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# Certain new dynamic nonlinear inequalities in two independent variables and applications

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## Abstract

Several inequalities were proved in 2018 by Boudeliou, in 2015 by Abdeldain and El-Deeb and in 1998 by Pachpatte. It is our aim in this paper to generalize these inequalities to time scales. Beside that, we also apply our inequalities to discrete and continuous calculus to obtain some new inequalities as special cases. Furthermore, we study the boundedness of some problems by applying our results.

**Keywords:** Gronwall-type inequality; Boundedness; Time scales

## 1 Introduction

In 2018, Boudeliou [9] discussed the following inequalities.

**Theorem 1.1** *Suppose  $a \in C(\hat{\Omega}, \mathbb{R}_+)$  is nondecreasing with respect to  $(\check{x}, \check{y}) \in \hat{\Omega} = I_1 \times I_2$ , let  $\hat{\alpha}(\check{x}) \in C^1(I_1, I_2)$  and  $\hat{\beta}(\check{y}) \in C^1(I_2, I_2)$  be nondecreasing functions with  $\hat{\alpha}(\check{x}) \leq \check{x}$  on  $I_1$ ,  $\hat{\beta}(\check{y}) \leq \check{y}$ , and  $g, u, p, f \in C(\hat{\Omega}, \mathbb{R}_+)$ . Furthermore, suppose  $\bar{\psi}, \bar{\varphi} \in C(\mathbb{R}_+, \mathbb{R}_+)$  are nondecreasing functions with  $\{\bar{\psi}, \bar{\varphi}\}(u) > 0$  for  $u > 0$ , and  $\lim_{u \rightarrow +\infty} \bar{\psi}(u) = +\infty$ . If  $u(\check{x}, \check{y})$  satisfies*

$$\begin{aligned} \bar{\psi}(u(\check{x}, \check{y})) \leq & a(\check{x}, \check{y}) + \int_0^{\hat{\alpha}(\check{x})} \int_0^{\hat{\beta}(\check{y})} [f(\check{s}, \check{t})\bar{\varphi}(u(\check{s}, \check{t})) + p(\check{s}, \check{t})] d\check{t} d\check{s} \\ & + \int_0^{\hat{\alpha}(\check{x})} \int_0^{\hat{\beta}(\check{y})} f(\check{s}, \check{t}) \left( \int_0^{\check{s}} g(\check{\tau}, \check{t})\bar{\varphi}(u(\check{\tau}, \check{t})) d\check{\tau} \right) d\check{t} d\check{s}, \end{aligned}$$

for  $(\check{x}, \check{y}) \in \hat{\Omega}$ , then

$$u(\check{x}, \check{y}) \leq \bar{\psi}^{-1} \left\{ \bar{G}^{-1} \left[ \bar{G}(q(\check{x}, \check{y})) + \int_0^{\hat{\alpha}(\check{x})} \int_0^{\hat{\beta}(\check{y})} f(\check{s}, \check{t}) \left( 1 + \int_0^{\check{s}} g(\check{\tau}, \check{t}) d\check{\tau} \right) d\check{t} d\check{s} \right] \right\},$$

for  $0 \leq \check{x} \leq \check{x}_1, 0 \leq \check{y} \leq \check{y}_1$ , where

$$q(\check{x}, \check{y}) = a(\check{x}, \check{y}) + \int_0^{\hat{\alpha}(\check{x})} \int_0^{\hat{\beta}(\check{y})} p(\check{s}, \check{t}) d\check{t} d\check{s},$$

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$$\check{G}(r) = \int_{r_0}^r \frac{d\check{s}}{\bar{\varphi} \circ \bar{\psi}^{-1}(\check{s})}, \quad r \geq r_0 > 0, \quad \check{G}(+\infty) = \int_{r_0}^{+\infty} \frac{d\check{s}}{\bar{\varphi} \circ \bar{\psi}^{-1}(\check{s})} = +\infty,$$

and  $(\check{x}_1, \check{y}_1) \in \hat{\Omega}$  is chosen so that

$$\left( \check{G}(q(\check{x}, \check{y})) + \int_0^{\hat{\alpha}(\check{x})} \int_0^{\hat{\beta}(\check{y})} f(\check{s}, \check{t}) \left( 1 + \int_0^{\check{s}} g(\check{\tau}, \check{t}) d\check{\tau} \right) d\check{t} d\check{s} \right) \in \text{Dom}(G^{-1}).$$

**Theorem 1.2** Assume that  $g, a, f, u, \hat{\beta}, \hat{\alpha}, \bar{\psi}$  and  $\bar{\varphi}$  be as in Theorem 1.1. If  $u(\check{x}, \check{y})$  satisfies

$$\begin{aligned} \bar{\psi}(u(\check{x}, \check{y})) \leq & a(\check{x}, \check{y}) + \left( \int_0^{\hat{\alpha}(\check{x})} \int_0^{\hat{\beta}(\check{y})} f(\check{s}, \check{t}) \bar{\varphi}(u(\check{s}, \check{t})) d\check{t} d\check{s} \right)^2 \\ & + \int_0^{\hat{\alpha}(\check{x})} \int_0^{\hat{\beta}(\check{y})} f(\check{s}, \check{t}) \bar{\varphi}(u(\check{s}, \check{t})) \left( \int_0^{\check{s}} g(\check{\tau}, \check{t}) \bar{\varphi}(u(\check{\tau}, \check{t})) d\check{\tau} \right) d\check{t} d\check{s}, \end{aligned}$$

for  $(\check{x}, \check{y}) \in \hat{\Omega}$ , then

$$u(\check{x}, \check{y}) \leq \bar{\psi}^{-1} \left\{ \check{H}^{-1} \left[ \check{H}(a(\check{x}, \check{y})) + \check{B}(\check{x}, \check{y}) + \left( \int_0^{\hat{\alpha}(\check{x})} \int_0^{\hat{\beta}(\check{y})} f(\check{s}, \check{t}) d\check{t} d\check{s} \right)^2 \right] \right\},$$

for  $0 \leq \check{x} \leq \check{x}_1, 0 \leq \check{y} \leq \check{y}_1$ , where

$$\begin{aligned} \check{B}(\check{x}, \check{y}) &= \int_0^{\hat{\alpha}(\check{x})} \int_0^{\hat{\beta}(\check{y})} f(\check{s}, \check{t}) \left( \int_0^{\check{s}} g(\check{\tau}, \check{t}) d\check{\tau} \right) d\check{t} d\check{s}, \\ \check{H}(r) &= \int_{r_0}^r \frac{d\check{s}}{(\bar{\varphi} \circ \bar{\psi}^{-1})^2(\check{s})}, \quad r \geq r_0 > 0, \quad \check{H}(+\infty) = \int_{r_0}^{+\infty} \frac{d\check{s}}{(\bar{\varphi} \circ \bar{\psi}^{-1})^2(\check{s})} = +\infty, \end{aligned}$$

and  $(\check{x}_1, \check{y}_1) \in \hat{\Omega}$  is chosen so that

$$\left( \check{H}(a(\check{x}, \check{y})) + \check{B}(\check{x}, \check{y}) + \left( \int_0^{\hat{\alpha}(\check{x})} \int_0^{\hat{\beta}(\check{y})} f(\check{s}, \check{t}) d\check{t} d\check{s} \right)^2 \right) \in \text{Dom}(\check{H}^{-1}).$$

In 1988, Hilger [33] presented time scale theory to unify continuous and discrete analysis. For some Gronwall–Bellman-type integral, dynamic inequalities and other type inequalities on time scales, see Refs. [1–8, 13, 14, 16–32, 34–41]. For more details on time scales calculus see [15].

A time scale  $\mathbb{T}$  is an arbitrary nonempty closed subset of  $\mathbb{R}$ . We suppose throughout the article that  $\mathbb{T}$  has the topology that it inherits from the standard topology on  $\mathbb{R}$ . The forward jump operator  $\sigma : \mathbb{T} \rightarrow \mathbb{T}$  is defined for any  $t \in \mathbb{T}$  by

$$\sigma(t) := \inf\{s \in \mathbb{T} : s > t\},$$

and the backward jump operator  $\rho : \mathbb{T} \rightarrow \mathbb{T}$  is defined for any  $t \in \mathbb{T}$  by

$$\rho(t) := \sup\{s \in \mathbb{T} : s < t\}.$$

In the previous two definitions, we set  $\inf \emptyset = \sup \mathbb{T}$  (i.e., if  $t$  is the maximum of  $\mathbb{T}$ , then  $\sigma(t) = t$ ) and  $\sup \emptyset = \inf \mathbb{T}$  (i.e., if  $t$  is the minimum of  $\mathbb{T}$ , then  $\rho(t) = t$ ), where  $\emptyset$  is the empty set.

A point  $t \in \mathbb{T}$  with  $\inf \mathbb{T} < t < \sup \mathbb{T}$  is said to be right-scattered if  $\sigma(t) > t$ , right-dense if  $\sigma(t) = t$ , left-scattered if  $\rho(t) < t$ , and left-dense if  $\rho(t) = t$ . Points that are simultaneously right-dense and left-dense are called dense points. Points that are simultaneously right-scattered and left-scattered are called isolated points.

We define the forward graininess function  $\mu : \mathbb{T} \rightarrow [0, \infty)$  for any  $t \in \mathbb{T}$  by  $\mu(t) := \sigma(t) - t$ .

Let  $f : \mathbb{T} \rightarrow \mathbb{R}$  be a function. Then the function  $f^\sigma : \mathbb{T} \rightarrow \mathbb{R}$  is defined by  $f^\sigma(t) = f(\sigma(t))$ ,  $\forall t \in \mathbb{T}$ , that is,  $f^\sigma = f \circ \sigma$ . In a similar manner, the function  $f^\rho : \mathbb{T} \rightarrow \mathbb{R}$  is defined by  $f^\rho(t) = f(\rho(t))$ ,  $\forall t \in \mathbb{T}$ , that is,  $f^\rho = f \circ \rho$ .

We introduce the set  $\mathbb{T}^\kappa$  as follows: If  $\mathbb{T}$  has a left-scattered maximum  $m$ , then  $\mathbb{T}^\kappa = \mathbb{T} - \{m\}$ , otherwise  $\mathbb{T}^\kappa = \mathbb{T}$ .

The interval  $[a, b]$  in  $\mathbb{T}$  is defined by

$$[a, b]_{\mathbb{T}} = \{t \in \mathbb{T} : a \leq t \leq b\}.$$

Open intervals and half-closed interval are defined similarly.

Suppose  $f : \mathbb{T} \rightarrow \mathbb{R}$  is a function and  $t \in \mathbb{T}^\kappa$ . Then we say that  $f^\Delta(t) \in \mathbb{R}$  is the delta derivative of  $f$  at  $t$  if for any  $\varepsilon > 0$  there exists a neighborhood  $U$  of  $t$  such that, for all  $s \in U$ , we have

$$|[f(\sigma(t)) - f(s)] - f^\Delta(t)[\sigma(t) - s]| \leq \varepsilon |\sigma(t) - s|.$$

Furthermore,  $f$  is said to be delta differentiable on  $\mathbb{T}^\kappa$  if it is delta differentiable at each  $t \in \mathbb{T}^\kappa$ .

If  $f, g : \mathbb{T} \rightarrow \mathbb{R}$  are delta differentiable functions at  $t \in \mathbb{T}^\kappa$ , then

1.  $(f + g)^\Delta(t) = f^\Delta(t) + g^\Delta(t)$ ;
2.  $(fg)^\Delta(t) = f^\Delta(t)g(t) + f(\sigma(t))g^\Delta(t) = f(t)g^\Delta(t) + f^\Delta(t)g(\sigma(t))$ ;
3.  $(\frac{f}{g})^\Delta(t) = \frac{f^\Delta(t)g(t) - f(t)g^\Delta(t)}{g(t)g(\sigma(t))}$  provided  $g(t)g(\sigma(t)) \neq 0$ .

A function  $g : \mathbb{T} \rightarrow \mathbb{R}$  is called right-dense continuous (rd-continuous) if  $g$  is continuous at the right-dense points in  $\mathbb{T}$  and its left-sided limits exist at all left-dense points in  $\mathbb{T}$ .

A function  $F : \mathbb{T} \rightarrow \mathbb{R}$  is said to be a delta antiderivative of  $f : \mathbb{T} \rightarrow \mathbb{R}$  if  $F^\Delta(t) = f(t)$  for all  $t \in \mathbb{T}^\kappa$ . In this case, the definite delta integral of  $f$  is defined by

$$\int_a^b f(\eta) \Delta \eta = F(b) - F(a) \quad \text{for all } a, b \in \mathbb{T}.$$

If  $g \in C_{rd}(\mathbb{T})$  and  $t, t_0 \in \mathbb{T}$ , then the definite integral  $G(t) := \int_{t_0}^t g(s) \Delta s$  exists, and  $G^\Delta(t) = g(t)$  holds.

Assume that  $a, b, c \in \mathbb{T}$ ,  $\alpha \in \mathbb{R}$ , and  $f, g$  be continuous functions on  $[a, b]_{\mathbb{T}}$ . Then

1.  $\int_a^b [f(t) + g(t)] \Delta \eta = \int_a^b f(\eta) \Delta \eta + \int_a^b g(\eta) \Delta \eta$ ;
2.  $\int_a^b \alpha f(\eta) \Delta \eta = \alpha \int_a^b f(\eta) \Delta \eta$ ;
3.  $\int_a^b f(\eta) \Delta \eta = \int_a^c f(\eta) \Delta \eta + \int_c^b f(\eta) \Delta \eta$ ;
4.  $\int_a^b f(\eta) \Delta \eta = - \int_b^a f(\eta) \Delta \eta$ ;
5.  $\int_a^a f(\eta) \Delta \eta = 0$ ;
6. if  $f(t) \geq g(t)$  on  $[a, b]_{\mathbb{T}}$ , then  $\int_a^b f(\eta) \Delta \eta \geq \int_a^b g(\eta) \Delta \eta$ .

We will need the following important relations between calculus on time scales  $\mathbb{T}$  and either continuous calculus on  $\mathbb{R}$  or discrete calculus on  $\mathbb{Z}$ . Note that:

1. If  $\mathbb{T} = \mathbb{R}$ , then

$$\sigma(t) = t, \quad \mu(t) = 0, \quad f^\Delta(t) = f'(t), \quad \int_a^b f(\eta) \Delta\eta = \int_a^b f(t) dt.$$

2. If  $\mathbb{T} = \mathbb{Z}$ , then

$$\sigma(t) = t + 1, \quad \mu(t) = 1, \quad f^\Delta(t) = f(t + 1) - f(t), \quad \int_a^b f(\eta) \Delta\eta = \sum_{t=a}^{b-1} f(t).$$

In the following, we present the basic theorems that will be needed in the proofs of our main results.

**Theorem 1.3** *If  $\hat{f}$  is  $\hat{\Delta}$ -integrable on  $[a, b]$ , then so is  $|\hat{f}|$ , and*

$$\left| \int_a^b \hat{f}(\check{t}) \hat{\Delta}\check{t} \right| \leq \int_a^b |\hat{f}(\check{t})| \hat{\Delta}\check{t}.$$

**Theorem 1.4** (Chain rule on time scales [15]) *Assume  $\hat{g} : \mathbb{R} \rightarrow \mathbb{R}$  is continuous,  $\check{g} : \check{\mathbb{T}} \rightarrow \mathbb{R}$  is  $\hat{\Delta}$ -differentiable on  $\mathbb{T}^*$ , and  $\hat{f} : \mathbb{R} \rightarrow \mathbb{R}$  is continuously differentiable. Then there exists  $c \in [\check{t}, \sigma(\check{t})]$  with*

$$(\hat{f} \circ \hat{g})^{\hat{\Delta}}(\check{t}) = \hat{f}'(\hat{g}(c)) \hat{g}^{\hat{\Delta}}(\check{t}). \tag{1.1}$$

**Theorem 1.5** (Chain rule on time scales [15]) *Let  $\hat{f} : \mathbb{R} \rightarrow \mathbb{R}$  be continuously differentiable and suppose  $\hat{g} : \check{\mathbb{T}} \rightarrow \mathbb{R}$  is  $\hat{\Delta}$ -differentiable. Then  $\hat{f} \circ \hat{g} : \check{\mathbb{T}} \rightarrow \mathbb{R}$  is  $\hat{\Delta}$ -differentiable and the formula*

$$(\hat{f} \circ \hat{g})^{\hat{\Delta}}(\check{t}) = \left\{ \int_0^1 [\hat{f}'(h\hat{g}^\sigma(\check{t}) + (1-h)\hat{g}(\check{t}))] dh \right\} \hat{g}^{\hat{\Delta}}(\check{t}) \tag{1.2}$$

holds.

This paper gives us the time scale versions of the results provided in [9]. These inequalities, proved here, extend some known results in the literature, and they are also unify the continuous and the discrete case.

## 2 Main results

In what follows,  $\mathbb{R}$  denotes the set of real numbers,  $\mathbb{R}_+ = [0, +\infty)$ ,  $\check{\mathbb{T}}_1, \check{\mathbb{T}}_2$  are two time scales and we put  $\Omega = \check{\mathbb{T}}_1 \times \check{\mathbb{T}}_2 = \{(\check{t}, \check{s}) : \check{t} \in \check{\mathbb{T}}_1, \check{s} \in \check{\mathbb{T}}_2\}$  which is a complete metric space with the metric  $\check{\rho}$  defined by

$$\check{\rho}((\check{t}, \check{s}), (\check{t}, \check{s})) = \sqrt{(\check{t} - \check{t})^2 + (\check{s} - \check{s})^2}, \quad \forall (\check{t}, \check{s}), (\check{t}, \check{s}) \in \check{\mathbb{T}}_1 \times \check{\mathbb{T}}_2.$$

$C_{rd}(\Omega, \mathbb{R}_+)$  denotes the set of all right-dense continuous functions from  $\Omega$  into  $\mathbb{R}_+$  and  $C_{rd}^1(\check{\mathbb{T}}_i, \check{\mathbb{T}}_i)$  denotes the set of all right-dense continuously delta-differentiable functions from  $\check{\mathbb{T}}_i$  into  $\check{\mathbb{T}}_i$ ,  $i = 1, 2$ . The two-variables time scales calculus and multiple integration on time scales were introduced in [10, 11] (see also [12]).

**Theorem 2.1** *Suppose that  $a \in C_{rd}(\Omega, \mathbb{R}_+)$  is nondecreasing with respect to  $(\check{x}, \check{y}) \in \Omega$ , and  $g, u, p, f \in C_{rd}(\Omega, \mathbb{R}_+)$ . Furthermore, suppose that  $\bar{\psi}, \bar{\varphi} \in C(\mathbb{R}_+, \mathbb{R}_+)$  are nondecreasing functions with  $\{\bar{\psi}, \bar{\varphi}\}(u) > 0$  for  $u > 0$ , and  $\lim_{u \rightarrow +\infty} \bar{\psi}(u) = +\infty$ . If  $u(\check{x}, \check{y})$  satisfies*

$$\begin{aligned} \bar{\psi}(u(\check{x}, \check{y})) &\leq a(\check{x}, \check{y}) + \int_0^{\check{x}} \int_0^{\check{y}} [f(\check{s}, \check{t})\bar{\varphi}(u(\check{s}, \check{t})) + p(\check{s}, \check{t})] \hat{\Delta} \check{t} \hat{\Delta} \check{s} \\ &\quad + \int_0^{\check{x}} \int_0^{\check{y}} f(\check{s}, \check{t}) \left( \int_0^{\check{s}} g(\check{\tau}, \check{t})\bar{\varphi}(u(\check{\tau}, \check{t})) \hat{\Delta} \check{\tau} \right) \hat{\Delta} \check{t} \hat{\Delta} \check{s}, \end{aligned}$$

for  $(\check{x}, \check{y}) \in \Omega$ , then

$$u(\check{x}, \check{y}) \leq \bar{\psi}^{-1} \left\{ \check{G}^{-1} \left[ \check{G}(q(\check{x}, \check{y})) + \int_0^{\check{x}} \int_0^{\check{y}} f(\check{s}, \check{t}) \left( 1 + \int_0^{\check{s}} g(\check{\tau}, \check{t}) \hat{\Delta} \check{\tau} \right) \hat{\Delta} \check{t} \hat{\Delta} \check{s} \right] \right\} \tag{2.1}$$

for  $0 \leq \check{x} \leq \check{x}_1, 0 \leq \check{y} \leq \check{y}_1$ , where

$$q(\check{x}, \check{y}) = a(\check{x}, \check{y}) + \int_0^{\check{x}} \int_0^{\check{y}} p(\check{s}, \check{t}) \hat{\Delta} \check{t} \hat{\Delta} \check{s}, \tag{2.2}$$

$$\check{G}(r) = \int_{r_0}^r \frac{\hat{\Delta} \check{s}}{\bar{\varphi} \circ \bar{\psi}^{-1}(\check{s})}, \quad r \geq r_0 > 0, \quad \check{G}(+\infty) = \int_{r_0}^{+\infty} \frac{\hat{\Delta} \check{s}}{\bar{\varphi} \circ \bar{\psi}^{-1}(\check{s})} = +\infty, \tag{2.3}$$

and  $(\check{x}_1, \check{y}_1) \in \Omega$  is chosen so that

$$\left( \check{G}(q(\check{x}, \check{y})) + \int_0^{\check{x}} \int_0^{\check{y}} f(\check{s}, \check{t}) \left( 1 + \int_0^{\check{s}} g(\check{\tau}, \check{t}) \hat{\Delta} \check{\tau} \right) \hat{\Delta} \check{t} \hat{\Delta} \check{s} \right) \in \text{Dom}(\check{G}^{-1}).$$

*Proof* Assume that  $a(\check{x}, \check{y}) > 0$ . Since  $q \geq 0$  and it is nondecreasing, fixing an arbitrary point  $(\check{\xi}, \check{\zeta}) \in \Omega$  and defining  $z(\check{x}, \check{y})$  by

$$\begin{aligned} z(\check{x}, \check{y}) &= q(\check{\xi}, \check{\zeta}) + \int_0^{\check{x}} \int_0^{\check{y}} f(\check{s}, \check{t})\bar{\varphi}(u(\check{s}, \check{t})) \hat{\Delta} \check{t} \hat{\Delta} \check{s} \\ &\quad + \int_0^{\check{x}} \int_0^{\check{y}} f(\check{s}, \check{t}) \left( \int_0^{\check{s}} g(\check{\tau}, \check{t})\bar{\varphi}(u(\check{\tau}, \check{t})) \hat{\Delta} \check{\tau} \right) \hat{\Delta} \check{t} \hat{\Delta} \check{s}, \end{aligned}$$

which is a positive and nondecreasing function for  $0 \leq \check{x} \leq \check{\xi} \leq \check{x}_1, 0 \leq \check{y} \leq \check{\zeta} \leq \check{y}_1$ , we have  $z(0, \check{y}) = z(\check{x}, 0) = q(\check{\xi}, \check{\zeta})$  and

$$u(\check{x}, \check{y}) \leq \bar{\psi}^{-1}(z(\check{x}, \check{y})). \tag{2.4}$$

Differentiating  $z(\check{x}, \check{y})$ , with respect to  $\check{x}$  and using (2.4), we get

$$\begin{aligned} z^{\hat{\Delta} \check{x}}(\check{x}, \check{y}) &= \int_0^{\check{y}} f(\check{x}, \check{t}) \left[ \bar{\varphi}(u(\check{x}, \check{t})) + \int_0^{\check{x}} g(\check{\tau}, \check{t})\bar{\varphi}(u(\check{\tau}, \check{t})) \hat{\Delta} \check{\tau} \right] \hat{\Delta} \check{t} \\ &\leq \int_0^{\check{y}} f(\check{x}, \check{t}) \left[ \bar{\varphi} \circ \bar{\psi}^{-1}(z(\check{x}, \check{t})) + \int_0^{\check{x}} g(\check{\tau}, \check{t})\bar{\varphi} \circ \bar{\psi}^{-1}(z(\check{\tau}, \check{t})) \hat{\Delta} \check{\tau} \right] \hat{\Delta} \check{t}, \end{aligned}$$

since  $\bar{\varphi} \circ \bar{\psi}^{-1}$  is nondecreasing with respect to  $(\check{x}, \check{y}) \in \mathbb{R}_+ \times \mathbb{R}_+$ , we have

$$\begin{aligned} z^{\hat{\Delta}\check{x}}(\check{x}, \check{y}) &\leq \int_0^{\check{y}} f(\check{x}, \check{t}) \left[ \bar{\varphi} \circ \bar{\psi}^{-1}(z(\check{x}, \check{t})) + \bar{\varphi} \circ \bar{\psi}^{-1}(z(\check{x}, \check{t})) \int_0^{\check{x}} g(\check{\tau}, \check{t}) \hat{\Delta}\check{\tau} \right] \hat{\Delta}\check{t} \\ &\leq \bar{\varphi} \circ \bar{\psi}^{-1}(z(\check{x}, \check{y})) \int_0^{\check{y}} f(\check{x}, \check{t}) \left[ 1 + \int_0^{\check{x}} g(\check{\tau}, \check{t}) \hat{\Delta}\check{\tau} \right] \hat{\Delta}\check{t}, \end{aligned} \tag{2.5}$$

and from (2.5) we get

$$\frac{z^{\hat{\Delta}\check{x}}(\check{x}, \check{y})}{\bar{\varphi} \circ \bar{\psi}^{-1}(z(\check{x}, \check{y}))} \leq \int_0^{\check{y}} f(\check{x}, \check{t}) \left( 1 + \int_0^{\check{x}} g(\check{\tau}, \check{t}) \hat{\Delta}\check{\tau} \right) \hat{\Delta}\check{t}. \tag{2.6}$$

From (2.6) we get

$$\check{G}(z(\check{x}, \check{y})) \leq \check{G}(q(\check{\xi}, \check{\zeta})) + \int_0^{\check{x}} \int_0^{\check{y}} f(\check{s}, \check{t}) \left( 1 + \int_0^{\check{s}} g(\check{\tau}, \check{t}) \hat{\Delta}\check{\tau} \right) \hat{\Delta}\check{t} \hat{\Delta}\check{s}.$$

Since  $(\check{\xi}, \check{\zeta}) \in \Omega$  is chosen arbitrarily,

$$z(\check{x}, \check{y}) \leq \check{G}^{-1} \left[ \check{G}(q(\check{x}, \check{y})) + \int_0^{\check{x}} \int_0^{\check{y}} f(\check{s}, \check{t}) \left( 1 + \int_0^{\check{s}} g(\check{\tau}, \check{t}) \hat{\Delta}\check{\tau} \right) \hat{\Delta}\check{t} \hat{\Delta}\check{s} \right]. \tag{2.7}$$

So from (2.7) and (2.4) we get the desired inequality in (2.1). For  $a(\check{x}, \check{y}) = 0$ , we carry out the above procedure with  $\epsilon > 0$  instead of  $a(\check{x}, \check{y})$  and subsequently let  $\epsilon \rightarrow 0$ . This completes the proof.  $\square$

**Corollary 2.2** *If we take  $\check{\mathbb{T}} = \mathbb{R}$  in Theorem 2.1, then the inequality*

$$\begin{aligned} \bar{\psi}(u(\check{x}, \check{y})) &\leq a(\check{x}, \check{y}) + \int_0^{\check{x}} \int_0^{\check{y}} [f(\check{s}, \check{t}) \bar{\varphi}(u(\check{s}, \check{t})) + p(\check{s}, \check{t})] d\check{t} d\check{s} \\ &\quad + \int_0^{\check{x}} \int_0^{\check{y}} f(\check{s}, \check{t}) \left( \int_0^{\check{s}} g(\check{\tau}, \check{t}) \bar{\varphi}(u(\check{\tau}, \check{t})) d\check{\tau} \right) d\check{t} d\check{s}, \end{aligned}$$

for  $(\check{x}, \check{y}) \in \Omega$ , implies

$$u(\check{x}, \check{y}) \leq \bar{\psi}^{-1} \left\{ \check{G}^{-1} \left[ \check{G}(q(\check{x}, \check{y})) + \int_0^{\check{x}} \int_0^{\check{y}} f(\check{s}, \check{t}) \left( 1 + \int_0^{\check{s}} g(\check{\tau}, \check{t}) d\check{\tau} \right) d\check{t} d\check{s} \right] \right\}$$

for  $0 \leq \check{x} \leq \check{x}_1, 0 \leq \check{y} \leq \check{y}_1$ , where

$$\begin{aligned} q(\check{x}, \check{y}) &= a(\check{x}, \check{y}) + \int_0^{\check{x}} \int_0^{\check{y}} p(\check{s}, \check{t}) d\check{t} d\check{s}, \\ \check{G}(r) &= \int_{r_0}^r \frac{d\check{s}}{\bar{\varphi} \circ \bar{\psi}^{-1}(\check{s})}, \quad r \geq r_0 > 0, \quad \check{G}(+\infty) = \int_{r_0}^{+\infty} \frac{d\check{s}}{\bar{\varphi} \circ \bar{\psi}^{-1}(\check{s})} = +\infty, \end{aligned} \tag{2.8}$$

and  $(\check{x}_1, \check{y}_1) \in \Omega$  is chosen so that

$$\left( \check{G}(q(\check{x}, \check{y})) + \int_0^{\check{x}} \int_0^{\check{y}} f(\check{s}, \check{t}) \left( 1 + \int_0^{\check{s}} g(\check{\tau}, \check{t}) d\check{\tau} \right) d\check{t} d\check{s} \right) \in \text{Dom}(\check{G}^{-1}).$$

**Corollary 2.3** *The discrete form can be obtained by letting  $\mathbb{T} = \mathbb{Z}$  in Theorem 2.1:*

$$\begin{aligned} \bar{\psi}(u(\check{x}, \check{y})) &\leq a(\check{x}, \check{y}) + \sum_{\check{s}=0}^{\check{x}-1} \sum_{\check{t}=0}^{\check{y}-1} [f(\check{s}, \check{t})\bar{\varphi}(u(\check{s}, \check{t})) + p(\check{s}, \check{t})] \\ &\quad + \sum_{\check{s}=0}^{\check{x}-1} \sum_{\check{t}=0}^{\check{y}-1} f(\check{s}, \check{t}) \left( \sum_{\check{\tau}=0}^{\check{s}-1} g(\check{\tau}, \check{t})\bar{\varphi}(u(\check{\tau}, \check{t})) \right) \end{aligned}$$

for  $(\check{x}, \check{y}) \in \Omega$ , which implies

$$u(\check{x}, \check{y}) \leq \bar{\psi}^{-1} \left\{ \check{G}^{-1} \left[ \check{G}(q(\check{x}, \check{y})) + \sum_{\check{s}=0}^{\check{x}-1} \sum_{\check{t}=0}^{\check{y}-1} f(\check{s}, \check{t}) \left( 1 + \sum_{\check{\tau}=0}^{\check{s}-1} g(\check{\tau}, \check{t}) \right) \right] \right\}$$

for  $0 \leq \check{x} \leq \check{x}_1, 0 \leq \check{y} \leq \check{y}_1$ , where

$$\begin{aligned} q(\check{x}, \check{y}) &= a(\check{x}, \check{y}) + \sum_{\check{s}=0}^{\check{x}-1} \sum_{\check{t}=0}^{\check{y}-1} p(\check{s}, \check{t}), \\ \check{G}(r) &= \sum_{\check{s}=r_0}^{r-1} \frac{1}{\bar{\varphi} \circ \bar{\psi}^{-1}(\check{s})}, \quad r \geq r_0 > 0, \quad \check{G}(+\infty) = \sum_{\check{s}=r_0}^{+\infty} \frac{1}{\bar{\varphi} \circ \bar{\psi}^{-1}(\check{s})} = +\infty, \end{aligned} \tag{2.9}$$

and  $(\check{x}_1, \check{y}_1) \in \Omega$  is chosen so that

$$\left( \check{G}(q(\check{x}, \check{y})) + \sum_{\check{s}=0}^{\check{x}-1} \sum_{\check{t}=0}^{\check{y}-1} f(\check{s}, \check{t}) \left( 1 + \sum_{\check{\tau}_0}^{\check{s}} g(\check{\tau}, \check{t}) \right) \right) \in \text{Dom}(\check{G}^{-1}).$$

**Theorem 2.4** *Assume that  $h, b \in C_{rd}(\Omega, \mathbb{R}_+)$ . Let  $g, f, p, a, u, \bar{\psi}$  and  $\bar{\varphi}$  be as in Theorem 2.1, if  $u(\check{x}, \check{y})$  satisfies*

$$\begin{aligned} \bar{\psi}(u(\check{x}, \check{y})) &\leq a(\check{x}, \check{y}) + \int_0^{\check{x}} \int_0^{\check{y}} [f(\check{s}, \check{t})\bar{\varphi}(u(\check{s}, \check{t})) + p(\check{s}, \check{t})] \hat{\Delta}\check{t}\hat{\Delta}\check{s} \\ &\quad + \int_0^{\check{x}} \int_0^{\check{y}} b(\check{s}, \check{t}) \left[ h(\check{s}, \check{t})\bar{\varphi}(u(\check{s}, \check{t})) + \int_0^{\check{s}} g(\check{\tau}, \check{t})\bar{\varphi}(u(\check{\tau}, \check{t})) \hat{\Delta}\check{\tau} \right] \hat{\Delta}\check{t}\hat{\Delta}\check{s} \end{aligned}$$

for  $(\check{x}, \check{y}) \in \Omega$ , then

$$u(\check{x}, \check{y}) \leq \bar{\psi}^{-1} \left\{ \check{G}^{-1} \left[ \check{G}(q(\check{x}, \check{y})) + A(\check{x}, \check{y}) + \int_0^{\check{x}} \int_0^{\check{y}} f(\check{s}, \check{t}) \hat{\Delta}\check{t}\hat{\Delta}\check{s} \right] \right\} \tag{2.10}$$

for  $0 \leq \check{x} \leq \check{x}_1, 0 \leq \check{y} \leq \check{y}_1$ , where  $q, \check{G}$  are defined by (2.2) and (2.3), respectively, and

$$\check{A}(\check{x}, \check{y}) = \int_0^{\check{x}} \int_0^{\check{y}} b(\check{s}, \check{t}) \left[ h(\check{s}, \check{t}) + \int_0^{\check{s}} g(\check{\tau}, \check{t}) \hat{\Delta}\check{\tau} \right] \hat{\Delta}\check{t}\hat{\Delta}\check{s} \tag{2.11}$$

and  $(\check{x}_1, \check{y}_1) \in \Omega$  is chosen so that

$$\left( \check{G}(q(\check{x}, \check{y})) + \check{A}(\check{x}, \check{y}) + \int_0^{\check{x}} \int_0^{\check{y}} f(\check{s}, \check{t}) \hat{\Delta}\check{t}\hat{\Delta}\check{s} \right) \in \text{Dom}(\check{G}^{-1}).$$

*Proof* Assume that  $a(\check{x}, \check{y}) > 0$ . Fixing an arbitrary  $(\check{\xi}, \check{\zeta}) \in \Omega$ , we define positive and non-decreasing function  $z(\check{x}, \check{y})$  by

$$z(\check{x}, \check{y}) = q(\check{\xi}, \check{\zeta}) + \int_0^{\check{x}} \int_0^{\check{y}} f(\check{s}, \check{t}) \bar{\varphi}(u(\check{s}, \check{t})) \hat{\Delta} \check{t} \hat{\Delta} \check{s} + \int_0^{\check{x}} \int_0^{\check{y}} b(\check{s}, \check{t}) \left[ h(\check{s}, \check{t}) \bar{\varphi}(u(\check{s}, \check{t})) + \int_0^{\check{s}} g(\check{\tau}, \check{t}) \bar{\varphi}(u(\check{\tau}, \check{t})) \hat{\Delta} \check{\tau} \right] \hat{\Delta} \check{t} \hat{\Delta} \check{s}$$

for  $0 \leq \check{x} \leq \check{\xi} \leq \check{x}_1, 0 \leq \check{y} \leq \check{\zeta} \leq y_1$ , then  $z(0, \check{y}) = z(\check{x}, 0) = q(\check{\xi}, \check{\zeta})$  and

$$u(\check{x}, \check{y}) \leq \bar{\psi}^{-1}(z(\check{x}, \check{y}));$$

then we have

$$\begin{aligned} z^{\hat{\Delta} \check{x}}(\check{x}, \check{y}) &= \int_0^{\check{y}} f(\check{x}, \check{t}) \bar{\varphi}(u(\check{x}, \check{t})) \hat{\Delta} \check{t} + \int_0^{\check{y}} b(\check{x}, \check{t}) \left( h(\check{x}, \check{t}) \bar{\varphi}(u(\check{x}, \check{t})) + \int_0^{\check{x}} g(\check{\tau}, \check{t}) \bar{\varphi}(u(\check{\tau}, \check{t})) \hat{\Delta} \check{\tau} \right) \hat{\Delta} \check{t} \\ &\leq \int_0^{\check{y}} f(\check{x}, \check{t}) \bar{\varphi} \circ \bar{\psi}^{-1}(z(\check{x}, \check{t})) \hat{\Delta} \check{t} + \int_0^{\check{y}} b(\check{x}, \check{t}) \\ &\quad \times \left( h(\check{x}, \check{t}) \bar{\varphi} \circ \bar{\psi}^{-1}(z(\check{x}, \check{t})) + \int_0^{\check{x}} g(\check{\tau}, \check{t}) \bar{\varphi} \circ \bar{\psi}^{-1}(z(\check{\tau}, \check{t})) \hat{\Delta} \check{\tau} \right) \hat{\Delta} \check{t} \\ &\leq \bar{\varphi} \circ \bar{\psi}^{-1}(z(\check{x}, \check{y})) \left[ \int_0^{\check{y}} f(\check{x}, \check{t}) \hat{\Delta} \check{t} + \int_0^{\check{y}} b(\check{x}, \check{t}) \left( h(\check{x}, \check{t}) + \int_0^{\check{x}} g(\check{\tau}, \check{t}) \hat{\Delta} \check{\tau} \right) \right] \hat{\Delta} \check{t}, \end{aligned}$$

then

$$\frac{z^{\hat{\Delta} \check{x}}(\check{x}, \check{y})}{\bar{\varphi} \circ \bar{\psi}^{-1}(z(\check{x}, \check{y}))} \leq \left[ \int_0^{\check{y}} f(\check{x}, \check{t}) \hat{\Delta} \check{t} + \int_0^{\check{y}} b(\check{x}, \check{t}) \left( h(\check{x}, \check{t}) + \int_0^{\check{x}} g(\check{\tau}, \check{t}) \hat{\Delta} \check{\tau} \right) \right] \hat{\Delta} \check{t}. \tag{2.12}$$

Integrating (2.12) and using (2.3) and (2.11), we get

$$\check{G}(z(\check{x}, \check{y})) \leq \check{G}(q(\check{\xi}, \check{\zeta})) + \check{A}(\check{x}, \check{y}) + \int_0^{\check{x}} \int_0^{\check{y}} f(\check{s}, \check{t}) \hat{\Delta} \check{t} \hat{\Delta} \check{s}.$$

Since  $(\check{\xi}, \check{\zeta}) \in \Omega$  is chosen arbitrarily,

$$z(\check{x}, \check{y}) \leq \check{G}^{-1} \left[ \check{G}(q(\check{x}, \check{y})) + \check{A}(\check{x}, \check{y}) + \int_0^{\check{x}} \int_0^{\check{y}} f(\check{s}, \check{t}) \hat{\Delta} \check{t} \hat{\Delta} \check{s} \right]. \tag{2.13}$$

From (2.13) and  $u(\check{x}, \check{y}) \leq \bar{\psi}^{-1}(z(\check{x}, \check{y}))$ , we get the required inequality in (2.10). For  $a(\check{x}, \check{y}) = 0$ , we carry out the above procedure with  $\epsilon > 0$  instead of  $a(\check{x}, \check{y})$  and subsequently let  $\epsilon \rightarrow 0$ . This completes the proof.  $\square$



**Corollary 2.5** *If we take  $\check{\mathbb{T}} = \mathbb{R}$  in Theorem 2.4, then the inequality*

$$\begin{aligned} \bar{\psi}(u(\check{x}, \check{y})) &\leq a(\check{x}, \check{y}) + \int_0^{\check{x}} \int_0^{\check{y}} [f(\check{s}, \check{t})\bar{\varphi}(u(\check{s}, \check{t})) + p(\check{s}, \check{t})] d\check{t} d\check{s} \\ &\quad + \int_0^{\check{x}} \int_0^{\check{y}} b(\check{s}, \check{t}) \left[ h(\check{s}, \check{t})\bar{\varphi}(u(\check{s}, \check{t})) + \int_0^{\check{s}} g(\check{\tau}, \check{t})\bar{\varphi}(u(\check{\tau}, \check{t})) d\check{\tau} \right] d\check{t} d\check{s}, \end{aligned}$$

for  $(\check{x}, \check{y}) \in \Omega$ , implies

$$u(\check{x}, \check{y}) \leq \bar{\psi}^{-1} \left\{ \check{G}^{-1} \left[ \check{G}(q(\check{x}, \check{y})) + A(\check{x}, \check{y}) + \int_0^{\check{x}} \int_0^{\check{y}} f(\check{s}, \check{t}) d\check{t} d\check{s} \right] \right\}$$

for  $0 \leq \check{x} \leq \check{x}_1, 0 \leq \check{y} \leq \check{y}_1$ , where  $\check{G}$  is defined by (2.8) and

$$\check{A}(\check{x}, \check{y}) = \int_0^{\check{x}} \int_0^{\check{y}} b(\check{s}, \check{t}) \left[ h(\check{s}, \check{t}) + \int_0^{\check{s}} g(\check{\tau}, \check{t}) d\check{\tau} \right] d\check{t} d\check{s}$$

and  $(\check{x}_1, \check{y}_1) \in \Omega$  is chosen so that

$$\left( \check{G}(q(\check{x}, \check{y})) + \check{A}(\check{x}, \check{y}) + \int_0^{\check{x}} \int_0^{\check{y}} f(\check{s}, \check{t}) d\check{t} d\check{s} \right) \in \text{Dom}(\check{G}^{-1}).$$

**Corollary 2.6** *The discrete form can be obtained by letting  $\check{\mathbb{T}} = \mathbb{Z}$  in Theorem 2.4:*

$$\begin{aligned} \bar{\psi}(u(\check{x}, \check{y})) &\leq a(\check{x}, \check{y}) + \sum_{\check{s}=0}^{\check{x}-1} \sum_{\check{t}=0}^{\check{y}-1} [f(\check{s}, \check{t})\bar{\varphi}(u(\check{s}, \check{t})) + p(\check{s}, \check{t})] \\ &\quad + \sum_{\check{s}=0}^{\check{x}-1} \sum_{\check{t}=0}^{\check{y}-1} b(\check{s}, \check{t}) \left[ h(\check{s}, \check{t})\bar{\varphi}(u(\check{s}, \check{t})) + \sum_{\check{\tau}=0}^{\check{s}-1} g(\check{\tau}, \check{t})\bar{\varphi}(u(\check{\tau}, \check{t})) \right], \end{aligned}$$

for  $(\check{x}, \check{y}) \in \Omega$ , implies

$$u(\check{x}, \check{y}) \leq \bar{\psi}^{-1} \left\{ \check{G}^{-1} \left[ \check{G}(q(\check{x}, \check{y})) + A(\check{x}, \check{y}) + \sum_{\check{s}=0}^{\check{x}-1} \sum_{\check{t}=0}^{\check{y}-1} f(\check{s}, \check{t}) \right] \right\}$$

for  $0 \leq \check{x} \leq \check{x}_1, 0 \leq \check{y} \leq \check{y}_1$ , where  $\check{G}$  is defined by (2.9) and

$$\check{A}(\check{x}, \check{y}) = \sum_{\check{s}=0}^{\check{x}-1} \sum_{\check{t}=0}^{\check{y}-1} b(\check{s}, \check{t}) \left[ h(\check{s}, \check{t}) + \sum_{\check{\tau}=0}^{\check{s}-1} g(\check{\tau}, \check{t}) \right]$$

and  $(\check{x}_1, \check{y}_1) \in \Omega$  is chosen so that

$$\left( \check{G}(q(\check{x}, \check{y})) + \check{A}(\check{x}, \check{y}) + \sum_{\check{s}=0}^{\check{x}-1} \sum_{\check{t}=0}^{\check{y}-1} f(\check{s}, \check{t}) \right) \in \text{Dom}(\check{G}^{-1}).$$

**Theorem 2.7** Assume that  $g, a, u, f, p, \bar{\psi}$  and  $\bar{\varphi}$  are as in Theorem 2.1. If  $u(\check{x}, \check{y})$  satisfies

$$\begin{aligned} \bar{\psi}(u(\check{x}, \check{y})) &\leq a(\check{x}, \check{y}) + \int_0^{\check{x}} \int_0^{\check{y}} \bar{\varphi}(u(\check{s}, \check{t})) [f(\check{s}, \check{t}) \bar{\varphi}(u(\check{s}, \check{t})) + p(\check{s}, \check{t})] \hat{\Delta} \check{t} \hat{\Delta} \check{s} \\ &\quad + \int_0^{\check{x}} \int_0^{\check{y}} f(\check{s}, \check{t}) \bar{\varphi}(u(\check{s}, \check{t})) \left( \int_0^{\check{s}} g(\check{\tau}, \check{t}) \bar{\varphi}(u(\check{\tau}, \check{t})) \hat{\Delta} \check{\tau} \right) \hat{\Delta} \check{t} \hat{\Delta} \check{s}, \end{aligned}$$

for  $(\check{x}, \check{y}) \in \Omega$ , then

$$\begin{aligned} u(\check{x}, \check{y}) &\leq \bar{\psi}^{-1} \left\{ \check{G}^{-1} \left( \check{F}^{-1} \left[ \check{F}(q_1(\check{x}, \check{y})) \right. \right. \right. \\ &\quad \left. \left. \left. + \int_0^{\check{x}} \int_0^{\check{y}} f(\check{s}, \check{t}) \left( 1 + \int_0^{\check{s}} g(\check{\tau}, \check{t}) \hat{\Delta} \check{\tau} \right) \hat{\Delta} \check{t} \hat{\Delta} \check{s} \right] \right) \right\}, \end{aligned} \tag{2.14}$$

for  $0 \leq \check{x} \leq \check{x}_1, 0 \leq \check{y} \leq \check{y}_1$ , where  $\check{G}$  is defined in (2.3) and

$$q_1(\check{x}, \check{y}) = \check{G}(a(\check{x}, \check{y})) + \int_0^{\check{x}} \int_0^{\check{y}} p(\check{s}, \check{t}) \hat{\Delta} \check{t} \hat{\Delta} \check{s}, \tag{2.15}$$

$$\check{F}(r) = \int_{r_0}^r \frac{\hat{\Delta} \check{s}}{((\bar{\varphi} \circ \bar{\psi}^{-1}) \circ \check{G}^{-1})(\check{s})}, \quad r \geq r_0 > 0, \tag{2.16}$$

$$\check{F}(+\infty) = \int_{r_0}^{+\infty} \frac{\hat{\Delta} \check{s}}{(\bar{\varphi} \circ \bar{\psi}^{-1}) \circ \check{G}^{-1}(\check{s})} = +\infty,$$

and  $(\check{x}_1, \check{y}_1) \in \Omega$  is chosen so that

$$\left( \check{F}(q_1(\check{x}, \check{y})) + \int_0^{\check{x}} \int_0^{\check{y}} f(\check{s}, \check{t}) \left( 1 + \int_0^{\check{s}} g(\check{\tau}, \check{t}) \hat{\Delta} \check{\tau} \right) \hat{\Delta} \check{t} \hat{\Delta} \check{s} \right) \in \text{Dom}(\check{F}^{-1}).$$

*Proof* Suppose that  $a(\check{\xi}, \check{\zeta}) > 0$ . Fixing an arbitrary  $(\check{\xi}, \check{\zeta}) \in \Omega$ , we define a positive and nondecreasing function  $z(\check{x}, \check{y})$  by

$$\begin{aligned} z(\check{x}, \check{y}) &= a(\check{\xi}, \check{\zeta}) + \int_0^{\check{x}} \int_0^{\check{y}} \bar{\varphi}(u(\check{s}, \check{t})) [f(\check{s}, \check{t}) \bar{\varphi}(u(\check{s}, \check{t})) + p(\check{s}, \check{t})] \hat{\Delta} \check{t} \hat{\Delta} \check{s} \\ &\quad + \int_0^{\check{x}} \int_0^{\check{y}} f(\check{s}, \check{t}) \bar{\varphi}(u(\check{s}, \check{t})) \left( \int_0^{\check{s}} g(\check{\tau}, \check{t}) \bar{\varphi}(u(\check{\tau}, \check{t})) \hat{\Delta} \check{\tau} \right) \hat{\Delta} \check{t} \hat{\Delta} \check{s}, \end{aligned}$$

for  $0 \leq \check{x} \leq \check{\xi} \leq \check{x}_1, 0 \leq \check{y} \leq \check{\zeta} \leq \check{y}_1$ , then  $z(0, \check{y}) = z(\check{x}, 0) = a(\check{\xi}, \check{\zeta})$  and

$$u(\check{x}, \check{y}) \leq \bar{\psi}^{-1}(z(\check{x}, \check{y})),$$

then we have

$$\begin{aligned} z^{\hat{\Delta} \check{x}}(\check{x}, \check{y}) &= \int_0^{\check{y}} \bar{\varphi}(u(\check{x}, \check{t})) [f(\check{x}, \check{t}) \bar{\varphi}(u(\check{x}, \check{t})) + p(\check{x}, \check{t})] \hat{\Delta} \check{t} \\ &\quad + \int_0^{\check{y}} f(\check{x}, \check{t}) \bar{\varphi}(u(\check{x}, \check{t})) \left( \int_0^{\check{x}} g(\check{\tau}, \check{t}) \bar{\varphi}(u(\check{\tau}, \check{t})) \hat{\Delta} \check{\tau} \right) \hat{\Delta} \check{t} \end{aligned}$$

$$\begin{aligned} &\leq \int_0^{\check{y}} \bar{\varphi} \circ \bar{\psi}^{-1}(z(\check{x}, \check{t})) [f(\check{x}, \check{t}) \bar{\varphi} \circ \bar{\psi}^{-1}(z(\check{x}, \check{t})) + p(\check{x}, \check{t})] \hat{\Delta} \check{t} \\ &\quad + \int_0^{\check{y}} f(\check{x}, \check{t}) \bar{\varphi} \circ \bar{\psi}^{-1}(z(\check{x}, \check{t})) \left( \int_0^{\check{x}} g(\check{\tau}, \check{t}) \bar{\varphi} \circ \bar{\psi}^{-1}(z(\check{\tau}, \check{t})) \hat{\Delta} \check{\tau} \right) \hat{\Delta} \check{t} \\ &\leq \bar{\varphi} \circ \bar{\psi}^{-1}(z(\check{x}, \check{y})) \int_0^{\check{y}} [f(\check{x}, \check{t}) \bar{\varphi} \circ \bar{\psi}^{-1}(z(\check{x}, \check{t})) + p(\check{x}, \check{t})] \hat{\Delta} \check{t} \\ &\quad + \bar{\varphi} \circ \bar{\psi}^{-1}(z(\check{x}, \check{y})) \int_0^{\check{y}} f(\check{x}, \check{t}) \left( \int_0^{\check{x}} g(\check{\tau}, \check{t}) \bar{\varphi} \circ \bar{\psi}^{-1}(z(\check{\tau}, \check{t})) \hat{\Delta} \check{\tau} \right) \hat{\Delta} \check{t}, \end{aligned}$$

or

$$\begin{aligned} \frac{z^{\hat{\Delta}\check{x}}(\check{x}, \check{y})}{\bar{\varphi} \circ \bar{\psi}^{-1}(z(\check{x}, \check{y}))} &\leq \int_0^{\check{y}} [f(\check{x}, \check{t}) \bar{\varphi} \circ \bar{\psi}^{-1}(z(\check{x}, \check{t})) + p(\check{x}, \check{t})] \hat{\Delta} \check{t} \\ &\quad + \int_0^{\check{y}} f(\check{x}, \check{t}) \left( \int_0^{\check{x}} g(\check{\tau}, \check{t}) \bar{\varphi} \circ \bar{\psi}^{-1}(z(\check{\tau}, \check{t})) \hat{\Delta} \check{\tau} \right) \hat{\Delta} \check{t}. \end{aligned} \tag{2.17}$$

Integrating (2.17) and using (2.3), we get

$$\begin{aligned} \check{G}(z(\check{x}, \check{y})) &\leq \check{G}(a(\check{\xi}, \check{\zeta})) + \int_0^{\check{x}} \int_0^{\check{y}} [f(\check{s}, \check{t}) \bar{\varphi} \circ \bar{\psi}^{-1}(z(\check{s}, \check{t})) + p(\check{s}, \check{t})] \hat{\Delta} \check{t} \hat{\Delta} \check{s} \\ &\quad + \int_0^{\check{x}} \int_0^{\check{y}} f(\check{s}, \check{t}) \left( \int_0^{\check{s}} g(\check{\tau}, \check{t}) \bar{\varphi} \circ \bar{\psi}^{-1}(z(\check{\tau}, \check{t})) \hat{\Delta} \check{\tau} \right) \hat{\Delta} \check{t} \hat{\Delta} \check{s}. \end{aligned}$$

$(\check{\xi}, \check{\zeta}) \in \Omega$  is chosen arbitrarily, then from (2.15) we have

$$\begin{aligned} \check{G}(z(\check{x}, \check{y})) &\leq q_1(\check{x}, \check{y}) + \int_0^{\check{x}} \int_0^{\check{y}} f(\check{s}, \check{t}) \bar{\varphi} \circ \bar{\psi}^{-1}(z(\check{s}, \check{t})) \hat{\Delta} \check{t} \hat{\Delta} \check{s} \\ &\quad + \int_0^{\check{x}} \int_0^{\check{y}} f(\check{s}, \check{t}) \left( \int_0^{\check{s}} g(\check{\tau}, \check{t}) \bar{\varphi} \circ \bar{\psi}^{-1}(z(\check{\tau}, \check{t})) \hat{\Delta} \check{\tau} \right) \hat{\Delta} \check{t} \hat{\Delta} \check{s}. \end{aligned}$$

Since  $q_1(\check{x}, \check{y}) > 0$  is a nondecreasing function, fixing an arbitrary point  $(\check{\xi}, \check{\zeta}) \in \Omega$  and defining  $\nu(\check{x}, \check{y}) > 0$  to be a nondecreasing function by

$$\begin{aligned} \nu(\check{x}, \check{y}) &= q_1(\check{\xi}, \check{\zeta}) + \int_0^{\check{x}} \int_0^{\check{y}} f(\check{s}, \check{t}) \bar{\varphi} \circ \bar{\psi}^{-1}(z(\check{s}, \check{t})) \hat{\Delta} \check{t} \hat{\Delta} \check{s} \\ &\quad + \int_0^{\check{x}} \int_0^{\check{y}} f(\check{s}, \check{t}) \left( \int_0^{\check{s}} g(\check{\tau}, \check{t}) \bar{\varphi} \circ \bar{\psi}^{-1}(z(\check{\tau}, \check{t})) \hat{\Delta} \check{\tau} \right) \hat{\Delta} \check{t} \hat{\Delta} \check{s}, \end{aligned}$$

for  $0 \leq \check{x} \leq \check{\xi} \leq \check{x}_1, 0 \leq \check{y} \leq \check{\zeta} \leq y_1$ , we have  $\nu(0, \check{y}) = \nu(\check{x}, 0) = q_1(\check{\xi}, \check{\zeta})$  and

$$z(\check{x}, \check{y}) \leq \check{G}^{-1}(\nu(\check{x}, \check{y})); \tag{2.18}$$

then we have

$$\begin{aligned} \nu^{\hat{\Delta}\check{x}}(\check{x}, \check{y}) &= \int_0^{\check{y}} f(\check{x}, \check{t}) \bar{\varphi} \circ \bar{\psi}^{-1}(z(\check{x}, \check{t})) \hat{\Delta} \check{t} \\ &\quad + \int_0^{\check{y}} f(\check{x}, \check{t}) \left( \int_0^{\check{x}} g(\check{\tau}, \check{t}) \bar{\varphi} \circ \bar{\psi}^{-1}(z(\check{\tau}, \check{t})) \hat{\Delta} \check{\tau} \right) \hat{\Delta} \check{t} \end{aligned}$$

$$\begin{aligned} &\leq \int_0^{\check{y}} f(\check{x}, \check{t}) \bar{\varphi} \circ \bar{\psi}^{-1}(G^{-1}(v(\check{x}, \check{t}))) \hat{\Delta} \check{t} \\ &\quad + \int_0^{\check{y}} f(\check{x}, \check{t}) \left( \int_0^{\check{x}} g(\check{\tau}, \check{t}) \bar{\varphi} \circ \bar{\psi}^{-1}(G^{-1}(v(\check{\tau}, \check{t}))) \hat{\Delta} \check{\tau} \right) \hat{\Delta} \check{t} \\ &\leq (\bar{\varphi} \circ \bar{\psi}^{-1}) \circ \check{G}^{-1}(v(\check{x}, \check{y})) \left[ \int_0^{\check{y}} f(\check{x}, \check{t}) \hat{\Delta} \check{t} + \int_0^{\check{y}} f(\check{x}, \check{t}) \left( \int_0^{\check{x}} g(\check{\tau}, \check{t}) \hat{\Delta} \check{\tau} \right) \hat{\Delta} \check{t} \right], \end{aligned}$$

or

$$\frac{v^{\hat{\Delta} \check{x}}(\check{x}, \check{y})}{(\bar{\varphi} \circ \bar{\psi}^{-1}) \circ \check{G}^{-1}(v(\check{x}, \check{y}))} \leq \left[ \int_0^{\check{y}} f(\check{x}, \check{t}) \hat{\Delta} \check{t} + \int_0^{\check{y}} f(\check{x}, \check{t}) \left( \int_0^{\check{x}} g(\check{\tau}, \check{t}) \hat{\Delta} \check{\tau} \right) \hat{\Delta} \check{t} \right]. \tag{2.19}$$

Integrating (2.19) and using (2.16), we get

$$\check{F}(v(\check{x}, \check{y})) \leq \check{F}(q_1(\check{\xi}, \check{\zeta})) + \int_0^{\check{x}} \int_0^{\check{y}} f(\check{s}, \check{t}) \left[ 1 + \int_0^{\check{s}} g(\check{\tau}, \check{t}) \hat{\Delta} \check{\tau} \right] \hat{\Delta} \check{t} \hat{\Delta} \check{s}.$$

Since we can choose  $(\check{\xi}, \check{\zeta}) \in \Omega$  arbitrarily, we have

$$v(\check{x}, \check{y}) \leq \check{F}^{-1} \left[ \check{F}(q_1(\check{x}, \check{y})) + \int_0^{\check{x}} \int_0^{\check{y}} f(\check{s}, \check{t}) \left[ 1 + \int_0^{\check{s}} g(\check{\tau}, \check{t}) \hat{\Delta} \check{\tau} \right] \hat{\Delta} \check{t} \hat{\Delta} \check{s} \right]. \tag{2.20}$$

From (2.20), (2.18) and  $u(\check{x}, \check{y}) \leq \bar{\psi}^{-1}(z(\check{x}, \check{y}))$  we get the desired inequality in (2.14). For  $a(\check{x}, \check{y}) = 0$ , we carry out the above procedure with  $\epsilon > 0$  instead of  $a(\check{x}, \check{y})$  and subsequently let  $\epsilon \rightarrow 0$ . This completes the proof.  $\square$

**Corollary 2.8** *If we take  $\check{\mathbb{T}} = \mathbb{R}$  in Theorem 2.7, then the inequality*

$$\begin{aligned} \bar{\psi}(u(\check{x}, \check{y})) &\leq a(\check{x}, \check{y}) + \int_0^{\check{x}} \int_0^{\check{y}} \bar{\varphi}(u(\check{s}, \check{t})) [f(\check{s}, \check{t}) \bar{\varphi}(u(\check{s}, \check{t})) + p(\check{s}, \check{t})] d\check{t} d\check{s} \\ &\quad + \int_0^{\check{x}} \int_0^{\check{y}} f(\check{s}, \check{t}) \bar{\varphi}(u(\check{s}, \check{t})) \left( \int_0^{\check{s}} g(\check{\tau}, \check{t}) \bar{\varphi}(u(\check{\tau}, \check{t})) \hat{\Delta} \check{\tau} \right) d\check{t} d\check{s}, \end{aligned}$$

for  $(\check{x}, \check{y}) \in \Omega$ , implies

$$u(\check{x}, \check{y}) \leq \bar{\psi}^{-1} \left\{ \check{G}^{-1} \left( \check{F}^{-1} \left[ \check{F}(q_2(\check{x}, \check{y})) + \int_0^{\check{x}} \int_0^{\check{y}} f(\check{s}, \check{t}) \left( 1 + \int_0^{\check{s}} g(\check{\tau}, \check{t}) d\check{\tau} \right) d\check{t} d\check{s} \right] \right) \right\},$$

for  $0 \leq \check{x} \leq \check{x}_1, 0 \leq \check{y} \leq \check{y}_1$ , where  $\check{G}$  is as defined in (2.8) and

$$\begin{aligned} q_2(\check{x}, \check{y}) &= \check{G}(a(\check{x}, \check{y})) + \int_0^{\check{x}} \int_0^{\check{y}} p(\check{s}, \check{t}) d\check{t} d\check{s}, \\ \check{F}(r) &= \int_{r_0}^r \frac{d\check{s}}{((\bar{\varphi} \circ \bar{\psi}^{-1}) \circ \check{G}^{-1})(\check{s})}, \quad r \geq r_0 > 0, \\ \check{F}(+\infty) &= \int_{r_0}^{+\infty} \frac{d\check{s}}{((\bar{\varphi} \circ \bar{\psi}^{-1}) \circ \check{G}^{-1})(\check{s})} = +\infty, \end{aligned}$$

and  $(\check{x}_1, \check{y}_1) \in \Omega$  is chosen so that

$$\left( \check{F}(q_2(\check{x}, \check{y})) + \int_0^{\check{x}} \int_0^{\check{y}} f(\check{s}, \check{t}) \left( 1 + \int_0^{\check{s}} g(\check{\tau}, \check{t}) d\check{\tau} \right) d\check{t} d\check{s} \right) \in \text{Dom}(\check{F}^{-1}).$$

**Corollary 2.9** *The discrete form of Theorem 2.7 can be obtained by letting  $\check{\mathbb{T}} = \mathbb{Z}$ :*

$$\begin{aligned} \check{\psi}(u(\check{x}, \check{y})) &\leq a(\check{x}, \check{y}) + \sum_{\check{s}=0}^{\check{x}-1} \sum_{\check{t}=0}^{\check{y}-1} \bar{\varphi}(u(\check{s}, \check{t})) [f(\check{s}, \check{t}) \bar{\varphi}(u(\check{s}, \check{t})) + p(\check{s}, \check{t})] \\ &\quad + \sum_{\check{s}=0}^{\check{x}-1} \sum_{\check{t}=0}^{\check{y}-1} f(\check{s}, \check{t}) \bar{\varphi}(u(\check{s}, \check{t})) \left( \sum_{\check{\tau}=0}^{\check{s}-1} g(\check{\tau}, \check{t}) \bar{\varphi}(u(\check{\tau}, \check{t})) \right), \end{aligned}$$

for  $(\check{x}, \check{y}) \in \Omega$ , implies

$$u(\check{x}, \check{y}) \leq \check{\psi}^{-1} \left\{ \check{G}^{-1} \left( \check{F}^{-1} \left[ \check{F}(\check{q}_2(\check{x}, \check{y})) + \sum_{\check{s}=0}^{\check{x}-1} \sum_{\check{t}=0}^{\check{y}-1} f(\check{s}, \check{t}) \left( 1 + \sum_{\check{\tau}=0}^{\check{s}-1} g(\check{\tau}, \check{t}) \right) \right] \right) \right\},$$

for  $0 \leq \check{x} \leq \check{x}_1, 0 \leq \check{y} \leq \check{y}_1$ , where  $\check{G}$  is as defined in (2.9) and

$$\begin{aligned} \check{q}_2(\check{x}, \check{y}) &= \check{G}(a(\check{x}, \check{y})) + \sum_{\check{s}=0}^{\check{x}-1} \sum_{\check{t}=0}^{\check{y}-1} p(\check{s}, \check{t}), \\ \check{F}(r) &= \sum_{\check{s}=r_0}^{r-1} \frac{1}{((\bar{\varphi} \circ \check{\psi}^{-1}) \circ \check{G}^{-1})(\check{s})}, \quad r \geq r_0 > 0, \\ \check{F}(+\infty) &= \sum_{\check{s}=r_0}^{+\infty} \frac{1}{(\bar{\varphi} \circ \check{\psi}^{-1}) \circ \check{G}^{-1}(\check{s})} = +\infty, \end{aligned}$$

and  $(\check{x}_1, \check{y}_1) \in \Omega$  is chosen so that

$$\left( \check{F}(\check{q}_2(\check{x}, \check{y})) + \sum_{\check{s}=0}^{\check{x}-1} \sum_{\check{t}=0}^{\check{y}-1} f(\check{s}, \check{t}) \left( 1 + \sum_{\check{\tau}=0}^{\check{s}-1} g(\check{\tau}, \check{t}) \right) \right) \in \text{Dom}(\check{F}^{-1}).$$

**Theorem 2.10** *Assume that  $g, a, f, u, \check{\psi}$  and  $\bar{\varphi}$  be as in Theorem 2.1. If  $u(\check{x}, \check{y})$  satisfies*

$$\begin{aligned} \check{\psi}(u(\check{x}, \check{y})) &\leq a(\check{x}, \check{y}) + \left( \int_0^{\check{x}} \int_0^{\check{y}} f(\check{s}, \check{t}) \bar{\varphi}(u(\check{s}, \check{t})) \hat{\Delta} \check{t} \hat{\Delta} \check{s} \right)^2 \\ &\quad + \int_0^{\check{x}} \int_0^{\check{y}} f(\check{s}, \check{t}) \bar{\varphi}(u(\check{s}, \check{t})) \left( \int_0^{\check{s}} g(\check{\tau}, \check{t}) \bar{\varphi}(u(\check{\tau}, \check{t})) \hat{\Delta} \check{\tau} \right) \hat{\Delta} \check{t} \hat{\Delta} \check{s}, \end{aligned}$$

for  $(\check{x}, \check{y}) \in \Omega$ , then

$$u(\check{x}, \check{y}) \leq \check{\psi}^{-1} \left\{ \check{H}^{-1} \left[ \check{H}(a(\check{x}, \check{y})) + \check{B}(\check{x}, \check{y}) + \left( \int_0^{\check{x}} \int_0^{\check{y}} f(\check{s}, \check{t}) \hat{\Delta} \check{t} \hat{\Delta} \check{s} \right)^2 \right] \right\}, \tag{2.21}$$

for  $0 \leq \check{x} \leq \check{x}_1, 0 \leq \check{y} \leq \check{y}_1$ , where

$$\check{B}(\check{x}, \check{y}) = \int_0^{\check{x}} \int_0^{\check{y}} f(\check{s}, \check{t}) \left( \int_0^{\check{s}} g(\check{\tau}, \check{t}) \hat{\Delta} \check{\tau} \right) \hat{\Delta} \check{t} \hat{\Delta} \check{s}, \tag{2.22}$$

$$\check{H}(r) = \int_{r_0}^r \frac{\hat{\Delta} \check{s}}{(\bar{\varphi} \circ \bar{\psi}^{-1})^2(\check{s})}, \quad r \geq r_0 > 0, \tag{2.23}$$

$$\check{H}(+\infty) = \int_{r_0}^{+\infty} \frac{\hat{\Delta} \check{s}}{(\bar{\varphi} \circ \bar{\psi}^{-1})^2(\check{s})} = +\infty,$$

and  $(\check{x}_1, \check{y}_1) \in \Omega$  is chosen so that

$$\left( \check{H}(a(\check{x}, \check{y})) + B(\check{x}, \check{y}) + \left( \int_0^{\check{x}} \int_0^{\check{y}} f(\check{s}, \check{t}) \hat{\Delta} \check{t} \hat{\Delta} \check{s} \right)^2 \right) \in \text{Dom}(\check{H}^{-1}).$$

*Proof* Assume that  $a(\check{x}, \check{y}) > 0$ . Taking  $(\check{\xi}, \check{\zeta}) \in \Omega$  as a fixed arbitrary point, we define  $z(\check{x}, \check{y}) > 0$  to be a nondecreasing function by

$$\begin{aligned} z(\check{x}, \check{y}) &= a(\check{\xi}, \check{\zeta}) + \left( \int_0^{\check{x}} \int_0^{\check{y}} f(\check{s}, \check{t}) \bar{\varphi}(u(\check{s}, \check{t})) \hat{\Delta} \check{t} \hat{\Delta} \check{s} \right)^2 \\ &\quad + \int_0^{\check{x}} \int_0^{\check{y}} f(\check{s}, \check{t}) \bar{\varphi}(u(\check{s}, \check{t})) \left( \int_0^{\check{s}} g(\check{\tau}, \check{t}) \bar{\varphi}(u(\check{\tau}, \check{t})) \hat{\Delta} \check{\tau} \right) \hat{\Delta} \check{t} \hat{\Delta} \check{s}, \end{aligned} \tag{2.24}$$

for  $0 \leq \check{x} \leq \check{\xi} \leq \check{x}_1, 0 \leq \check{y} \leq \check{\zeta} \leq \check{y}_1$ , hence  $z(0, \check{y}) = z(\check{x}, 0) = a(\check{\xi}, \check{\zeta})$  and

$$u(\check{x}, \check{y}) \leq \bar{\psi}^{-1}(z(\check{x}, \check{y})).$$

From (2.24), and applying the chain rule on time scales, Theorem 1.4, we get

$$\begin{aligned} z^{\hat{\Delta} \check{x}}(\check{x}, \check{y}) &= 2 \left( \int_0^c \int_0^{\check{y}} f(\check{s}, \check{t}) \bar{\varphi}(u(\check{s}, \check{t})) \hat{\Delta} \check{t} \hat{\Delta} \check{s} \right) \int_0^{\check{y}} f(\check{x}, \check{t}) \bar{\varphi}(u(\check{x}, \check{t})) \hat{\Delta} \check{t} \\ &\quad + \int_0^{\check{y}} f(\check{x}, \check{t}) \bar{\varphi}(u(\check{x}, \check{t})) \left( \int_0^{\check{x}} g(\check{\tau}, \check{t}) \bar{\varphi}(u(\check{\tau}, \check{t})) \hat{\Delta} \check{\tau} \right) \hat{\Delta} \check{t} \\ &\leq 2 \left( \int_0^c \int_0^{\check{y}} f(\check{s}, \check{t}) \bar{\varphi} \circ \bar{\psi}^{-1}(z(\check{s}, \check{t})) \hat{\Delta} \check{t} \hat{\Delta} \check{s} \right) \int_0^{\check{y}} f(\check{x}, \check{t}) \bar{\varphi} \circ \bar{\psi}^{-1}(z(\check{x}, \check{t})) \hat{\Delta} \check{t} \\ &\quad + \int_0^{\check{y}} f(\check{x}, \check{t}) \bar{\varphi} \circ \bar{\psi}^{-1}(z(\check{x}, \check{t})) \left( \int_0^{\check{x}} g(\check{\tau}, \check{t}) \bar{\varphi} \circ \bar{\psi}^{-1}(z(\check{\tau}, \check{t})) \hat{\Delta} \check{\tau} \right) \hat{\Delta} \check{t} \\ &\leq 2(\bar{\varphi} \circ \bar{\psi}^{-1}(z(\check{x}, \check{y})))^2 \left( \int_0^c \int_0^{\check{y}} f(\check{s}, \check{t}) \hat{\Delta} \check{t} \hat{\Delta} \check{s} \right) \int_0^{\check{y}} f(\check{x}, \check{t}) \hat{\Delta} \check{t} \\ &\quad + (\bar{\varphi} \circ \bar{\psi}^{-1}(z(\check{x}, \check{y})))^2 \int_0^{\check{y}} f(\check{x}, \check{t}) \left( \int_0^{\check{x}} g(\check{\tau}, \check{t}) \hat{\Delta} \check{\tau} \right) \hat{\Delta} \check{t}, \end{aligned}$$

thus, we have

$$\begin{aligned} \frac{z^{\hat{\Delta} \check{x}}(\check{x}, \check{y})}{(\bar{\varphi} \circ \bar{\psi}^{-1}(z(\check{x}, \check{y})))^2} &\leq 2 \left( \int_0^c \int_0^{\check{y}} f(\check{s}, \check{t}) \hat{\Delta} \check{t} \hat{\Delta} \check{s} \right) \int_0^{\check{y}} f(\check{x}, \check{t}) \hat{\Delta} \check{t} \\ &\quad + \int_0^{\check{y}} f(\check{x}, \check{t}) \left( \int_0^{\check{x}} g(\check{\tau}, \check{t}) \hat{\Delta} \check{\tau} \right) \hat{\Delta} \check{t} \end{aligned}$$

$$\begin{aligned}
 &= \left[ \left( \int_0^{\check{x}} \int_0^{\check{y}} f(\check{s}, \check{t}) \hat{\Delta} \check{t} \hat{\Delta} \check{s} \right)^2 \right]^{\hat{\Delta} \check{x}} \\
 &\quad + \int_0^{\check{y}} f(\check{x}, \check{t}) \left( \int_0^{\check{x}} g(\check{\tau}, \check{t}) \hat{\Delta} \check{\tau} \right) \hat{\Delta} \check{t}.
 \end{aligned} \tag{2.25}$$

Integrating (2.25) and using (2.23), we get

$$\begin{aligned}
 \check{H}(z(\check{x}, \check{y})) &\leq \check{H}(a(\check{\xi}, \check{\zeta})) + \left( \int_0^{\check{x}} \int_0^{\check{y}} f(\check{s}, \check{t}) \hat{\Delta} \check{t} \hat{\Delta} \check{s} \right)^2 \\
 &\quad + \int_0^{\check{x}} \int_0^{\check{y}} f(\check{s}, \check{t}) \left( \int_0^{\check{s}} g(\check{\tau}, \check{t}) \hat{\Delta} \check{\tau} \right) \hat{\Delta} \check{t} \hat{\Delta} \check{s}.
 \end{aligned}$$

Since  $(\check{\xi}, \check{\zeta}) \in \Omega$  is chosen arbitrarily,

$$z(\check{x}, \check{y}) \leq \check{H}^{-1} \left[ \check{H}(a(\check{x}, \check{y})) + \check{B}(\check{x}, \check{y}) + \left( \int_0^{\check{x}} \int_0^{\check{y}} f(\check{s}, \check{t}) \hat{\Delta} \check{t} \hat{\Delta} \check{s} \right)^2 \right]. \tag{2.26}$$

From (2.26) and  $u(\check{x}, \check{y}) \leq \bar{\psi}^{-1}(z(\check{x}, \check{y}))$ , we get the desired inequality (2.21). For  $a(\check{x}, \check{y}) = 0$ , we carry out the above procedure with  $\epsilon > 0$  instead of  $a(\check{x}, \check{y})$  and subsequently let  $\epsilon \rightarrow 0$ . This completes the proof.  $\square$

**Corollary 2.11** *If we take  $\check{\mathbb{T}} = \mathbb{R}$  in Theorem 2.10, then the inequality*

$$\begin{aligned}
 \bar{\psi}(u(\check{x}, \check{y})) &\leq a(\check{x}, \check{y}) + \left( \int_0^{\check{x}} \int_0^{\check{y}} f(\check{s}, \check{t}) \bar{\varphi}(u(\check{s}, \check{t})) \, d\check{t} \, d\check{s} \right)^2 \\
 &\quad + \int_0^{\check{x}} \int_0^{\check{y}} f(\check{s}, \check{t}) \bar{\varphi}(u(\check{s}, \check{t})) \left( \int_0^{\check{s}} g(\check{\tau}, \check{t}) \bar{\varphi}(u(\check{\tau}, \check{t})) \, d\check{\tau} \right) \, d\check{t} \, d\check{s},
 \end{aligned}$$

for  $(\check{x}, \check{y}) \in \Omega$ , implies

$$u(\check{x}, \check{y}) \leq \bar{\psi}^{-1} \left\{ \check{H}^{-1} \left[ \check{H}(a(\check{x}, \check{y})) + \check{B}(\check{x}, \check{y}) + \left( \int_0^{\check{x}} \int_0^{\check{y}} f(\check{s}, \check{t}) \, d\check{t} \, d\check{s} \right)^2 \right] \right\},$$

for  $0 \leq \check{x} \leq \check{x}_1, 0 \leq \check{y} \leq \check{y}_1$ , where

$$\begin{aligned}
 \check{B}(\check{x}, \check{y}) &= \int_0^{\check{x}} \int_0^{\check{y}} f(\check{s}, \check{t}) \left( \int_0^{\check{s}} g(\check{\tau}, \check{t}) \, d\check{\tau} \right) \, d\check{t} \, d\check{s}, \\
 \check{H}(r) &= \int_{r_0}^r \frac{d\check{s}}{(\bar{\varphi} \circ \bar{\psi}^{-1})^2(\check{s})}, \quad r \geq r_0 > 0, \quad \check{H}(+\infty) = \int_{r_0}^{+\infty} \frac{d\check{s}}{(\bar{\varphi} \circ \bar{\psi}^{-1})^2(\check{s})} = +\infty,
 \end{aligned}$$

and  $(\check{x}_1, \check{y}_1) \in \Omega$  is chosen so that

$$\left( \check{H}(a(\check{x}, \check{y})) + \check{B}(\check{x}, \check{y}) + \left( \int_0^{\check{x}} \int_0^{\check{y}} f(\check{s}, \check{t}) \, d\check{t} \, d\check{s} \right)^2 \right) \in \text{Dom}(\check{H}^{-1}).$$

**Corollary 2.12** *The discrete form can be obtained by letting  $\check{\mathbb{T}} = \mathbb{Z}$  in Theorem 2.10:*

$$\begin{aligned} \check{\psi}(u(\check{x}, \check{y})) &\leq a(\check{x}, \check{y}) + \left( \sum_{\check{s}=0}^{\check{x}-1} \sum_{\check{t}=0}^{\check{y}-1} f(\check{s}, \check{t}) \check{\varphi}(u(\check{s}, \check{t})) \right)^2 \\ &\quad + \sum_{\check{s}=0}^{\check{x}-1} \sum_{\check{t}=0}^{\check{y}-1} f(\check{s}, \check{t}) \check{\varphi}(u(\check{s}, \check{t})) \left( \sum_{\check{\tau}=0}^{\check{s}-1} g(\check{\tau}, \check{t}) \check{\varphi}(u(\check{\tau}, \check{t})) \right), \end{aligned}$$

for  $(\check{x}, \check{y}) \in \Omega$ , implies

$$u(\check{x}, \check{y}) \leq \check{\psi}^{-1} \left\{ \check{H}^{-1} \left[ \check{H}(a(\check{x}, \check{y})) + \check{B}(\check{x}, \check{y}) + \left( \sum_{\check{s}=0}^{\check{x}-1} \sum_{\check{t}=0}^{\check{y}-1} f(\check{s}, \check{t}) \right)^2 \right] \right\},$$

for  $0 \leq \check{x} \leq \check{x}_1, 0 \leq \check{y} \leq \check{y}_1$ , where

$$\begin{aligned} \check{B}(\check{x}, \check{y}) &= \sum_{\check{s}=0}^{\check{x}-1} \sum_{\check{t}=0}^{\check{y}-1} f(\check{s}, \check{t}) \left( \sum_{\check{\tau}=0}^{\check{s}-1} g(\check{\tau}, \check{t}) \right), \\ \check{H}(r) &= \sum_{\check{s}=r_0}^{r-1} \frac{1}{(\check{\varphi} \circ \check{\psi}^{-1})^2(\check{s})}, \quad r \geq r_0 > 0, \quad \check{H}(+\infty) = \sum_{\check{s}=r_0}^{+\infty} \frac{1}{(\check{\varphi} \circ \check{\psi}^{-1})^2(\check{s})} = +\infty, \end{aligned}$$

and  $(\check{x}_1, \check{y}_1) \in \Omega$  is chosen so that

$$\left( \check{H}(a(\check{x}, \check{y})) + \check{B}(\check{x}, \check{y}) + \left( \sum_{\check{s}=0}^{\check{x}-1} \sum_{\check{t}=0}^{\check{y}-1} f(\check{s}, \check{t}) \right)^2 \right) \in \text{Dom}(\check{H}^{-1}).$$

### 3 Applications

The present section illustrates how Theorems 2.7 and 2.1 can be used to study the bound- edness of the solutions of some initial boundary value problem for partial dynamic equa- tions in two independent variables.

Let us consider the problem

$$u^{\hat{\Delta}\check{x}\hat{\Delta}\check{y}}(\check{x}, \check{y}) = \check{F}\left(\check{x}, \check{y}, u(\check{x}, \check{y}), \int_0^{\check{x}} \check{k}(\check{s}, \check{y}, u(\check{s}, \check{y})) \hat{\Delta}\check{s}\right), \tag{3.1}$$

$$u(\check{x}, 0) = a_1(\check{x}), \quad u(0, \check{y}) = a_2(\check{y}), \quad a_1(0) = a_2(0) = 0, \tag{3.2}$$

for any  $(\check{x}, \check{y}) \in \Omega$ , where  $\check{k} \in C_{\text{rd}}(\Omega \times \mathbb{R}, \mathbb{R})$ ,  $\check{F} \in C_{\text{rd}}(\Omega \times \mathbb{R} \times \mathbb{R}, \mathbb{R})$ ,  $a_1 \in C_{\text{rd}}(\check{\mathbb{T}}_1, \mathbb{R})$  and  $a_2 \in C_{\text{rd}}(\check{\mathbb{T}}_2, \mathbb{R})$ .

**Theorem 3.1** *Suppose that the functions  $\check{k}, \check{F}, a_2, a_1$  in (3.1) and (3.2) satisfy the conditions*

$$\begin{aligned} |\check{F}(\check{x}, \check{y}, u(\check{x}, \check{y}, v))| &\leq \check{\varphi}(|u(\check{x}, \check{y})|) [f(\check{x}, \check{y}) \check{\varphi}(|u(\check{x}, \check{y})|) + p(\check{x}, \check{y})] \\ &\quad + f(\check{x}, \check{y}) \check{\varphi}(|u(\check{x}, \check{y})|) v, \end{aligned} \tag{3.3}$$

$$|\check{k}(\check{x}, \check{y}, u(\check{x}, \check{y}))| \leq g(\check{x}, \check{y}) \check{\varphi}(|u(\check{x}, \check{y})|), \tag{3.4}$$

$$|a_1(\check{x}) + a_2(\check{y})| \leq a(\check{x}, \check{y}), \tag{3.5}$$



where the functions  $p, g, a, f,$  and  $\bar{\varphi}$  are defined as in Theorem 2.7 with  $a(\check{x}, \check{y}) > 0,$  for all  $(\check{x}, \check{y}) \in \Omega,$  then

$$|u(\check{x}, \check{y})| \leq \check{G}^{-1} \left( \check{F}^{-1} \left[ \check{F}(q_2(\check{x}, \check{y})) + \int_0^{\check{x}} \int_0^{\check{y}} f(\check{s}, \check{t}) \left[ 1 + \int_0^{\check{s}} g(\check{\tau}, \check{t}) \hat{\Delta} \check{\tau} \right] \hat{\Delta} \check{t} \hat{\Delta} \check{s} \right] \right), \tag{3.6}$$

for  $0 \leq \check{x} \leq \check{x}_1, 0 \leq \check{y} \leq \check{y}_1,$  where  $F, q_2$  and  $G$  are defined as in Theorem 2.7.

*Proof* If the problem (3.1) and (3.2) has a solution  $u(\check{x}, \check{y}),$  it can be written as

$$u(\check{x}, \check{y}) = a_1(\check{x}) + a_2(\check{y}) + \int_0^{\check{x}} \int_0^{\check{y}} \check{F} \left( \check{s}, \check{t}, u(\check{s}, \check{t}), \int_0^{\check{s}} \check{k}(\check{\tau}, \check{t}, u(\check{\tau}, \check{t})) \hat{\Delta} \check{\tau} \right) \hat{\Delta} \check{t} \hat{\Delta} \check{s}, \tag{3.7}$$

for any  $(\check{x}, \check{y}) \in \Omega.$  Using the conditions (3.3), (3.4) and (3.5) in (3.7), we get

$$\begin{aligned} |u(\check{x}, \check{y})| &\leq a(\check{x}, \check{y}) + \int_0^{\check{x}} \int_0^{\check{y}} \bar{\varphi}(|u(\check{s}, \check{t})|) [f(\check{s}, \check{t}) \bar{\varphi}(|u(\check{s}, \check{t})|) + p(\check{s}, \check{t})] \hat{\Delta} \check{t} \hat{\Delta} \check{s} \\ &\quad + \int_0^{\check{x}} \int_0^{\check{y}} f(\check{s}, \check{t}) \bar{\varphi}(|u(\check{s}, \check{t})|) \left( \int_0^{\check{s}} g(\check{\tau}, \check{t}) \bar{\varphi}(|u(\check{\tau}, \check{t})|) \hat{\Delta} \check{\tau} \right) \hat{\Delta} \check{t} \hat{\Delta} \check{s}, \end{aligned} \tag{3.8}$$

for any  $(\check{x}, \check{y}) \in \Omega.$  Now, an application of Theorem 2.7 to (3.8) yields the required inequality in (3.6) where  $\bar{\psi}(u) = u.$  □

Let us consider the initial boundary value problem of the form

$$(z^q)^{\hat{\Delta} \check{x} \hat{\Delta} \check{y}}(\check{x}, \check{y}) = \check{A} \left( \check{x}, \check{y}, z(\check{x}, \check{y}), \int_0^{\check{x}} h(\check{s}, \check{y}, z(\check{s}, \check{y})) \hat{\Delta} \check{s} \right) \tag{3.9}$$

$$z(\check{x}, 0) = a_1(\check{x}), \quad z(0, \check{y}) = a_2(\check{y}), \quad a_1(0) = a_2(0) = 0, \tag{3.10}$$

for any  $(\check{x}, \check{y}) \in \Omega.$

**Theorem 3.2** Assume that the functions  $h, A, a_2, a_1$  in (3.9) and (3.10) satisfy the conditions

$$|A(\check{x}, \check{y}, z(\check{x}, \check{y}), v)| \leq f(\check{x}, \check{y}) |z^r(\check{x}, \check{y})| + f(\check{x}, \check{y}) v, \tag{3.11}$$

$$|h(\check{x}, \check{y}, z(\check{x}, \check{y}))| \leq g(\check{x}, \check{y}) |z^r(\check{x}, \check{y})|, \tag{3.12}$$

$$|a_1(\check{x}) + a_2(\check{y})| \leq a(\check{x}, \check{y}), \tag{3.13}$$

where  $r \geq q > 0,$  then

$$|z(\check{x}, \check{y})| \leq \left[ (a(\check{x}, \check{y}))^{\frac{q-r}{q}} + \frac{q-r}{q} \int_0^{\check{x}} \int_0^{\check{y}} f(\check{s}, \check{t}) \left( 1 + \int_0^{\check{s}} g(\check{\tau}, \check{t}) \hat{\Delta} \check{\tau} \right) \hat{\Delta} \check{t} \hat{\Delta} \check{s} \right]^{\frac{1}{q-r}}, \tag{3.14}$$

for  $0 \leq \check{x} \leq \check{x}_1, 0 \leq \check{y} \leq \check{y}_1.$

*Proof* If the problem (3.9) and (3.10), has a solution  $z(\check{x}, \check{y})$  it can be written as

$$z^q(\check{x}, \check{y}) = a_1(x) + a_2(y) + \int_0^{\check{x}} \int_0^{\check{y}} \check{F} \left( \check{s}, \check{s} \check{t}, u(\check{s}, \check{t}), \int_0^{\check{s}} \check{k}(\check{\tau}, \check{t}, u(\check{\tau}, \check{t})) \hat{\Delta} \check{\tau} \right) \hat{\Delta} \check{t} \hat{\Delta} \check{s}, \tag{3.15}$$

for any  $(\check{x}, \check{y}) \in \Omega$ . Using the conditions (3.11), (3.12) and (3.13) in (3.15), we get

$$\begin{aligned}
 |z^q(\check{x}, \check{y})| &\leq a(\check{x}, \check{y}) + \int_0^{\check{x}} \int_0^{\check{y}} f(\check{s}, \check{t}) |z^r(s, t)| \hat{\Delta} \check{t} \hat{\Delta} \check{s} \\
 &\quad + \int_0^{\check{x}} \int_0^{\check{y}} f(\check{s}, \check{t}) \left( \int_0^{\check{s}} g(\check{\tau}, \check{t}) |z^r(\check{\tau}, \check{t})| \hat{\Delta} \check{\tau} \right) \hat{\Delta} \check{t} \hat{\Delta} \check{s},
 \end{aligned}
 \tag{3.16}$$

from (3.16), we get

$$\begin{aligned}
 |z^q(\check{x}, \check{y})| &\leq a(\check{x}, \check{y}) + \int_0^{\check{x}} \int_0^{\check{y}} f(\check{s}, \check{t}) |z^r(\check{t}, \check{t})| \hat{\Delta} \check{t} \hat{\Delta} \check{s} \\
 &\quad + \int_0^{\check{x}} \int_0^{\check{y}} f(\check{s}, \check{t}) \left( \int_0^{\check{s}} g(\check{\tau}, \check{t}) |z^r(\check{\tau}, \check{t})| \hat{\Delta} \check{\tau} \right) \hat{\Delta} \check{t} \hat{\Delta} \check{s},
 \end{aligned}
 \tag{3.17}$$

for any  $(\check{x}, \check{y}) \in \Omega$ . A suitable application of Theorem 2.1 to (3.17) with  $\bar{\psi}(u) = u^q$ ,  $\bar{\varphi}(u) = u^r$  and  $p(\check{x}, \check{y}) = 0$  gives the required inequality in (3.14). □

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