \psi'(s) (\psi(\tau) - \psi(s))^{\alpha-1} z(s) ds, \quad \tau \in (0, d].$$

*Remark 2.12* (see [34]) Under the hypotheses of Lemma 2.11, let  $z$  be a nondecreasing function on  $(0, d]$ . Then we have

$$w(\tau) \leq z(\tau)\mathbb{E}_\alpha(k\Gamma(\alpha)[\psi(\tau) - \psi(0)]^\alpha), \quad \tau \in (0, d],$$

where  $\mathbb{E}_\alpha$  is the Mittag-Leffler function defined by (6).

### 3 Main results

In this section, we establish the existence, uniqueness, and Ulam–Hyers–Mittag-Leffler stability.

We impose the following conditions.

(H<sub>1</sub>)  $f \in C(I \times \mathbb{R}^2, \mathbb{R}), g \in C(I, [-h, d]), g(\tau) \leq \tau, h > 0$ .

(H<sub>2</sub>) There exists  $L_f > 0$  such that

$$|f(\tau, u_1, u_2) - f(\tau, v_1, v_2)| \leq L_f \sum_{i=1}^2 |u_i - v_i| \quad \text{for all } \tau \in I, u_i, v_i \in \mathbb{R}, i = 1, 2.$$

(H<sub>3</sub>) We have the inequality

$$\frac{2L_f \Gamma(\gamma)(\psi(d) - \psi(0))^\alpha}{\Gamma(\gamma + \alpha)} < 1.$$

**Theorem 3.1** *Assume that (H<sub>1</sub>), (H<sub>2</sub>), and (H<sub>3</sub>) are satisfied. Then*

- (i) (2)–(4) has a unique solution in  $C[-h, d] \cap C_{1-\gamma, \psi}[c, d]$ .
- (ii) (2) is Ulam–Hyers–Mittag-Leffler stable.

*Proof* From Lemma 2.9 we get that (2)–(4) is equivalent to the following system:

$$y(\tau) = \begin{cases} \varphi(\tau), & \tau \in [-h, 0], \\ \frac{(\psi(\tau) - \psi(0))^{\gamma-1}}{\Gamma(\gamma)} y_0 + \frac{1}{\Gamma(\alpha)} \int_0^\tau \psi'(s)(\psi(\tau) - \psi(s))^{\alpha-1} f(s, y(s), y(g(s))) ds, & \tau \in (0, d]. \end{cases} \tag{8}$$

The existence of a solution for (8) can be turned into a fixed point problem in  $X := C[-h, d]$  for the operator  $T_f$  defined by

$$T_f(x)(\tau) = \begin{cases} \varphi(\tau), & \tau \in [-h, 0], \\ \frac{(\psi(\tau) - \psi(0))^{\gamma-1}}{\Gamma(\gamma)} y_0 + \frac{1}{\Gamma(\alpha)} \int_0^\tau \psi'(s)(\psi(\tau) - \psi(s))^{\alpha-1} f(s, y(s), y(g(s))) ds, & \tau \in (0, d]. \end{cases} \tag{9}$$

Note that for any continuous function  $f$ ,  $T_f$  is also continuous. Indeed,

$$\begin{aligned} & |T_f(x)(\tau) - T_f(x)(\tau_0)| \\ &= \left| \frac{(\psi(\tau) - \psi(0))^{\gamma-1}}{\Gamma(\gamma)} y_0 + \frac{1}{\Gamma(\alpha)} \int_0^\tau \psi'(s)(\psi(\tau) - \psi(s))^{\alpha-1} f(s, y(s), y(g(s))) ds \right. \end{aligned}$$

$$\begin{aligned}
 & \left| -\frac{(\psi(\tau_0) - \psi(0))^{\gamma-1}}{\Gamma(\gamma)} y_0 - \frac{1}{\Gamma(\alpha)} \int_0^{\tau_0} \psi'(s) (\psi(\tau_0) - \psi(s))^{\alpha-1} f(s, y(s), y(g(s))) ds \right| \\
 & \rightarrow 0
 \end{aligned}$$

as  $\tau \rightarrow \tau_0$ .

Next, we show  $T_f$  defined in (9) is a contraction mapping on  $X := C[-h, d]$  with respect to  $\|\cdot\|_{C_{1-\gamma;\psi}[0,d]}$ . Consider  $T_f : X \rightarrow X$  defined in (9). For  $\tau \in [-h, 0]$ , we have

$$|T_f(x)(\tau) - T_f(y)(\tau)| = 0, \quad x, y \in C([-h, 0], \mathbb{R}).$$

For all  $\tau \in (0, d]$ , we have

$$\begin{aligned}
 & |T_f(x)(\tau) - T_f(y)(\tau)| \\
 & \leq \frac{1}{\Gamma(\alpha)} \int_0^\tau \psi'(s) (\psi(\tau) - \psi(s))^{\alpha-1} |f(s, x(s), x(g(s))) - f(s, y(s), y(g(s)))| ds \\
 & \leq \frac{L_f}{\Gamma(\alpha)} \int_0^\tau \psi'(s) (\psi(\tau) - \psi(s))^{\alpha-1} (\psi(s) - \psi(0))^{\gamma-1} \{ (\psi(s) - \psi(0))^{1-\gamma} [|x(s) - y(s)| \\
 & \quad + |x(g(s) - y(g(s)))] \} ds \\
 & \leq \frac{L_f}{\Gamma(\alpha)} \int_0^\tau \psi'(s) (\psi(\tau) - \psi(s))^{\alpha-1} (\psi(s) - \psi(0))^{\gamma-1} \\
 & \quad \times \left[ \max_{s \in [0,d]} |(\psi(s) - \psi(0))^{1-\gamma} (x(s) - y(s))| \right. \\
 & \quad \left. + \max_{s \in [0,d]} |(\psi(s) - \psi(0))^{1-\gamma} x(g(s) - y(g(s)))| \right] ds \\
 & \leq \frac{2L_f}{\Gamma(\alpha)} \|x - y\|_{C_{1-\gamma;\psi}[0,d]} \int_0^\tau \psi'(s) (\psi(\tau) - \psi(s))^{\alpha-1} (\psi(s) - \psi(0))^{\gamma-1} ds \\
 & = \frac{2L_f (\psi(\tau) - \psi(0))^{\alpha+\gamma-1}}{\Gamma(\alpha)} \frac{\Gamma(\gamma)\Gamma(\alpha)}{\Gamma(\gamma + \alpha)} \|x - y\|_{C_{1-\gamma;\psi}[0,d]},
 \end{aligned}$$

which implies that

$$\|T_f(x) - T_f(y)\|_{C_{1-\gamma;\psi}[0,d]} \leq \frac{2L_f \Gamma(\gamma) (\psi(d) - \psi(0))^\alpha}{\Gamma(\alpha + \gamma)} \|x - y\|_{C_{1-\gamma;\psi}[0,d]}.$$

Thus  $T_f$  is a contraction (via the norm  $\|\cdot\|_{C_{1-\gamma;\psi}[0,d]}$  on  $X$ ). Now apply the Banach contraction principle to establish (i).

Now we prove (ii). Let  $y \in C[-h, 0] \cap C_{1-\gamma;\psi}[0, d]$  be a solution to (2). We denote by  $x \in C[-h, 0] \cap C_{1-\gamma;\psi}[0, d]$  the unique solution to problem (1). Now

$$x(\tau) = \begin{cases} \varphi(\tau), & \tau \in [-h, 0], \\ \frac{(\psi(\tau) - \psi(0))^{\gamma-1}}{\Gamma(\gamma)} y_0 + \frac{1}{\Gamma(\alpha)} \int_0^\tau \psi'(s) (\psi(\tau) - \psi(s))^{\alpha-1} f(s, y(s), y(g(s))) ds, & \tau \in (0, d]. \end{cases}$$

From Remark 2.10 we have

$$\begin{aligned} & \left| y(\tau) - \frac{(\psi(\tau) - \psi(0))^{\gamma-1}}{\Gamma(\gamma)} y_0 - \frac{1}{\Gamma(\alpha)} \int_0^\tau \psi'(s) (\psi(\tau) - \psi(s))^{\alpha-1} f(s, y(s), y(g(s))) ds \right| \\ & \leq \varepsilon \mathbb{E}_\alpha((\psi(\tau) - \psi(0))^\alpha) \end{aligned} \tag{10}$$

for  $\tau \in (0, d]$  and note that  $|y(\tau) - x(\tau)| = 0$  for  $\tau \in [-h, 0]$ .

For all  $\tau \in (0, d]$ , it follows from  $(H_2)$  and (10) that

$$\begin{aligned} & |y(\tau) - x(\tau)| \\ & \leq \left| y(\tau) - \frac{(\psi(\tau) - \psi(0))^{\gamma-1}}{\Gamma(\gamma)} y_0 - \frac{1}{\Gamma(\alpha)} \int_0^\tau \psi'(s) (\psi(\tau) - \psi(s))^{\alpha-1} f(s, y(s), y(g(s))) ds \right| \\ & \quad + \left| \frac{1}{\Gamma(\alpha)} \int_0^\tau \psi'(s) (\psi(\tau) - \psi(s))^{\alpha-1} f(s, y(s), y(g(s))) ds \right. \\ & \quad \left. - \frac{1}{\Gamma(\alpha)} \int_0^\tau \psi'(s) (\psi(\tau) - \psi(s))^{\alpha-1} f(s, x(s), x(g(s))) ds \right| \\ & \leq \varepsilon \mathbb{E}_\alpha((\psi(\tau) - \psi(0))^\alpha) \\ & \quad + \frac{L_f}{\Gamma(\alpha)} \int_0^\tau \psi'(s) (\psi(\tau) - \psi(s))^{\alpha-1} [|y(s) - x(s)| + |y(g(s)) - x(g(s))|] ds. \end{aligned} \tag{11}$$

For all  $w \in C([-h, d], \mathbb{R}_+)$ , consider the operator

$$T_1 : C([-h, d], \mathbb{R}_+) \rightarrow C([-h, d], \mathbb{R}_+)$$

defined by

$$T_1(w)(\tau) = \begin{cases} 0, & \tau \in [-h, 0], \\ \varepsilon \mathbb{E}_\alpha((\psi(\tau) - \psi(0))^\alpha) \\ \quad + \frac{L_f}{\Gamma(\alpha)} \left( \int_0^\tau \psi'(s) (\psi(\tau) - \psi(s))^{\alpha-1} w(s) ds \right. \\ \quad \left. + \int_0^\tau \psi'(s) (\psi(\tau) - \psi(s))^{\alpha-1} w(g(s)) ds \right), & \tau \in (0, d]. \end{cases}$$

We prove that  $T_1$  is a Picard operator. For all  $\tau \in [0, d]$ , it follows from  $(H_2)$  that

$$|T_1(w)(\tau) - T_1(z)(\tau)| \leq \frac{2L_f \Gamma(\gamma) (\psi(\tau) - \psi(0))^{\alpha+\gamma-1}}{\Gamma(\alpha + \gamma)} \|w - z\|_{C_{1-\gamma; \psi}[0, d]}$$

for all  $w, z \in C([-h, d], \mathbb{R})$ . Then we obtain

$$\|T_1(w) - T_1(z)\|_{C_{1-\gamma; \psi}[0, d]} \leq \frac{2L_f \Gamma(\gamma) (\psi(d) - \psi(0))^\alpha}{\Gamma(\alpha + \gamma)} \|w - z\|_{C_{1-\gamma; \psi}[0, d]}$$

for all  $w, z \in C([-h, d], \mathbb{R})$ . Thus  $T_1$  is a contraction (via the norm  $\|\cdot\|_{C_{1-\gamma; \psi}[0, d]}$  on  $C([-h, d], \mathbb{R})$ ).

Applying the Banach contraction principle to  $T_1$ , we see that  $T_1$  is a Picard operator and  $F_{T_1} = w^*$ . Then, for all  $\tau \in [0, d]$ , we have

$$w^*(\tau) (= T_1 w^*(\tau))$$

$$\begin{aligned}
 &= \varepsilon \mathbb{E}_\alpha((\psi(\tau) - \psi(0))^\alpha) \\
 &\quad + \frac{L_f}{\Gamma(\alpha)} \left( \int_0^\tau \psi'(s)(\psi(\tau) - \psi(s))^{\alpha-1} w^*(s) ds \right. \\
 &\quad \left. + \int_0^\tau \psi'(s)(\psi(\tau) - \psi(s))^{\alpha-1} w^*(g(s)) ds \right).
 \end{aligned}$$

Next, we show that the solution  $w^*$  is increasing. For all  $0 \leq \tau_1 < \tau_2 \leq d$  (letting  $m := \min_{s \in [0,d]} [w^*(s) + w^*(g(s))] \in \mathbb{R}_+$ ), we have

$$\begin{aligned}
 &w^*(\tau_2) - w^*(\tau_1) \\
 &= \varepsilon \left[ \mathbb{E}_\alpha((\psi(\tau_2) - \psi(0))^\alpha) - \mathbb{E}_\alpha((\psi(\tau_1) - \psi(0))^\alpha) \right] \\
 &\quad + \frac{L_f}{\Gamma(\alpha)} \int_0^{\tau_1} \psi'(s) [(\psi(\tau_2) - \psi(s))^{\alpha-1} - (\psi(\tau_1) - \psi(s))^{\alpha-1}] (w^*(s) + w^*(g(s))) ds \\
 &\quad + \frac{L_f}{\Gamma(\alpha)} \int_{\tau_1}^{\tau_2} \psi'(s) (\psi(\tau_2) - \psi(s))^{\alpha-1} (w^*(s) + w^*(g(s))) ds \\
 &\geq \varepsilon \left[ \mathbb{E}_\alpha((\psi(\tau_2) - \psi(0))^\alpha) - \mathbb{E}_\alpha((\psi(\tau_1) - \psi(0))^\alpha) \right] \\
 &\quad + \frac{mL_f}{\Gamma(\alpha)} \int_0^{\tau_1} \psi'(s) [(\psi(\tau_2) - \psi(s))^{\alpha-1} - (\psi(\tau_1) - \psi(s))^{\alpha-1}] ds \\
 &\quad + \frac{mL_f}{\Gamma(\alpha)} \int_{\tau_1}^{\tau_2} \psi'(s) (\psi(\tau_2) - \psi(s))^{\alpha-1} ds \\
 &= \varepsilon \left[ \mathbb{E}_\alpha((\psi(\tau_2) - \psi(0))^\alpha) - \mathbb{E}_\alpha((\psi(\tau_1) - \psi(0))^\alpha) \right] \\
 &\quad + \frac{mL_f}{\Gamma(\alpha + 1)} \left[ (\psi(\tau_2) - \psi(0))^\alpha - (\psi(\tau_1) - \psi(0))^\alpha \right] \\
 &> 0.
 \end{aligned}$$

Thus  $w^*$  is increasing, so  $w^*(g(\tau)) \leq w^*(\tau)$  since  $g(\tau) \leq \tau$  and

$$w^*(\tau) \leq \varepsilon \mathbb{E}_\alpha((\psi(\tau) - \psi(0))^\alpha) + \frac{2L_f}{\Gamma(\alpha)} \int_0^\tau \psi'(s)(\psi(\tau) - \psi(s))^{\alpha-1} w^*(s) ds.$$

Using Lemma 2.11 and Remark 2.12, we obtain

$$\begin{aligned}
 w^*(\tau) &\leq \varepsilon \mathbb{E}_\alpha((\psi(\tau) - \psi(0))^\alpha) \mathbb{E}_\alpha(2L_f(\psi(\tau) - \psi(0))^\alpha) \quad (\tau \in [0, d]) \\
 &\leq \varepsilon \mathbb{E}_\alpha((\psi(\tau) - \psi(0))^\alpha) \mathbb{E}_\alpha(2L_f(\psi(d) - \psi(0))^\alpha) \\
 &= c_{\mathbb{E}_\alpha} \varepsilon \mathbb{E}_\alpha((\psi(\tau) - \psi(0))^\alpha),
 \end{aligned}$$

where  $c_{\mathbb{E}_\alpha} := \mathbb{E}_\alpha(2L_f(\psi(d) - \psi(0))^\alpha)$ .

In particular, if  $w = |y - x|$ , from (11),  $w \leq T_1 w$  by Lemma 2.8 we obtain  $w \leq w^*$ , where  $T_1$  is an increasing Picard operator. As a result, we get

$$|y(\tau) - x(\tau)| \leq c_{E_\alpha} \varepsilon \mathbb{E}_\alpha((\psi(\tau) - \psi(0))^\alpha), \quad \tau \in [-h, d],$$

and thus (2) is Ulam–Hyers–Mittag-Leffler stable. □



Now we change  $(H_3)$  to

$(H_4)$  We have the inequality

$$\frac{2L_f \Gamma(\gamma) e^{\theta(\psi(d)-\psi(0))} (\psi(d) - \psi(0))^\alpha}{\Gamma(\alpha + \gamma)} < 1, \quad \theta > 0.$$

**Theorem 3.2** *Assume that  $(H_1)$ ,  $(H_2)$ , and  $(H_4)$  are satisfied. Then*

- (i) (2)–(4) has a unique solution in  $C[-h, d] \cap C_{1-\gamma; \psi}[0, d]$ .
- (ii) (2) is Ulam–Hyers–Mittag-Leffler stable.

*Proof* As in Theorem 3.1, we need only prove that  $T_f$  defined as before is a contraction on  $X$  (via the norm  $\| \cdot \|_B$ ). Since the process is standard, we only give the main difference in the proof as follows: For all  $\tau \in (0, d]$ , we have

$$\begin{aligned} & |T_f(x)(\tau) - T_f(y)(\tau)| \\ & \leq \frac{1}{\Gamma(\alpha)} \int_0^\tau \psi'(s) (\psi(\tau) - \psi(s))^{\alpha-1} |f(s, x(s), x(g(s))) - f(s, y(s), y(g(s)))| ds \\ & \leq \frac{L_f}{\Gamma(\alpha)} \int_0^\tau \psi'(s) (\psi(\tau) - \psi(s))^{\alpha-1} (|x(s) - y(s)| + |x(g(s)) - y(g(s))|) \\ & \leq \frac{L_f}{\Gamma(\alpha)} \int_0^\tau \psi'(s) (\psi(\tau) - \psi(s))^{\alpha-1} (\psi(s) - \psi(0))^{\gamma-1} e^{\theta(\psi(s)-\psi(0))} \\ & \quad \times \left\{ \max_{0 \leq s \leq d} (\psi(s) - \psi(0))^{1-\gamma} e^{-\theta(\psi(s)-\psi(0))} (|x(s) - y(s)| + |x(g(s)) - y(g(s))|) \right\} ds \\ & \leq \frac{2L_f}{\Gamma(\alpha)} \|x - y\|_B \int_0^\tau \psi'(s) (\psi(\tau) - \psi(s))^{\alpha-1} (\psi(s) - \psi(0))^{\gamma-1} e^{\theta(\psi(s)-\psi(0))} ds \\ & \leq \frac{2L_f}{\Gamma(\alpha)} \|x - y\|_B e^{\theta(\psi(d)-\psi(0))} \int_0^\tau \psi'(s) (\psi(\tau) - \psi(s))^{\alpha-1} (\psi(s) - \psi(0))^{\gamma-1} ds \\ & \leq \frac{2L_f \Gamma(\gamma) e^{\theta(\psi(d)-\psi(0))} (\psi(d) - \psi(0))^{\alpha+\gamma-1}}{\Gamma(\alpha + \gamma)} \|x - y\|_B. \end{aligned}$$

Then

$$\|T_f(x) - T_f(y)\|_B \leq \frac{2L_f \Gamma(\gamma) e^{\theta(\psi(d)-\psi(0))} (\psi(d) - \psi(0))^\alpha}{\Gamma(\alpha + \gamma)} \|x - y\|_B.$$

Thus  $T_f$  is a contraction (via the norm  $\| \cdot \|_B$  on  $X$ ). □

### 4 Examples

In this section, we give two examples illustrating our main results.

*Example 4.1* Consider the fractional-order system

$$\begin{cases} {}^H \mathbb{D}_{0^+}^{\frac{1}{2}, \frac{1}{2}; e^\tau} x(\tau) = \frac{1}{4} \frac{x^2(\tau-1)}{1+x^2(\tau-1)} + \frac{1}{4} \arctan(x(\tau)), & \tau \in (0, 1], \\ I_{0^+}^{1-\gamma; e^\tau} x(0^+) = x_0, \\ x(\tau) = 0, & \tau \in [-h, 0], \end{cases} \tag{12}$$

and the following inequality

$$|{}^H\mathbb{D}_{0^+}^{\frac{1}{2}, \frac{1}{2}; e^\tau} x(\tau) - f(\tau, y(\tau), y(\tau - 1))| \leq \varepsilon E_{\frac{1}{2}}((e^\tau - 1)^{\frac{1}{2}}).$$

Let  $\alpha = \frac{1}{2}$ ,  $\beta = \frac{1}{2}$ . Then  $\gamma = \alpha + \beta(1 - \alpha) = \frac{3}{4}$ ,  $d = 1$ ,  $\psi(\cdot) = e^\cdot$ ,  $g(\cdot) = \cdot - 1$ ,  $f(\cdot, x(\cdot), g(x(\cdot))) = \frac{1}{4} \frac{x^2(\cdot-1)}{1+x^2(\cdot-1)} + \frac{1}{4} \arctan(x(\cdot))$ , and  $L_f = \frac{1}{4}$ . Thus,

$$\frac{2L_f \Gamma(\gamma)(\psi(d) - \psi(0))^\alpha}{\Gamma(\alpha + \gamma)} \approx 0.8861 < 1.$$

Now all the assumptions in Theorem 3.1 are satisfied, so problem (12) has a unique solution, and the first equation in (12) is Ulam–Hyers–Mittag-Leffler stable with

$$|y(\tau) - x(\tau)| \leq c_{\mathbb{E}_{\frac{1}{2}}} \varepsilon \mathbb{E}_{\frac{1}{2}}((e^\tau - 1)^{\frac{1}{2}}), \quad \tau \in [-1, 1],$$

where  $c_{\mathbb{E}_{\frac{1}{2}}} = \mathbb{E}_{\frac{1}{2}}(\frac{\sqrt{e-1}}{2})$ .

**Example 4.2** Consider the fractional-order system

$$\begin{cases} {}^H\mathbb{D}_{0^+}^{\frac{1}{3}, \frac{1}{4}; \tau^2} x(\tau - 2) = \frac{1}{5} \frac{x^2(\tau-2)}{1+x^2(\tau-2)} + \frac{1}{5} \sin(x(\tau - 2)), & \tau \in I = (0, 1], \\ I_{0^+}^{1-\gamma; \tau^2} x(0^+) = x_0, \\ x(\tau) = 0, & \tau \in [-1, 0], \end{cases} \tag{13}$$

and the inequality

$$|{}^H\mathbb{D}_{0^+}^{\frac{1}{3}, \frac{1}{4}; \tau^2} x(\tau) - f(\tau, y(\tau), y(\tau - 1))| \leq \varepsilon \mathbb{E}_{\frac{1}{3}}(\tau^{\frac{2}{3}}).$$

Following Theorem 3.2, let  $\alpha = \frac{1}{3}$  and  $\beta = \frac{1}{4}$ . Then  $\gamma = \alpha + \beta(1 - \alpha) = \frac{1}{2}$ . Let  $d = 1$ ,  $\theta = \frac{1}{3}$ ,  $\psi(\cdot) = \cdot^2$ , and  $L_f = \frac{1}{5}$ . Thus

$$\frac{2L_f \Gamma(\gamma)e^{\theta(\psi(d)-\psi(0))}(\psi(d) - \psi(0))^\alpha}{\Gamma(\alpha + \gamma)} \approx 0.8766 < 1.$$

Now all the assumptions in Theorem 3.2 are satisfied, so (13) has a unique solution, and the first equation in (13) is Ulam–Hyers–Mittag-Leffler stable with

$$|y(\tau) - x(\tau)| \leq c_{\mathbb{E}_{\frac{1}{3}}} \varepsilon \mathbb{E}_{\frac{1}{3}}(\tau^{\frac{2}{3}}), \quad \tau \in [-1, 1],$$

where  $c_{\mathbb{E}_{\frac{1}{3}}} = \mathbb{E}_{\frac{1}{3}}(\frac{2}{5})$ .

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**Competing interests**

The authors declare that they have no competing interests.

### Authors' contributions

All authors read and approved the final manuscript.

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