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# A new approach to the Cauchy and Goursat problems for the nonlinear Wheeler–DeWitt equation

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**Abstract.** We consider a nonlinear version of the Wheeler–DeWitt equation which was introduced by Cooper, Susskind, and Thorlacius in the context of two-dimensional quantum cosmology. We establish the existence of global solutions to the Cauchy problem and Goursat problems which, both, arise naturally in physics. Our method of proof is based on a nonlinear transformation of the Wheeler–DeWitt equation and on techniques introduced by Baez and collaborators and by Tsutsumi for nonlinear wave equations.

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#### 1. Introduction

### Objective of this paper

The Wheeler–DeWitt equation provides a simple, yet challenging model which describes a homogeneous isotropic Universe filled with a scalar field y with mass m. This equation arose from an early attempt to combine ideas from quantum mechanics and general relativity. The Wheeler–DeWitt is a linear, but singular wave equation which reads as follows [8–10]:

$$\frac{\partial^2 \psi}{\partial x^2} + \frac{p}{x} \frac{\partial \psi}{\partial x} - \frac{1}{x^2} \frac{\partial^2 \psi}{\partial y^2} + m^2 x^4 y^2 \psi - x^2 \psi = 0, \qquad (1.1)$$

in which the independent variable  $x \in (0, +\infty)$  represents a scale factor and the scalar field y is viewed as an independent variable. Moreover,  $p \in \mathbb{R}$  is a factor-ordering coefficient due to quantization, and the unknown function  $\psi = \psi(x, y) \in \mathbb{C}$  is the so-called wave function of the Universe for the minisuperspace model under consideration.

A mathematical study of the corresponding Cauchy problem with prescribed initial condition at y = 0, say

$$\psi(x,0) = \psi_0(x), \qquad \frac{\partial \psi}{\partial y}(x,0) = \psi_1(x), \qquad (1.2)$$

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was initiated by Dias and Figueira [4] in two simplified cases: they treated the case  $x \in (0, R)$  with R > 0 as well as the massless case m = 0 in the whole interval  $x \in (0, +\infty)$  by introducing a suitable transformation of the equation [6,7].

On the other hand, more recently for a modeling effects arising in quantum cosmology, Cooper et al. [3] introduced a *nonlinear Wheeler–DeWitt equation*, namely

$$\frac{\partial^2 \psi}{\partial x^2} + \frac{p}{x} \frac{\partial \psi}{\partial x} - \frac{1}{x^2} \frac{\partial^2 \psi}{\partial y^2} + m^2 x^4 y^2 \psi - x^2 \psi + \lambda(x) |\psi|^r \psi = 0, \qquad (1.3)$$

in which the function  $\lambda = \lambda(x) \in \mathbb{R}$  is prescribed and  $r \geq 1$  is a parameter. This model was found to provide a better description of some phenomena in quantum cosmology. (We also refer [12] for an alternative nonlinear model.) In Dias and Figueira [5], this nonlinear model was also consider in a simplified case, that is,  $x \in (0, R)$  with R > 0, and the Cauchy problem was solved for general data  $\left(\psi(x, 0), \frac{\partial \psi}{\partial y}(x, 0)\right)$  and for the function  $\lambda(x) = \lambda x^{q-2}, q \geq \frac{1}{2} rp$  with  $\lambda \in \mathbb{R}$ .

In the present work, we pursue this analysis further and rely on the transformation introduced in [6,7] (in the linear case) in order to study the nonlinear equation (1.3) in the whole interval x > 0. Specifically, we assume that the nonlinearity of the Wheeler–DeWitt equation satisfies the conditions

$$r \ge 2, \qquad \lambda(x) = \lambda x^{q-2}, \quad q = \frac{p-1}{2}r, \quad \lambda \in \mathbb{R}.$$
 (1.4)

By setting

$$z = \log x, \qquad x \in (0, +\infty) \tag{1.5}$$

and in view of

$$u(z,y) = x^{\frac{p-1}{2}} \psi(x,y) = e^{\frac{p-1}{2}z} \psi(e^z,y),$$
(1.6)

we arrive at the following terminology.

**Definition 1.1.** The **reduced nonlinear Wheeler–DeWitt equation** by definition is

$$\frac{\partial^2 u}{\partial z^2} - \frac{\partial^2 u}{\partial y^2} - \frac{1}{4} (p-1)^2 u + \left( m^2 y^2 e^{6z} - e^{4z} \right) u + \lambda |u|^r u = 0.$$
(1.7)

in which u = u(z, y) is a complex-valued function defined over  $(z, y) \in \mathbb{R}^2$ .

Observe that the principal part of (1.7) decomposes into two parts, i.e.

• the 1 + 1 Klein-Gordon operator, that is,

$$\frac{\partial^2 u}{\partial z^2} - \frac{\partial^2 u}{\partial y^2} - \frac{1}{4} (p-1)^2 u \tag{1.8}$$

• and a potential term of exponential type

$$\left(m^2 y^2 e^{6z} - e^{4z}\right) u. \tag{1.9}$$

In addition, the nonlinear version of the Wheeler–DeWitt equation under consideration also involves the nonlinear term

$$\lambda |u|^r u. \tag{1.10}$$

Our objective in this paper is establishing a well-posedness theory for the Cauchy problem and for the Goursat problem by extending the methods introduced originally by Baez et al. [1,2] and Tsutsumi [14] for nonlinear wave equations.

#### Main result of this paper

First of all, in Sect. 2, we study the massless case m = 0 and consider the Cauchy problem for the equation (1.7) with data

$$\left(u(x,0),\frac{\partial u}{\partial y}(x,0)\right) = \left(u_0(x),v_0(x)\right) \in X \times H_V^1,\tag{1.11}$$

where (in this case y is regarded as our "time" variable)

$$V(z) = e^{4z},$$
  

$$H_{V}^{1} = \left\{ u \in H^{1}(\mathbb{R}) / V^{1/2}u \in L^{2}(\mathbb{R}) \right\},$$
  

$$X = \left\{ u \in H_{V}^{1} / \frac{d^{2}u}{dz^{2}} - Vu \in L^{2}(\mathbb{R}) \right\},$$
  
(1.12)

endowed with their natural norms. Here, we will be able to rely on rather standard techniques for nonlinear Klein–Gordon equations (see for instance [13] and the references therein). Considering next a particular class of initial data and provided  $\lambda < 0$ , we study the sequence <sup>1</sup>

$$v_p(z,y) = e^{ic_p^2 y} u_p(z,c_p y),$$
 (1.13)

where  $c_p = \frac{1}{2}(p-1)$  (with  $p \neq 1$ ) and  $u_p$  is the solution to the corresponding Cauchy problem and, when  $p \to \infty$ , we prove that the functions  $v_p$  converge in the topology  $C([-T,T]; L^2(\mathbb{R})), \forall T > 0$ , toward a function

$$\widetilde{v}(\widehat{z},\widehat{y}) \in C(\mathbb{R};L^2(\mathbb{R})) \cap L^{\infty}_{\text{loc}}(\mathbb{R};X)$$
(1.14)

such that

$$\frac{\partial \widetilde{v}}{\partial y} \in L^{\infty}_{\text{loc}}(\mathbb{R}; L^2(\mathbb{R})), \qquad \widetilde{v}(\widehat{z}, 0) = \lim_{p \to \infty} u_p(\widehat{z}, 0) \text{ in } L^2(\mathbb{R}), \tag{1.15}$$

and, moreover, this function is nothing but a solution to the **nonlinear** Schrodinger equation

$$i\frac{\partial\widetilde{v}}{\partial y} + \frac{1}{2}\left(\frac{\partial^2\widetilde{v}}{\partial z^2} - V\widetilde{v} + \lambda \,|\widetilde{v}|^r\,\widetilde{v}\right) = 0. \tag{1.16}$$

Our technique of proof for this latter statement is an adaptation of the method developed by Tsutsumi [14] for two space dimensions and V = 0. Importantly, our result validates a heuristic given by physicists about the Wheeler–DeWitt equation.

<sup>1</sup>Here,  $i = \sqrt{-1}$ .

Next, in Sect. 3 we study the periodic Goursat problem associated with the Wheeler–DeWitt equation (1.7), and establish the existence of  $2\pi$ -periodic solutions ((in the y variable) which is now regarded as the "space" variable), when with data are prescribed on the characteristic cone

$$C_0 = \{(z, y) \mid z = |y|, |y| \le \pi\}.$$
(1.17)

Our technique of proof is an adaptation of the method developed by Baez et al. [1,2] and begins by reducing the problem under consideration to a more convenient Cauchy problem for an evolution equation. When  $m \neq 0$ , in the equation (1.7) we need to replace the function  $m^2y^2e^{6z}$  by  $m^2\theta(y^2)e^{6z}$  where  $\theta(y^2)$  is the  $2\pi$ -periodic extension of the function  $y^2$  in  $[-\pi, \pi]$ . In order to obtain smooth local (in the variable z) solutions, we restrict the Goursat data accordingly, and to obtain global (in z) solutions we take  $\lambda > 0$ .

Two cases are of particular interest and are covered by our theorems in this section:

- Case  $m^2 y^2 = k^2$  (a positive constant). This is a simplification which is often made in the physical applications, for instance in the study of tunneling solutions; cf. [8].
- Case  $c_p = 0$ , that is p = 1. The spatial curvature term  $e^{4z}$  is also neglected in the study of inflationary solutions, cf. again [8].

### 2. The Cauchy problem for the massless case

In this section we extend to the nonlinear equation (1.7), in the particular case m = 0, the existence results for the Cauchy problem and the singular limit when  $p \to \infty$  obtained in [6] and [7]. We write the equation (1.7) for m = 0:

$$\frac{\partial^2 u}{\partial y^2} - \frac{\partial^2 u}{\partial z^2} + \frac{1}{4}(p-1)^2 u + Vu + \lambda |u|^r u = 0, \qquad (2.1)$$

with  $V(z) = e^{4z}u, (z, y) \in \mathbb{R}^2$ .

We will study the Cauchy problem for initial data u(z,0),  $\frac{\partial u}{\partial y}(z,0)$ , for  $z \in \mathbb{R}$ . For this purpose we introduce, as in [6], the space (in z)

$$H_{V}^{1} = \left\{ v \in H^{1}(\mathbb{R}) / V^{1/2} v \in L^{2}(\mathbb{R}) \right\}$$
(2.2)

with norm

 $\|v\|_{H^1_V} = \left(\|v\|_{H^1}^2 + \|V^{1/2}v\|_2^2\right)^{1/2},$ 

where  $\|\cdot\|_p$  denotes the standard  $L^p$  norm. Let

$$X = \left\{ v \in H_V^1 \mid \frac{\partial^2 v}{\partial z^2} - Vv \in L^2 \right\},\,$$

and  $H=H^1_V\times L^2,\, D(A)=X\times H^1_V,\, A\colon D(A)\subset H\to H$  defined by

$$A\begin{pmatrix}v_1\\v_2\end{pmatrix} = \begin{pmatrix}0 & 1\\\frac{\partial^2}{\partial z^2} - V - c_p^2 & 0\end{pmatrix}\begin{pmatrix}v_1\\v_2\end{pmatrix}$$
(2.3)

with  $c_p = \frac{1}{2} (p - 1)$ .

With  $v = \frac{\partial u}{\partial y}$  the equation (2.1) can be written in the first-order form

$$\frac{\partial}{\partial y} \begin{pmatrix} u \\ v \end{pmatrix} = A \begin{pmatrix} u \\ v \end{pmatrix} + J \begin{pmatrix} u \\ v \end{pmatrix}, \qquad J \begin{pmatrix} u \\ v \end{pmatrix} = \begin{pmatrix} 0 \\ -\lambda |u|^r u \end{pmatrix}.$$
(2.4)

The operator A is skew-self-adjoint in H (cf. [6], Theorem 1) and so generates a unitary group of operators in H. We take the initial (in y) data

$$\left(u_0(\widehat{z}) = u(\widehat{z}, 0), \ v_0(\widehat{z}) = \frac{\partial u}{\partial y}(\widehat{z}, 0)\right) \in D(A).$$

We study first the existence of a local (in y) solution to the Cauchy problem

$$u \in C\left([0, y_0]; X\right) \cap C^1\left([0, y_0]; H^1_V\right) \cap C^2\left([0, y_0], L^2\right).$$
(2.5)

$$\begin{split} & \text{If } \varphi = \begin{pmatrix} u \\ v \end{pmatrix} \in D(A) = X \times H_V^1 \text{ it is easy to see, since } H^1(\mathbb{R}) \hookrightarrow L^\infty(\mathbb{R}), \text{ that} \\ & J\varphi \in D(A), \text{ and if } \varphi_1 = \begin{pmatrix} u_1 \\ v_1 \end{pmatrix}, \varphi_2 = \begin{pmatrix} u_2 \\ v_2 \end{pmatrix} \in D(A) \text{ we have} \\ & A(J\varphi_1 - J\varphi_2) = \begin{pmatrix} -\lambda |u_1|^r u_1 + \lambda |u_2|^r u_2 \\ 0 \end{pmatrix}, \\ & \left\| J(\varphi_1) - J(\varphi_2) \right\|_A^2 = \left\| J(\varphi_1) - J(\varphi_2) \right\|_{H_V^1 \times L^2}^2 + \left\| AJ(\varphi_1) - AJ(\varphi_2) \right\|_{H_V^1 \times L^2}^2 \\ & = |\lambda|^2 \left\| |u_1|^r u_1 - |u_2|^r u_2 \right\|_2^2 + |\lambda|^2 \left\| |u_1|^r u_1 - |u_2|^r u_2 \right\|_{H^1}^2 \\ & + |\lambda|^2 \left\| V^{1/2} \left( |u_1|^r u_1 - |u_2|^r u_2) \right\|_2^2. \end{split}$$

We have

$$||u_1|^r u_1 - |u_2|^r u_2| \le c (|u_1|^r + |u_2|^r) |u_1 - u_2|$$

and so

$$\left\| V^{1/2} \left( |u_1|^r u_1 - |u_2|^r u_2 \right) \right\|_2 \le c \left( \|\varphi_1\|_A^r + \|\varphi_2\|_A^r \right) \|\varphi_1 - \varphi_2\|_A$$

since  $H^1(\mathbb{R}) \hookrightarrow L^{\infty}(\mathbb{R})$ . Moreover, for  $r \geq 2$ , it is not difficult to derive

$$\begin{aligned} \left\| |u_1|^r u_1 - |u_2|^r u_2 \right\|_{H^1} &\leq c \left( \|u_1\|_{H^1}^r + \|u_2\|_{H^1}^r \right) \|u_1 - u_2\|_{H^1} \\ &\leq c \left( \|\varphi_1\|_A^r + \|\varphi_2\|_A^r \right) \|\varphi_1 - \varphi_2\|_A. \end{aligned}$$

Hence,

$$\begin{split} \left\|J(\varphi_1)-J(\varphi_2)\right\|_A &\leq c\left(\|\varphi_1\|_A^r+\|\varphi_2\|_A^r\right)\,\|\varphi_1-\varphi_2\|_A. \end{split}$$
 In view of Theorem X.72 in [13], we conclude the following.

**Theorem 2.1.** For  $\varphi_0 = \begin{pmatrix} u_0 \\ v_0 \end{pmatrix} \in D(A)$ , there exists a  $y_0 > 0$  and a unique function  $\varphi(\widehat{y}) = (u(\widehat{y}), v(\widehat{y})), y \in [0, y_0]$ , such that  $\varphi \in C([0, y_0]; D(A)) \cap C^1([0, y_0]; H)$  and  $\frac{\partial}{\partial y} \begin{pmatrix} u \\ v \end{pmatrix} = A \begin{pmatrix} u \\ v \end{pmatrix} + J \begin{pmatrix} u \\ v \end{pmatrix}, y \in [0, y_0], \varphi(0) = \varphi_0.$ 

Returning to the Cauchy problem for (2.1) we deduce the following result:

**Corollary 2.1.** For  $(u_0, v_0) \in D(A)$ , there exists  $a y_0 > 0$  and a unique function  $u(\hat{y}) \in C([0, y_0]; X) \cap C^1([0, y_0]; H) \cap C^2([0, y_0]; L^2)$  satisfying (2.1) for  $y \in [0, y_0]$  and  $u(0) = u_0$ ,  $\frac{\partial u}{\partial y}(0) = v_0$ .

Moreover, we have the energy conservation law

$$E(y) = \frac{1}{2} \int_{\mathbb{R}} \left| \frac{\partial u}{\partial y} \right|^2 dz + \frac{1}{4} (p-1)^2 \int_{\mathbb{R}} |u|^2 dz + \frac{1}{2} \int_{\mathbb{R}} V|u|^2 dz + \frac{\lambda}{n+2} \int_{\mathbb{R}} |u|^{r+2} dz = E(0), \quad y \in [0, y_0].$$
(2.6)

Now, let us assume  $\lambda > 0$ . From (2.6) we establish the existence of a local solution to the Cauchy problem, if  $p \neq 1$ , setting  $\varphi(y) = \left(u(y), \frac{\partial u}{\partial y}(y)\right), y \in [0, y_0], H = H_V^1 \times L^2$ ,

$$||AJ(\varphi)||_H \le c ||\varphi||_H^{r+1} \le c.$$
 (2.7)

Hence, from the semigroup integral formula we deduce

$$\begin{aligned} \|A\varphi(y)\|_H &\leq \|A\varphi(0)\|_H + \int_0^y \|AJ(\varphi(s))\|_H \, ds \\ &\leq \|A\varphi_0\|_H + c \int_0^y \|\varphi(s)\|_H^{r+1} ds \\ &\leq \|A\varphi_0\|_H + cy \end{aligned}$$

and so, by Gronwall's inequality,

$$||A\varphi(y)||_H \le ||A\varphi(0)||_H e^{cy}.$$

We can thus state the following result.

**Theorem 2.2.** Assuming  $\lambda > 0$ ,  $p \neq 1$  and  $(u_0, v_0) \in D(A)$ , there is a unique function  $u \in C((0, +\infty); X) \cap C^1((0, +\infty); H_V^1) \cap C^2((0, +\infty); L^2)$  satisfying (2.1) and  $u(0) = u_0$ ,  $\frac{\partial u}{\partial y}(0) = v_0$ .

Now, consider, for each  $p \neq 1$  and with  $\lambda > 0$ ,  $\left(u_p(0), \frac{\partial u_p}{\partial y}(0)\right) \in D(A)$ , the unique solution  $u_p \in C((0, +\infty); X) \cap C^1((0, +\infty); H^1_V) \cap C^2((0, +\infty); L^2)$  of the previous Cauchy problem.

Let us introduce (cf. [7]) the function

$$v_p(z,y) = e^{ic_p^2 y} u_p(z,c_p y), \qquad c_p = \frac{1}{2}(p-1)$$
 (2.8)

and

$$\varepsilon_p^2 = \frac{1}{2c_p^2} = \frac{2}{(p-1)^2}.$$
(2.9)

We have

$$i\frac{\partial v_p}{\partial y} - \varepsilon_p^2 \frac{\partial^2 v_p}{\partial y^2} + \frac{1}{2} \left( \frac{\partial^2 v_p}{\partial z^2} - V v_p - \lambda |v_p|^r v_p \right) = 0,$$
  

$$v_p(z,0) = v_{0p}(z) = u_{0p}(z), \quad \frac{\partial v_p}{\partial y}(z,0) = v_{1p}(z) = c_p(iu_{0p} + u_{1p})(z),$$
(2.10)

$$\{u_{0p}\}_p \text{ bounded in } X, \quad \{u_{1p}\}_p \text{ bounded in } H^1_V, u_{0p} \xrightarrow[p \to \infty]{} \widetilde{v}_0 \text{ in } L^2(\mathbb{R}), \quad \text{with } \widetilde{v}_0 \in X.$$
 (2.11)

Using the technique in [14], we want to extend Theorem 3 in [7] to obtain the following result:

**Theorem 2.3.** Assume (2.10) and (2.11). Then, there exists a unique function  $\tilde{v} \in C(\mathbb{R}_+; L^2) \cap L^{\infty}_{loc}(\mathbb{R}_+; X)$ , such that  $v_y \in L^{\infty}_{loc}(\mathbb{R}_+, L^2)$ , solution to the Cauchy problem

$$i\frac{\partial\widetilde{v}}{\partial y} + \frac{1}{2}\left(\frac{\partial^{2}\widetilde{v}}{\partial z^{2}} - V\widetilde{v} - \lambda|\widetilde{v}|^{r}\widetilde{v}\right) = 0, \qquad (\lambda > 0, \quad r \ge 2),$$
  
$$\widetilde{v}(0) = \widetilde{v}_{0}.$$
(2.12)

Moreover, for each T > 0, we have (with  $v_p$  solution to (2.10)),

$$v_p \xrightarrow[p \to \infty]{} \widetilde{v}$$
 in  $C([0,T]; L^2(\mathbb{R}))$  (with the sup norm).

*Proof.* To simplify the notation, we will replace  $v_p$  by v and  $\varepsilon_p^2$  by  $\varepsilon^2$  (if necessary) and we assume  $\lambda = 1$ .

Multiplying the equation in (2.10) by  $\overline{v}_y$  (complex conjugate of  $v_y$ ), integrating in  $\mathbb{R}$  (in z) and taking the real part, we obtain (denoting by  $v_y$  the derivative  $\frac{\partial v}{\partial y}, \ldots$ ),

$$\frac{1}{2}\varepsilon^{2}\frac{d}{dy}\int|v_{y}|^{2}dz + \frac{1}{4}\frac{d}{dy}\int|v_{z}|^{2}dz + \frac{1}{4}\frac{d}{dy}\int V|v|^{2}dz + \frac{1}{2}\frac{1}{r+2}\frac{d}{dy}\int|v|^{r+2}dz = 0.$$
(2.13)

Hence, with c independent of p and y,

$$\varepsilon_p \| (v_p)_y \|_2 \le c, \tag{2.14}$$

$$\|(v_p)_z\|_2 \le c,\tag{2.15}$$

$$\|v_p\|_{r+2} \le c, \tag{2.16}$$

$$\|V^{1/2} v_p\|_2 \le c. \tag{2.17}$$

Multiplying the equation in (2.10) by  $\overline{v}_p$ , integrating in  $\mathbb{R}$ , and taking the imaginary part, we obtain

$$\varepsilon^2 \operatorname{Im} \int v_{yy} \overline{v} \, dz - \operatorname{Re} \int v_y \overline{v} \, dz = 0,$$

and since

$$\operatorname{Im} \int v_{yy}\overline{v}\,dz = \operatorname{Im} \left(\frac{d}{dy}\int v_y\overline{v}\,dz - \int v_y\overline{v}_y\,dz\right) = \operatorname{Im} \frac{d}{dy}\int v_y\overline{v}\,dz,$$

we find

$$\varepsilon^2 \frac{d}{dy} \operatorname{Im} \int v_y \overline{v} \, dz - \frac{d}{dy} \frac{1}{2} \int |v|^2 dz = 0$$
$$\int |v|^2 dz \le 2 \varepsilon^2 \, \|v_y\|_2 \, \|v\|_2 + c,$$

and so, by (2.14),

$$\|v_p\|_2 \le c. \tag{2.18}$$

Now (the calculations can be justified by a suitable regularization technique) we take the y derivative in the equation in (2.10) to obtain, by multiplying by  $(\overline{v}_p)_y$ , integrating and taking the imaginary part:

$$\operatorname{Im} \varepsilon^{2} \int \frac{\partial^{3} v}{\partial y^{3}} \,\overline{v}_{y} \, dz - \operatorname{Re} \int v_{yy} \overline{v}_{y} \, dz - \operatorname{Im} \frac{1}{2} \int \frac{\partial^{3} v}{\partial y \, \partial^{2} z} \,\overline{v}_{y} \, dz \\ + \operatorname{Im} \frac{1}{2} \int V v_{y} \overline{v}_{y} \, dz + \operatorname{Im} \frac{1}{2} \int \left( |v|^{r} v \right)_{y} \,\overline{v}_{y} \, dz = 0, \\ \operatorname{Im} \frac{d}{dy} \, \varepsilon^{2} \int v_{yy} \overline{v}_{y} \, dz - \frac{1}{2} \frac{d}{dy} \int |v_{y}|^{2} dz + \frac{r}{2} \operatorname{Im} \int |v|^{r-2} \operatorname{Re}(v \overline{v}_{y}) \, v \overline{v}_{y} \, dz = 0, \\ \operatorname{Im} \frac{d}{dy} \, \varepsilon^{2} \int v_{yy} \overline{v}_{y} \, dz - \frac{1}{2} \frac{d}{dy} \int |v_{y}|^{2} dz + \frac{r}{2} \operatorname{Im} \int |v|^{r-2} \operatorname{Re}(v \overline{v}_{y}) \, v \overline{v}_{y} \, dz = 0, \\ \operatorname{Im} \frac{d}{dy} \, \varepsilon^{2} \int v_{yy} \overline{v}_{y} \, dz - \frac{1}{2} \frac{d}{dy} \int |v_{y}|^{2} dz + \frac{r}{2} \operatorname{Im} \int |v|^{r-2} \operatorname{Re}(v \overline{v}_{y}) \, v \overline{v}_{y} \, dz = 0,$$

and so, by (2.15), (2.18) and (2.11), for y > 0 we find

$$\int |v_y|^2 \, dz \le c + \varepsilon^2 \, \|v_{yy}\|_2 \, \|v_y\|_2 + c \int_0^y \int |v_y|^2 \, dz \, d\tau,$$

and so

$$\int |(v_p)_y|^2 dz \le c + \left(\varepsilon_p^4 \, \|(v_p)_{yy}\|_2^2\right) + c \int_0^y \int |(v_p)_y|^2 dz \, d\tau.$$
(2.19)

Now, we take again the y derivative in (2.10), multiply by  $(\overline{v}_p)_{yy}$ , integrate in  $\mathbb{R}$ , and take the real part:

$$\varepsilon^{2} \frac{d}{dy} \int |v_{yy}|^{2} dz + \frac{1}{2} \frac{d}{dy} \int |v_{yz}|^{2} dz + \frac{1}{2} \frac{d}{dy} \int V |v_{y}|^{2} dz \frac{1}{2} \operatorname{Re} \int (|v|^{r} v)_{y} \overline{v}_{yy} dz = 0.$$
(2.20)

We have (cf. [14], pg. 640):

$$2\operatorname{Re}\left((|v|^{r}v)_{y}\,\overline{v}_{yy}\right) = \frac{r}{2}\,|v|^{r-2}\,\frac{d}{dy}(v\overline{v}_{y}+\overline{v}v_{y})^{2}+|v|^{r}\,\frac{d}{dy}|v_{y}|^{2} \quad (2.21)$$
$$-r|v|^{r-2}\left(v|v_{y}|^{2}\overline{v}_{y}+\overline{v}|v_{y}|^{2}v_{y}\right).$$

Hence, by (2.20) and (2.21), we obtain, by applying the Gagliardo–Nirenberg inequality:

$$\varepsilon^{4} \frac{d}{dy} \int |v_{yy}|^{2} dz + \frac{1}{2} \varepsilon^{2} \frac{d}{dy} \int |v_{yz}|^{2} dz + \frac{1}{2} \varepsilon^{2} \frac{d}{dy} \int V |v_{y}|^{2} dz + \frac{\varepsilon^{2}}{8} \frac{d}{dy} \int |v|^{r-2} \left( \operatorname{Re}(v\overline{v}_{y}) \right)^{2} dz + \frac{\varepsilon^{2}}{4} \frac{d}{dy} \int |v|^{r} |v_{y}|^{2} dz \leq c \varepsilon^{2} \int |v|^{r-1} |v_{y}|^{3} dz \leq c \varepsilon^{2} \|v\|_{\infty}^{r-1} \|v_{y}\|_{2}^{5/2} \|v_{yz}\|_{2}^{1/2} \leq c \|v\|_{\infty}^{r-1} \left( \varepsilon^{2} \|v_{yz}\|_{2}^{2} \right)^{1/4} \|v_{y}\|_{2}^{5/2} \varepsilon^{3/2}.$$

Hence, in view of (2.15), (2.18), (2.11) and (2.19), we get

$$\varepsilon^{4} \int |v_{yy}|^{2} dz + \varepsilon^{2} \int |v_{yz}|^{2} dz + \varepsilon^{2} \int V|v_{y}|^{2} dz + \varepsilon^{2} \int |v|^{r-2} \left(\operatorname{Re}(v\overline{v}_{y}))^{2} dz + \frac{1}{2} \int |v_{y}|^{2} dz\right)$$

$$\leq c + \frac{1}{2} \left( \varepsilon^4 \| v_{yy} \|_2^2 \right) + c \int_0^y \| v_y \|_2^{5/2} \varepsilon^{3/2} \left( \varepsilon^2 \| v_{yz} \|_2^2 \right)^{1/4} d\tau + c \int_0^y \int | v_y |^2 dz \, d\tau.$$

Therefore, by (2.14), we obtain

$$\begin{aligned} &\frac{1}{2} \varepsilon^4 \int |v_{yy}|^2 dz + \varepsilon^2 \int |v_{yz}|^2 dz + \frac{1}{2} \int |v_y|^2 dz + \varepsilon^2 \int V |v_y|^2 dz \\ &\leq c + c \int_0^y \|v_y\|_2 \left(\varepsilon^2 \|v_{yz}\|_2^2\right)^{1/4} d\tau + c \int_0^y \int |v_y|^2 dz \, d\tau \\ &\leq c + c \int_0^y \int |v_y|^2 dz \, d\tau + c \int_0^y \left(\varepsilon^2 \|v_{yz}\|_2^2\right)^{1/2} d\tau \\ &\leq c + c \int_0^y \int |v_y|^2 dz \, d\tau + c \int_0^y \varepsilon^2 \int |v_{yz}|^2 dz \, d\tau + c \, y. \end{aligned}$$

We conclude that, by applying the Gronwall inequality, and for fixed T > 0, and  $y \in [0, T]$ ,

$$\varepsilon_p^2 \int |(v_p)_{yz}|^2 dz + \int |(v_p)_y|^2 dz \le c(T),$$
(2.22)

$$\varepsilon_p^4 \int |(v_p)_{yy}|^2 dz + \varepsilon_p^2 \int V |(v_p)_y|^2 dz \le c(T).$$
(2.23)

We have, in particular, from (2.14), (2.15), (2.17), (2.18), (2.22),

$$v_{p} \in L^{\infty}(\mathbb{R}_{+}; H^{1}), \quad V^{1/2}v_{p} \in L^{\infty}(\mathbb{R}_{+}; L^{2}),$$
  

$$(v_{p})_{y} \in L^{\infty}(]0, T[; L^{2}), \quad \varepsilon_{p}(v_{p})_{y} \in L^{\infty}(\mathbb{R}_{+}; L^{2}).$$
(2.24)

From (2.10) (cf. [14], pg. 642, for similar computations with  $V \equiv 0$ ) we deduce

$$\begin{split} \varepsilon_p^2 \frac{\partial^2 v_p}{\partial y^2} &- \varepsilon_q^2 \frac{\partial^2 v_q}{\partial y^2} - i \frac{\partial}{\partial y} (v_p - v_q) - \frac{1}{2} \frac{\partial^2}{\partial z^2} (v_p - v_q) \\ &+ \frac{1}{2} V(v_p - v_q) + \frac{1}{2} |v_p|^r v_p - \frac{1}{2} |v_q|^r v_q = 0. \end{split}$$

Multiplying the previous equation by  $\overline{v_p - \tilde{v}_q}$ , taking the imaginary part and integrating in z, we see that for any fixed T > 0 and all  $y \in [0, T]$ ,

$$\begin{split} \frac{d}{dy} \|v_p - v_q\|_2^2 &+ 2 \operatorname{Im} \int \left(\overline{v_p - v_q}\right) \left(\varepsilon_p^2 \frac{\partial^2 v_p}{\partial y^2} - \varepsilon_q^2 \frac{\partial^2 v_q}{\partial y^2}\right) dz \\ &= -\operatorname{Im} \int \left(\overline{v_p - v_q}\right) \left(|v_p|^r v_p - |v_q|^r v_q\right) dz, \\ \frac{d}{dy} \|v_p - v_q\|_2^2 &+ 2\varepsilon_p^2 \operatorname{Im} \int \left(\overline{v_p - v_q}\right) \left(\frac{\partial^2 v_p}{\partial y^2} - \frac{\partial^2 v_q}{\partial y^2}\right) dz \\ &+ 2(\varepsilon_p^2 - \varepsilon_q^2) \operatorname{Im} \int \left(\overline{v_p - v_q}\right) \frac{\partial^2 v_q}{\partial y^2} dz \\ &= \frac{d}{dy} \|v_p - v_q\|_2^2 + 2(\varepsilon_p^2 - \varepsilon_q^2) \frac{d}{dy} \operatorname{Im} \int \left(\overline{v_p - v_q}\right) \frac{\partial v_q}{\partial y} dz \end{split}$$

$$-2(\varepsilon_p^2 - \varepsilon_q^2) \operatorname{Im} \int \frac{d}{dy} \left(\overline{v_p - v_q}\right) \frac{\partial v_q}{\partial y} dz$$
$$= -\operatorname{Im} \int \left(\overline{v_p - v_q}\right) \left(|v_p|^r v_p - |v_q|^r v_q\right) dz.$$

Hence, we obtain

$$\begin{aligned} \frac{d}{dy} \|v_p - v_q\|_2^2 + 2(\varepsilon_p^2 - \varepsilon_q^2) \frac{d}{dy} \operatorname{Im} \int (\overline{v_p - v_q}) \frac{\partial v_q}{\partial y} dz \\ &\leq (\varepsilon_p^2 + \varepsilon_q^2) c(T) + \left( \|v_p\|_{\infty}^{r-1} + \|v_q\|_{\infty}^{r-1} \right) \|v_p - v_q\|_2^2 \\ &\leq c(T) \left(\varepsilon_p^2 + \varepsilon_q^2\right) + c \|v_p - v_q\|_2^2. \end{aligned}$$

For  $y \in [0, T]$ , we have

$$\|v_p(y) - v_q(y)\|_2^2 \le (\varepsilon_p^2 + \varepsilon_q^2) c(T) + c \int_0^y \|v_p(\tau) - v_q(\tau)\|_2^2 d\tau.$$

Applying Gronwall's inequality, we deduce that  $\{v_p\}$  is a Cauchy sequence in  $L^{\infty}(]0, T[; L^2(\mathbb{R}))$  and so, by a suitable diagonalization method, there exists a function  $\tilde{v} \in L^{\infty}_{\text{loc}}(\mathbb{R}_+; L^2(\mathbb{R}))$  and a subsequence  $v_p \xrightarrow[p \to \infty]{} \tilde{v}$  in  $L^{\infty}_{\text{loc}}(\mathbb{R}_+; L^2(\mathbb{R}))$ .

By the previous estimates, it is easy to prove that

$$\begin{split} \widetilde{v} &\in L^{\infty}_{\text{loc}}(\mathbb{R}_+; H^1(\mathbb{R})), \quad \widetilde{v}_y \in L^{\infty}_{\text{loc}}(\mathbb{R}_+; L^2(\mathbb{R})), \\ V^{1/2} \, \widetilde{v} &\in L^{\infty}(\mathbb{R}_+; L^2(\mathbb{R})), \quad \text{and so} \ \, \widetilde{v} \in C(\mathbb{R}_+; L^2(\mathbb{R})) \end{split}$$

By applying Aubin's Lemma (cf. [11]) there exists a subsequence  $v_p \xrightarrow{p \to \infty} \widetilde{v}$  a.e. in  $\mathbb{R}_+ \times \mathbb{R}$ . Hence,  $\widetilde{v}$  satisfies (2.12) in the sense of distributions and  $\widetilde{v} \in L^{\infty}_{\text{loc}}(\mathbb{R}_+; X)$ . Finally, by standard methods, it is easy to see that  $\widetilde{v}$  is the unique function with these properties that satisfies the Cauchy problem (2.12), and this achieves the proof of Theorem 2.3.

**Remark 2.1.** If, for  $\lambda > 0$ ,  $p \neq 1$ , u is the solution to the Cauchy problem for the equation (2.1) under the conditions in Theorem 2.2, we can multiply (2.1) by  $\frac{\partial \overline{u}}{\partial z}$ , then take the real part, and integrate over  $\mathbb{R}$  (in z),

$$0 = \operatorname{Re} \frac{d}{dy} \int \frac{\partial u}{\partial y} \frac{\partial \overline{u}}{\partial z} \, dz + \operatorname{Re} \int V u \, \frac{\partial \overline{u}}{\partial z} \, dz = \operatorname{Re} \frac{d}{dy} \int \frac{\partial u}{\partial y} \, \frac{\partial \overline{u}}{\partial z} \, dz - 2 \int V |u|^2 \, dz,$$

and so, by the energy conservation (2.6), we obtain

$$\int_0^y \int V|u|^2 \, dz \, d\tau \le c,\tag{2.25}$$

c independent of y > 0, and so we have the decay property

$$\int_{y}^{y+1} \int V|u|^2 \, dz \, d\tau \xrightarrow[y \to \infty]{} 0.$$

## 3. The periodic Goursat problem

In this section, we investigate the nonlinear Wheeler–DeWitt equation by following the approach and techniques developed in [1]. The difference is that, in our case, we have the following additional term in (1.7):

$$f(z,y)u$$
, with  $f(z,y) = m^2 y^2 e^{6z} - e^{4z} - c_p^2$ , (3.1)

where  $c_p = \frac{1}{2}(p-1)$  and u is complex valued. With (in this case z will be the "time" variable)

$$\Box u = \frac{\partial^2 u}{\partial z^2} - \frac{\partial^2 u}{\partial y^2} \quad \text{and} \quad g(u) = \lambda |u|^r u \tag{3.2}$$

the equation (1.7) can be rewritten as

$$\Box u + f(z, y) u + g(u) = 0.$$
(3.3)

As in [1], we introduce the characteristic cones

$$C_{z} = \{(\tau, y) \mid \tau = z + |y|, |y| \le \pi\}$$
(3.4)

and the functions  $\phi_+$ ,  $\phi_-$ ,  $\phi$ ,  $c_0(z)$  and  $c_{\pi}(z)$ , for a  $2\pi$  periodic (in y) solution u of equation (3.3), defined by

$$\begin{aligned}
\phi_{+}(z, y) &= u(z + y, y), \quad 0 \leq y \leq \pi, \\
\phi_{-}(z, y) &= u(z + y, -y), \quad 0 \leq y \leq \pi, \\
\phi(z, y) &= (\phi_{+}(z, y), \phi_{-}(z, y)), \\
c_{0}(z) &= u(z, 0) = \phi_{+}(z, 0) = \phi_{-}(z, 0), \\
c_{\pi}(z) &= u(z + \pi, \pi) = \phi_{+}(z, \pi) = \phi_{-}(z, \pi).
\end{aligned}$$
(3.5)

We then recall the following; see Lemma 1 in [1].

**Lemma 3.1.** If u is a  $C^2$  solution to the equation  $\Box u = h(z, y)$  on a neighborhood U of  $C_z$ , when h is a continuous function in U, then

$$\begin{split} \partial_{zy}^2 \phi_+(z,y) &= \frac{1}{2} \left( \partial_y^2 \phi_+(z,y) + h_+(z,y) \right), \\ \partial_{zy}^2 \phi_-(z,y) &= \frac{1}{2} \left( \partial_y^2 \phi_-(z,y) + h_-(z,y) \right), \end{split}$$

where  $h_+(z,y) = h(z+y,y), h_-(z,y) = h(z+y,-y), 0 \le y \le \pi$ .

Now, if u is a  $C^2$  function,  $2\pi$ -periodic in y, solution to (3.3), we can multiply by  $\frac{\partial \overline{u}}{\partial z}$ , take the real part, and integrate in y:

$$\frac{1}{2} \frac{\partial}{\partial z} \int_{-\pi}^{\pi} \left( \left| \frac{\partial u}{\partial z} \right|^2 + \left| \frac{\partial u}{\partial y} \right|^2 \right) dy + \frac{\lambda}{r+2} \frac{\partial}{\partial z} \int_{-\pi}^{\pi} |u|^{r+2} dy \\ + \frac{1}{2} \frac{\partial}{\partial z} \int_{-\pi}^{\pi} f(z, y) |u|^2 dy - \frac{1}{2} \int_{-\pi}^{\pi} \frac{\partial f}{\partial z}(z, y) |u|^2 dy = 0.$$
(3.6)

In addition, with z' = z + y, it is not difficult to deduce

$$\frac{1}{2} \int_{0}^{\pi} \left( |\partial_{y}\phi_{+}|^{2}(z,y) + |\partial_{y}\phi_{-}|^{2}(z,y) \right) dy$$

$$= \frac{1}{2} \int_{-\pi}^{\pi} \left( \left| \frac{\partial u}{\partial y} \right|^{2}(z',y) + \left| \frac{\partial u}{\partial z} \right|^{2}(z',y) \right) dy$$

$$+ \operatorname{Re} \int_{-\pi}^{\pi} \frac{\partial u}{\partial z}(z',y) \frac{\partial \overline{u}}{\partial y}(z',y) dy$$
(3.7)

and

$$\begin{split} \frac{\partial}{\partial z} \operatorname{Re} & \int_{-\pi}^{\pi} \frac{\partial u}{\partial z}(z', y) \frac{\partial \overline{u}}{\partial y}(z', y) \, dy \\ &= \operatorname{Re} \int_{-\pi}^{\pi} \frac{\partial^2 u}{\partial z^2}(z', y) \frac{\partial \overline{u}}{\partial y}(z', y) \, dy + \operatorname{Re} \int_{-\pi}^{\pi} \frac{\partial u}{\partial z}(z', y) \frac{\partial^2 \overline{u}}{\partial y \, \partial z}(z', y) \, dy \\ &= \operatorname{Re} \int_{-\pi}^{\pi} \left( \frac{\partial^2 u}{\partial y^2}(z', y) - f(z', y) \, u(z', y) - \lambda \, |u|^r \, u(z', y) \right) \frac{\partial \overline{u}}{\partial y}(z', y) \, dy \\ &= -\int_{-\pi}^{\pi} \left( f(z', y) \frac{1}{2} \frac{\partial}{\partial y} |u(z', y)|^2 - \frac{1}{r+2} \frac{\partial}{\partial y} |u|^{r+2}(z', y) \right) dy \\ &= \frac{1}{2} \int_{-\pi}^{\pi} \frac{\partial f}{\partial y}(z', y) \, |u(z', y)|^2 \, dy \\ &= \frac{1}{2} \int_{0}^{\pi} \frac{\partial f}{\partial y}(z', y) \, |\phi_+(z, y)|^2 \, dy + \frac{1}{2} \int_{0}^{\pi} \frac{\partial f}{\partial y}(z', -y) \, |\phi_-(z, y)|^2 \, dy. \end{split}$$
(3.8)

From (3.6), (3.7) and (3.8), with z' = z + y we deduce

$$\frac{1}{2} \frac{\partial}{\partial z} \int_{0}^{\pi} \left( |\partial_{y}\phi_{+}|^{2}(z,y) + |\partial_{y}\phi_{-}|^{2}(z,y) \right) dy \\
= -\frac{\lambda}{r+2} \frac{\partial}{\partial z} \int_{0}^{\pi} \left( |\phi_{+}|^{r+2}(z,y) + |\phi_{-}|^{r+2}(z,y) \right) dy \\
-\frac{1}{2} \frac{\partial}{\partial z} \int_{0}^{\pi} \left( f(z',y) |\phi_{+}|^{2}(z,y) + f(z',-y) |\phi_{-}|^{2}(z,y) \right) dy \quad (3.9) \\
+ \frac{1}{2} \int_{0}^{\pi} \left( \frac{\partial f}{\partial z}(z',y) |\phi_{+}|^{2}(z,y) + \frac{\partial f}{\partial z}(z',-y) |\phi_{-}|^{2}(z,y) \right) dy \\
+ \frac{1}{2} \int_{0}^{\pi} \left( \frac{\partial f}{\partial y}(z',y) |\phi_{+}|^{2}(z,y) + \frac{\partial f}{\partial y}(z',-y) |\phi_{-}|^{2}(z,y) \right) dy$$

and so, with z' = z + y,  $\tau' = \tau + y$ , we have

$$E(z) = \frac{1}{2} \int_0^{\pi} \left( |\partial_y \phi_+|^2(z, y) + |\partial_y \phi_-|^2(z, y) \right) dy + \frac{\lambda}{r+2} \int_0^{\pi} \left( |\phi_+|^{r+2}(z, y) + |\phi_-|^{r+2}(z, y) \right) dy + \frac{1}{2} \int_0^{\pi} \left( f(z', y) |\phi_+|^2(z, y) + f(z', -y) |\phi_-|^2(z, y) \right) dy$$
(3.10)

$$= E(0) + \frac{1}{2} \int_0^z \int_0^\pi \left( \frac{\partial f}{\partial z}(\tau', y) |\phi_+|^2(\tau, y) + \frac{\partial f}{\partial z}(\tau', -y) |\phi_-|^2(\tau, y) \right) dy dz$$
  
+ 
$$\frac{1}{2} \int_0^z \int_0^\pi \left( \frac{\partial f}{\partial y}(\tau', y) |\phi_+|^2(\tau, y) + \frac{\partial f}{\partial y}(\tau', -y) |\phi_-|^2(\tau, y) \right) dy d\tau,$$

and E(z) is the energy associated to our problem.

Recall that  $\phi(0, y) = (\phi_+(0, y), \phi_-(0, y)), 0 \le y \le \pi$  are the Goursat data  $(u(y, y), u(y, -y)), 0 \le y \le \pi$ . For each z, that is, for each cone  $C_z$ , in [1] it is introduced the Banach space  $(0 \le y \le \pi)$ :

$$H(C_z) = \left\{ \phi(z, \widehat{y}) = \left( \phi_+(z, \widehat{y}), \phi_-(z, \widehat{y}) \right) = \left( u(z + \widehat{y}, \widehat{y}), u(z + \widehat{y}, -\widehat{y}) \right) \right\}$$

with finite norm  $\|\phi(z,\cdot)\|_{H(C_z)}$ 

$$= \left( \int_0^\pi \left( |\partial_y \phi_+(z,y)|^2 + |\partial_y \phi_-(z,y)|^2 \right) dy \right)^{1/2} + |c_0(z)|$$
  
and such that  $c_0(z) = \phi_+(z,0) = \phi_-(z,0),$ 

$$c_{\pi}(z) = \phi_{+}(z,\pi) = \phi_{-}(z,\pi) \bigg\}.$$
 (3.11)

We have

$$H(C_z) \hookrightarrow (L^p(0,\pi))^2$$
, for  $1 \le p \le +\infty$ . (3.12)

Now, to solve the Goursat  $2\pi$ -periodic (in y) problem for the equation (3.3), with data

$$(u(y,y) = \phi_+(0,y), \quad u(y,-y) = \phi_-(0,y))$$

 $(0 \le y \le \pi)$  in  $H(C_0)$ , we follow closely the idea in Section 4 of [1], which reduces the problem to an abstract Cauchy form

$$\phi(z) = T_z \phi(0) - k_z (fu + g(u)),$$

with  $k_z$  linear with values in  $C_z$  defined by:

$$\begin{split} \phi &= (\phi_+, \phi_-), \quad \phi_+(0, 0) = \phi_-(0, 0), \quad \phi_+(0, \pi) = \phi_-(0, \pi), \\ \phi_+(z, y) &= u(z + y, y), \quad \phi_-(z, y) = u(z + y, -y), \\ (T_z \phi(0))(z, y) &= \left(\phi_+\left(0, \frac{z + 2y}{2}\right) + \phi_-\left(0, \frac{z}{2}\right) - c_0(0), \\ \phi_-\left(0, \frac{z + 2y}{2}\right) + \phi_+\left(0, \frac{z}{2}\right) - c_0(0)\right), \end{split}$$
for  $y \leq \pi - \frac{z}{2}$ 

$$(T_z\phi(0))(z,y) = \left(\phi_+\left(0,\frac{z+2y}{2}-\pi\right) + \phi_-\left(0,\frac{z}{2}\right) - 2c_0(0) + c_\pi(0), \phi_-\left(0,\frac{z+2y}{2}-\pi\right) + \phi_+\left(0,\frac{z}{2}\right) - 2c_0(0) + c_\pi(0)\right)$$

for  $\pi - \frac{z}{2} \le y \le \pi$ ,

where

$$c_{0}(z) = \phi_{+}\left(0, \frac{z}{2}\right) + \phi_{-}\left(0, \frac{z}{2}\right) - c_{0}(0),$$
  

$$c_{\pi}(z) = \phi_{+}\left(0, \frac{z}{2}\right) + \phi_{-}\left(0, \frac{z}{2}\right) - 2c_{0}(0) + c_{\pi}(0),$$
  

$$c_{0}(0) = \phi_{+}(0, 0) = \phi_{-}(0, 0), \quad c_{\pi}(0) = \phi_{+}(0, \pi) = \phi_{-}(0, \pi),$$

and, for a continuous function h(z, y),  $2\pi$ -periodic in y,

$$(k_{z}h)_{\pm}(y) = \int_{0}^{(z+2y)/2} \int_{0}^{z/2} h\left(p+q, \pm(p-q)\right) dq \, dp, \quad \text{for } y \le \pi - \frac{z}{2},$$
  

$$(k_{z}h)_{\pm}(y) = \int_{0}^{(z+2y)/2-\pi} \int_{\pi}^{y+\pi} h\left(p+q, \pm(p-q)\right) dq \, dp$$
  

$$+ \int_{0}^{\pi} \int_{0}^{z/2} h\left(p+q, \pm(p-q)\right) dq \, dp$$
  

$$+ \int_{\pi}^{(z+2y)/2} \int_{p-\pi}^{z/2} h\left(p+q, \pm(p-q)\right) dq \, dp, \quad \text{for } \pi - \frac{z}{2} \le y \le \pi.$$
  
(3.13)

Let us introduce, with  $C_{\tau}$  defined in (3.4),

$$D_z = \bigcup C_{\tau}, \quad \text{for } 0 \le \tau \le z.$$

For u continuous,  $2\pi$ -periodic in y, it is easy to see, cf. [1] and with c independent of  $z \in [0, \pi]$ ,

$$||k_z(fu+g(u))||_{H(z)} \le c||fu+g(u)||_{L^2(D_z)}.$$
(3.14)

Hence, by applying the estimate (8) in [1] and for all  $\phi$  satisfying (3.13) and  $z \in [0, \pi]$ , we find

$$\|\phi(z)\|_{H(C_z)} \le (1 + c\sqrt{z}) \|\phi(0)\|_{H(C_0)} + c \|fu + g(u)\|_{L^2(D_z)}.$$
(3.15)

Now, for a function  $\phi = (\phi_+, \phi_-)$  defined in  $C_z$  we say that  $\phi \in L^p(C_z)$ ,  $1 \le p \le +\infty$ , if  $\phi_+(z, \hat{y})$  and  $\phi_-(z, \hat{y})$  belong to  $L^p(0, \pi)$  and we put

$$\|\phi\|_{L^p(C_z)} = \|\phi_+(z,\widehat{y})\|_{L^p(0,\pi)} + \|\phi_-(z,\widehat{y})\|_{L^p(0,\pi)}.$$

We have  $\|\phi\|_{L^{\infty}(C_z)} \leq c \|\phi\|_{H(C_z)}$ , for  $\phi \in H(C_z)$ . By setting in (3.13),  $N_z(\phi) = -k_z(fu + g(u))$ , we want to prove the following result which is a variant of Theorem 2 in [1].

**Theorem 3.1.** If  $\phi(0) \in H(C_0)$ , then there is a  $z_0 \in (0,\pi)$ ] and a unique continuous function  $\phi(\hat{z}) = (\phi_+(\hat{z}), \phi_-(\hat{z})) : [0, z_0] \to \tilde{H}_1(0,\pi) = \{\phi = (\phi_+, \phi_-) \in H^1(0,\pi)^2 \mid \phi_+(0) = \phi_-(0), \phi_+(\pi) = \phi_-(\pi)\}$  such that

$$\phi(z) = T_z \phi(0) + N_z(\phi), \qquad z \in [0, z_0]. \tag{3.16}$$

*Proof.* Replacing an iteration method by a fixed point argument, we follow the lines of the proof of Theorem 2 in [1], which is a special case of the proof of

Theorem 13 in [2]. We have, with an increasing continuous function  $\theta \colon \mathbb{R} \to \mathbb{R}$  with  $\theta(0) = 1$ ,

$$\begin{aligned} \|N_{z}(\phi_{1}) - N_{z}(\phi_{2})\|_{L^{2}(0,\pi)} &\leq \theta(M) \|\phi_{1}(z) - \phi_{2}(z)\|_{\widetilde{H}^{1}(0,\pi)} \\ & \text{if } \|\phi_{1}(z)\|_{\widetilde{H}^{1}(0,\pi)}, \|\phi_{2}(z)\|_{\widetilde{H}^{1}(0,\pi)} \leq M(3.17) \end{aligned}$$

since  $H^1((0, 2\pi)) \hookrightarrow L^\infty((0, 2\pi)),$ 

$$||a|^r a - |b|^r b| \le c \left( |a|^{r-1} + |b|^{r-1} \right) |a-b|, \qquad a, b \in \mathbb{C},$$

and, in addition, we have, by (3.1), for  $z, y \in [0, \pi]$ ,

$$|f(z,y)| \le m^2 \pi^2 e^{6\pi} + e^{4\pi} + c_p^2.$$

For  $\phi \in C([0, z_0]; \widetilde{H}^1(0, \pi)$  let us define  $\widetilde{\phi} \in C([0, z_0], \widetilde{H}^1(0, \pi)$  by  $\widetilde{\phi}(z) = T_z \phi(0) + N_z(\phi), \qquad z \in [0, z_0].$ 

With  $\phi_i \in C([0, z_0]; \widetilde{H}^1(0, \pi), i = 1, 2, \phi_{i+}(z, \widehat{y}) = u_i(z + \widehat{y}, \widehat{y})$  and  $\phi_{i-}(z, \widehat{y}) = u_i(z + \widehat{y}, -\widehat{y})$ , in view of (3.14), (3.15), (3.17), with  $X_1 = C([0, z_0]; \widetilde{H}^1(0, \pi))$ , we find

$$\begin{split} \|\phi_{2} - \phi_{1}\|_{X_{1}} &\leq (1 + c\sqrt{z_{0}}) \|\phi_{2}(0) - \phi_{1}(0)\|_{\widetilde{H}^{1}(0,\pi)} \\ &+ c\,\theta(M) \int_{0}^{z_{0}} \|\phi_{2}(z) - \phi_{1}(z)\|_{\widetilde{H}^{1}(0,\pi)} \, dz \\ &\leq (1 + c\sqrt{z_{0}}) \|\phi_{2}(0) - \phi_{1}(0)\|_{\widetilde{H}^{1}(0,\pi)} + c\,\theta(M) \, z_{0} \, \|\phi_{1} - \phi_{2}\|_{X} \\ &\text{ if } \|\phi_{1}\|_{X_{1}}, \|\phi_{2}\|_{X_{1}} \leq M \quad (X_{1} \text{ endowed with the sup norm}). \\ (3.18) \end{split}$$

If we choose  $M \ge \|\phi_1(0)\|_{\widetilde{H}^1(0,\pi)} + 1$ , then from (3.18) with  $\phi_2 \equiv 0$ ,

$$\begin{aligned} \|\widetilde{\phi}_1\|_{X_1} &\leq (1 + c\sqrt{z_0}) \, \|\phi_1(0)\|_{\widetilde{H}^1(0,\pi)} + c\,\theta(M) \, z_0 \, M \\ &\leq (1 + c\sqrt{z_0}) \, (M-1) + c\,\theta(M) \, z_0 \, M \leq M \end{aligned}$$

for  $z_0 \leq z(M)$ .

From (3.18) we also derive, for  $\phi_1, \phi_2$  such that  $\phi_1(0) = \phi_2(0)$ ,

$$\|\widetilde{\phi}_2 - \widetilde{\phi}_1\|_{X_1} \le c\,\theta(M)\,z_0\,\|\phi_2 - \phi_1\|_{X_1} \le \frac{1}{2}\,\|\phi_2 - \phi_1\|_X$$

for  $z_0 \leq z_1(M)$ . Then, for  $z_0 \leq \min(z(M), z_1(M)))$ , the map  $\phi \to \tilde{\phi}$  is a strict contraction in the subspace

$$\left\{\phi \in C([0, z_0]; \widetilde{H}^1(0, \pi) / \phi(0) = \phi_1(0), \|\phi\|_{X_1} \le M\right\}$$

which is a Banach space. Hence, there is a unique fixed point, and the theorem is proved.  $\hfill \Box$ 

In order to prove a global (in z) existence result for the equation (3.16) we need to extend (3.10) which was proved for  $u \in C^2(D_{z_0})$  that is for  $\phi = (\phi_+, \phi_-) \in (C^2([0, \pi]))^2$ . In that case we must assume  $r \ge 2$  in (1.7), to extend Theorem 4 in [1] to our case:

**Theorem 3.2.** Assume the hypothesis of Theorem 3.1. Then the associated function u in  $C^2(D_{z_0})$  is a solution to equation (3.3) if and only if  $\phi_{\pm}(0) \in C^2([0,\pi])$  and satisfy the following nonlinear conditions:

$$\begin{aligned} \partial_y \phi_{\pm}(0,\pi) &- \partial_y \phi_{\pm}(0,0) + \int_0^{\pi} \left( f(y,y) \, \phi_{\mp}(0,y) + g(\phi_{\mp}(0,y)) \right) dy = 0, \\ \partial_y^2 \phi_{\pm}(0,\pi) &- \partial_y^2 \phi_{\pm}(0,0) \\ &= f(\pi,\pi) \, \phi_{\pm}(0,\pi) + g(\phi_{\pm}(0,\pi)) - f(0,0) \, \phi_{\pm}(0,0) - g(\phi_{\pm}(0,0)) \\ &- 2 \int_0^{\pi} \left( \frac{\partial f}{\partial z}(y,\mp y) \, \phi_{\mp}(0,y) + f(y,\mp y) \, \partial_z \phi_{\mp}(0,y) + \frac{\partial}{\partial z} g(\phi_{\mp}(0,y)) \right) dy. \end{aligned}$$
(3.19)

The proof of Theorem 3.2 is similar to the proof of Theorem 4 in [1]. In particular, for the second condition in (3.19) we must apply Lemma 3.1.

To prove that the solution  $\phi$  obtained in Theorem 3.1 is global in z, we must extend to  $\phi$  the energy formula (3.10), proved for  $\phi \in C^2$ . This can be made by an approximation method exactly as it was developed in the proof of Theorem 6 in [1]: we approximate  $\phi(0) \in H(C_0) = \tilde{H}^1(0,\pi)$  by a sequence  $\{\phi_{n\pm}(0)\} \in H(C_0) \cap C^2([0,\pi])$  satisfying conditions (3.19). The corresponding solutions  $\phi_n = (\phi_{n+}, \phi_{n-})$  satisfy (3.10) and, cf. a variant of Theorem 3 in [1], we obtain  $\|\phi_n(z) - \phi(z)\|_{\tilde{H}^1(0,\pi)} \xrightarrow[n \to \infty]{} 0$ . Hence, the energy formula (3.10) can be extended for  $\phi \in C([0, z_0]; \tilde{H}^1(0, \pi))$ .

Now, let  $\phi \in C([0, z_0]; \widetilde{H}^1(0, \pi)$  be the unique solution to (3.16) for a given  $\phi(0) \in \widetilde{H}^1(0, \pi)$ . Let u be the associated function such that  $\phi = (\phi_+, \phi_-)$ ,  $\phi_+(z, y) = u(z + y, y), \phi_-(z, y) = u(z + y, -y), y \in [0, \pi]$  and assume  $\lambda > 0$ . From (3.10) we deduce that

$$\frac{1}{2} \int_0^{\pi} \left( |\partial_y \phi_+|^2 + |\partial_y \phi_-|^2 \right) (z, y) \, dy + \frac{\lambda}{r+2} \int_0^{\pi} \left( |\phi_+|^{r+2} + |\phi_-|^{r+2} \right) (z, y) \, dy \\
\leq c(\varepsilon) + \varepsilon \int_0^{\pi} \left( |\phi_+|^{r+2} + |\phi_-|^{r+2} \right) (z, y) \, dy + E(0) \\
+ c z + c \int_0^z \int_0^{\pi} \left( |\phi_+|^{r+2} + |\phi_+|^{r+2} \right) (\tau, y) \, dy \, d\tau, \quad \text{for each } \varepsilon > 0.$$

We can choose  $\varepsilon < \frac{\lambda}{r+2}$  and, by applying Gronwall's inequality, it follows that

$$\frac{1}{2} \int_0^{\pi} \left( |\partial_y \phi_+|^2 + |\partial_y \phi_-|^2 \right) (z, y) \, dy \\ + \frac{\lambda}{r+2} \int_0^{\pi} \left( |\phi_+|^{r+2} + |\phi_-|^{r+2} \right) (z, y) \, dy \\ \le c(z),$$

c continuous in  $(0, +\infty)$ . Hence,  $\|\phi(z)\|_{\widetilde{H}^1(0,\pi)} \leq c_1(z), c_1$  continuous in  $(0, +\infty)$ . Hence, we can finally state the following result.

**Theorem 3.3.** Assume  $\lambda > 0$ . Let  $\phi_0 = (\phi_{0+}, \phi_{0-}) \in H(C_0) = \tilde{H}^1(0, \pi)$  and  $u_0$  its associated function such that  $\phi_{0+}(y) = u_0(y, y), \ \phi_{0-}(y) = u_0(y, -y),$ 

 $y \in (0,\pi)[$ . Then, there exists a unique function  $\phi \in C((0,+\infty); \widetilde{H}^1(0,\pi)$  such that

$$\phi(z) = T_z \phi_0 + N_z(\phi), \qquad \phi(0) = \phi_0, \quad z \ge 0,$$

and the associated function u(z, y) defined by

$$u(z+y,y) = \phi_+(z,y), \qquad u(z+y,-y) = \phi_-(z,y),$$

is a weak solution to the Goursat  $2\pi$ -periodic (in y) problem for the equation (3.3) in  $D = \{(\tau, y) \mid |y| \le \tau \le z + |y|, z \ge 0, |y| \le \pi\}$  and  $2\pi - D$  translations (with f replaced by  $f(\hat{z}, \theta(\hat{y}))$ , where  $\theta(\hat{y})$  is the  $2\pi$ -periodic extension of  $\hat{y}^2$ defined in  $[-\pi, \pi]$ ). In addition, if  $\phi_0 \in C^2([0, \pi])$ , then u is a classical solution to the Goursat  $2\pi$ -periodic (in y) problem for the equation (3.3) in the same domain.

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