Faster Compact Diffie–Hellman: Endomorphisms on the *x*-line

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Abstract. We describe an implementation of fast elliptic curve scalar multiplication, optimized for Diffie–Hellman Key Exchange at the 128bit security level. The algorithms are compact (using only *x*-coordinates), run in constant time with uniform execution patterns, and do not distinguish between the curve and its quadratic twist; they thus have a built-in measure of side-channel resistance. (For comparison, we also implement two faster but non-constant-time algorithms.) The core of our construction is a suite of two-dimensional differential addition chains driven by efficient endomorphism decompositions, built on curves selected from a family of \mathbb{Q} -curve reductions over \mathbb{F}_{p^2} with $p = 2^{127} - 1$. We include state-of-the-art experimental results for twist-secure, constant-time, *x*-coordinate-only scalar multiplication.

Keywords: Elliptic curve cryptography, scalar multiplication, twistsecure, side channel attacks, endomorphism, Kummer variety, addition chains, Montgomery curve.

1 Introduction

In this paper, we discuss the design and implementation of state-of-the-art Elliptic Curve Diffie–Hellman key exchange (ECDH) primitives for security level of approximately 128 bits. The major priorities for our implementation are

1. **Compactness:** We target x-coordinate-only systems. These systems offer the advantages of shorter keys, simple and fast algorithms, and (when properly designed) the use of arbitrary x-values, not just legitimate xcoordinates of points on a curve (the "illegitimate" values are x-coordinates on the quadratic twist). For x-coordinate ECDH, the elliptic curve exists only to supply formulæ for scalar multiplications, and a hard elliptic curve discrete logarithm problem (ECDLP) to underwrite a hard computational Diffie–Hellman problem (CDHP) on x-coordinates. The users should not have to verify whether given values correspond to points on a curve, nor should they have to compute any quantity that cannot be derived simply from x-coordinates alone. In particular, neither a user nor an algorithm should have to distinguish between the curve and its quadratic twist—and the curve must be chosen to be twist-secure.

2. Fast, constant-time execution: Every Diffie-Hellman key exchange is essentially comprised of four scalar multiplications,¹ so optimizing scalar multiplication $P \mapsto [m]P$ for varying P and m is a very high priority. At the same time, a minimum requirement for protecting against sidechannel timing attacks is that every scalar multiplication $P \mapsto [m]P$ must be computed in constant time (and ideally with the same execution pattern), regardless of the values of m and P.

Our implementation targets a security level of approximately 128 bits (comparable with Curve25519 [3], secp256r1 [12], and brainpoolP256t1 [11]). The reference system with respect to our desired properties is Bernstein's Curve25519, which is based on an efficient, uniform differential addition chain applied to a well-chosen pair of curve and twist presented as Montgomery models. These models not only provide highly efficient group operations, but they are optimized for x-coordinate-only operations, which (crucially) do not distinguish between the curve and its twist. Essentially, well-chosen Montgomery curves offer compactness straight out of the box.

Having chosen Montgomery curves as our platform, we must implement a fast, uniform, and constant-time scalar multiplication on their x-coordinates. To turbocharge our scalar multiplication, we apply a combination of efficiently computable pseudo-endomorphisms and two-dimensional differential addition chains. The use of efficient endomorphisms follows in the tradition of [21], [33], [16], and [15], but to the best of our knowledge, this work represents the first use of endomorphism scalar decompositions in the *pure* x-coordinate setting (that is, without additional input to the addition chain).

Our implementation is built on a curve-twist pair $(\mathcal{E}, \mathcal{E}')$ equipped with efficiently computable endomorphisms (ψ, ψ') . The family of Q-curve reductions in [32] offer a combination of fast endomorphisms and compatibility with fast underlying field arithmetic. Crucially (and unlike earlier endomorphism constructions such as [16] and [15]), they also offer the possibility of twist-secure group orders over fast fields. One of these curves, with almost-prime order over a 254-bit field, forms the foundation of our construction (see §2). Any other curve from the same family over the same field could be used with only very minor modifications to the formulæ below and the source code for our implementations; we explain our specific curve choice in Appendix A. The endomorphisms ψ and ψ' induce efficient pseudo-endomorphisms ψ_x and ψ'_x on the x-line; we explain their construction and use in §3.

¹ We do not count the cost of authenticating keys, etc., here. In the *static* Diffie-Hellman protocol, two of the scalar multiplications can be computed in advance; in this fixed-base scenario (where P is constant but m varies) one can profit from extensive precomputations. For simplicity, in this work we concentrate on the *dynamic* case (where P and m are variable).

The key idea of this work is to replace conventional scalar multiplications $(m, x(P)) \mapsto x([m]P)$ with multiscalar multiexponentiations

 $((a,b), x(P)) \longmapsto x([a]P \oplus [b]\psi(P)) \text{ or } x([a]P \oplus [b]\psi'(P)) ,$

where (a, b) is either a short multiscalar decomposition of a random full-length scalar m (that is, such that $[m]P = [a]P \oplus [b]\psi(P)$ or $[a]P \oplus [b]\psi'(P)$), or a random short multiscalar. The choice of ψ or ψ' formally depends on whether P is on \mathcal{E} or \mathcal{E}' , but there is no difference between ψ and ψ' on the level of xcoordinates: they are implemented using exactly the same formulæ. Since every element of the base field is the x-coordinate of a point on \mathcal{E} or \mathcal{E}' , we may view the transformation above as acting purely on field elements and not curve points.

From a practical point of view, the two crucial differences compared with conventional ECDH over a 254-bit field are

- 1. The use of 128-bit **multiscalars** (a, b) in \mathbb{Z}^2 in place of the 254-bit scalar m in \mathbb{Z} . We treat the geometry of multiscalars, the distribution of their corresponding scalar values, and the derivation of constant-bitlength scalar decompositions in §4.
- 2. The use of **two-dimensional differential addition chains** to compute $x([a]P \oplus [b]\psi(P))$ given only (a, b) and x(P). We detail this process in §5.

We have implemented three different two-dimensional differential addition chains: one due to Montgomery [24] via Stam [34], one due to Bernstein [4], and one due to Azarderakhsh and Karabina [1]. We provide implementation details and timings for scalar multiplications based on each of our chains in §6. Each offers a different combination of speed, uniformity, and constant-time execution. The differential nature of these chains is essential in the *x*-coordinate setting, which prevents the effective use of the vector chains traditionally used in the endomorphism literature (such as [35]).

A Magma implementation is publicly available at

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http://research.microsoft.com/en-us/downloads/ef32422a-af38-4c83-a033-a7aafbc1db55/
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and a complete mixed-assembly-and-C implementation is publicly available (in eBATS [8] format) at

http://hhisil.yasar.edu.tr/files/hisil20140318compact.tar.gz .

2 The Curve

We begin by defining our curve-twist pair $(\mathcal{E}, \mathcal{E}')$. We work over

 $\mathbb{F}_{p^2} := \mathbb{F}_p(i)$, where $p := 2^{127} - 1$ and $i^2 = -1$.

We chose this Mersenne prime for its compatibility with a range of fast techniques for modular arithmetic, including Montgomery- and NIST-style approaches. We build efficient \mathbb{F}_{p^2} -arithmetic on top of the fast \mathbb{F}_p -arithmetic described in [10].

In what follows, it will be convenient to define the constants

$$u := 1466100457131508421$$
, $v := \frac{1}{2}(p-1) = 2^{126} - 1$, $w := \frac{1}{4}(p+1) = 2^{125}$

The Curve \mathcal{E} and its Twist \mathcal{E}' . We define \mathcal{E} to be the elliptic curve over \mathbb{F}_{p^2} with affine Montgomery model

$$\mathcal{E}: y^2 = x(x^2 + Ax + 1)$$

where

$$A = A_0 + A_1 \cdot i \quad \text{with} \quad \begin{cases} A_0 = 45116554344555875085017627593321485421 \ A_1 = 2415910908 \ . \end{cases}$$

The element 12/A is not a square in \mathbb{F}_{p^2} , so the curve over \mathbb{F}_{p^2} defined by

$$\mathcal{E}': (12/A)y^2 = x(x^2 + Ax + 1)$$

is a model of the quadratic twist of \mathcal{E} . The twisting \mathbb{F}_{p^4} -isomorphism $\delta : \mathcal{E} \to \mathcal{E}'$ is defined by $\delta : (x, y) \mapsto (x, (A/12)^{1/2}y)$. The map $\delta_1 : (x, y) \mapsto (x_W, y_W) = (\frac{12}{A}x + 4, \frac{12^2}{A^2}y)$ defines an \mathbb{F}_{p^2} -isomorphism between \mathcal{E}' and the Weierstrass model

$$\mathcal{E}_{2,-1,s}: y_W^2 = x_W^3 + 2(9(1+si) - 24)x_W - 8(9(1+si) - 16)$$

of [32, Theorem 1] with

$$s = i(1 - 8/A^2) = 86878915556079486902897638486322141403$$

so \mathcal{E} is a Montgomery model of the quadratic twist of $\mathcal{E}_{2,-1,s}$. (In the notation of [32, §5] we have $\mathcal{E} \cong \mathcal{E}'_{2,-1,s}$ and $\mathcal{E}' \cong \mathcal{E}_{2,-1,s}$.) These curves all have *j*-invariant

$$j(\mathcal{E}) = j(\mathcal{E}') = j(\mathcal{E}_{2,-1,s}) = 2^8 \frac{(A^2 - 3)^3}{A^2 - 4} = 2^6 \frac{(5 - 3si)^3 (1 - si)}{(1 + s^2)^2}$$

Group Structures. Using the SEA algorithm [28], we find that

 $#\mathcal{E}(\mathbb{F}_{p^2}) = 4N$ and $#\mathcal{E}'(\mathbb{F}_{p^2}) = 8N'$

where

$$N = v^2 + 2u^2$$
 and $N' = 2w^2 - u^2$

are 252-bit and 251-bit primes, respectively. Looking closer, we see that

$$\mathcal{E}(\mathbb{F}_{p^2}) \cong (\mathbb{Z}/2\mathbb{Z})^2 \times \mathbb{Z}/N\mathbb{Z}$$
 and $\mathcal{E}'(\mathbb{F}_{p^2}) \cong \mathbb{Z}/2\mathbb{Z} \times \mathbb{Z}/4\mathbb{Z} \times \mathbb{Z}/N'\mathbb{Z}$

Recall that every element of \mathbb{F}_{p^2} is either the *x*-coordinate of two points in $\mathcal{E}(\mathbb{F}_{p^2})$, the *x*-coordinate of two points in $\mathcal{E}'(\mathbb{F}_{p^2})$, or the *x*-coordinate of one point of order two in both $\mathcal{E}(\mathbb{F}_{p^2})$ and $\mathcal{E}'(\mathbb{F}_{p^2})$. The *x*-coordinates of the points of exact order 2 in $\mathcal{E}(\mathbb{F}_{p^2})$ (and in $\mathcal{E}'(\mathbb{F}_{p^2})$) are 0 and $-\frac{1}{2}A \pm \frac{1}{2}\sqrt{A^2 - 4}$; the points of exact order 4 in $\mathcal{E}'(\mathbb{F}_{p^2})$ have *x*-coordinates ± 1 . Either of the points with *x*-coordinate 2 will serve as a generator for the cryptographic subgroup $\mathcal{E}(\mathbb{F}_{p^2})[N]$; either of the points with *x*-coordinate 2 - i generate $\mathcal{E}'(\mathbb{F}_{p^2})[N']$.

Curve Points, x-Coordinates, and Random Bitstrings. Being Montgomery curves, both \mathcal{E} and \mathcal{E}' are compatible with the Elligator 2 construction [5, §5]. For our curves, [5, Theorem 5] defines efficiently invertible injective maps $\mathbb{F}_{p^2} \to \mathcal{E}(\mathbb{F}_{p^2})$ and $\mathbb{F}_{p^2} \to \mathcal{E}'(\mathbb{F}_{p^2})$. This allows points on \mathcal{E} and/or \mathcal{E}' to be encoded in such a way that they are indistinguishable from uniformly random 254-bit strings. Since we work with x-coordinates only in this article, a square root is saved when computing the injection (see [5, §5.5] for more details).

The ECDLP on \mathcal{E} and \mathcal{E}' . Suppose we want to solve an instance of the DLP in $\mathcal{E}(\mathbb{F}_{p^2})$ or $\mathcal{E}'(\mathbb{F}_{p^2})$. Applying the Pohlig–Hellman–Silver reduction [25], we almost instantly reduce to the case of solving a DLP instance in either $\mathcal{E}(\mathbb{F}_{p^2})[N]$ or $\mathcal{E}'(\mathbb{F}_{p^2})[N']$. The best known approach to solving such a DLP instance is Pollard's rho algorithm [26], which (properly implemented) can solve DLP instances in $\mathcal{E}(\mathbb{F}_{p^2})[N]$ (resp. $\mathcal{E}'(\mathbb{F}_{p^2})[N']$) in around $\frac{1}{2}\sqrt{\pi N} \sim 2^{125.8}$ (resp. $\frac{1}{2}\sqrt{\pi N'} \sim 2^{125.3}$) group operations on average [9]. One might expect that working over \mathbb{F}_{p^2} would imply a $\sqrt{2}$ -factor speedup in the rho method by using Frobenius classes; but this seems not to be the case, since neither \mathcal{E} nor \mathcal{E}' is a subfield curve [36, §6].

The embedding degrees of \mathcal{E} and \mathcal{E}' with respect to N and N' are $\frac{1}{50}(N-1)$ and $\frac{1}{2}(N'-1)$, respectively, so ECDLP instances in $\mathcal{E}(\mathbb{F}_{p^2})[N]$ and $\mathcal{E}(\mathbb{F}_{p^2})[N']$ are not vulnerable to the Menezes–Okamoto–Vanstone [22] or Frey–Rück [14] attacks. The trace of \mathcal{E} is $p^2 + 1 - 4N \neq \pm 1$, so neither \mathcal{E} nor \mathcal{E}' are amenable to the Smart–Satoh–Araki–Semaev attack [27], [29], [30].

While our curves are defined over a quadratic extension field, this does not seem to reduce the expected difficulty of the ECDLP when compared with elliptic curves over similar-sized prime fields. Taking the Weil restriction of \mathcal{E} (or \mathcal{E}') to \mathbb{F}_p as in the Gaudry–Hess–Smart attack [18], for example, produces a simple abelian surface over \mathbb{F}_p ; and the best known attacks on DLP instances on simple abelian surfaces over \mathbb{F}_p offer no advantage over simply attacking the ECDLP on the original curve (see [31], [17], and [15, §9] for further discussion).

Superficially, \mathcal{E} is what we would normally call twist-secure (in the sense of Bernstein [3] and Fouque-Réal-Lercier-Valette [13]), since its twist \mathcal{E}' has a similar security level. Indeed, \mathcal{E} (and the whole class of curves from which it was drawn) was designed with this notion of twist-security in mind. However, twist-security is more subtle in the context of endomorphism-based scalar decompositions; we will return to this subject in §4 below.

The Endomorphism Ring. Let $\pi_{\mathcal{E}}$ denote the Frobenius endomorphism of \mathcal{E} . The curve \mathcal{E} is ordinary (its trace $t_{\mathcal{E}}$ is prime to p), so its endomorphism ring is an order in the quadratic field $K := \mathbb{Q}(\pi_{\mathcal{E}})$. (The endomorphism ring of an ordinary curve and its twist are always isomorphic, so what holds below for \mathcal{E} also holds for \mathcal{E}' .) We will see below that \mathcal{E} has an endomorphism ψ such that $\psi^2 = -[2]\pi_{\mathcal{E}}$. The discriminant of $\mathbb{Z}[\psi]$ is the fundamental discriminant

$$D_K = -8 \cdot 5 \cdot 397 \cdot 10528961 \cdot 6898209116497 \cdot 1150304667927101$$

of K, so $\mathbb{Z}[\psi]$ is the maximal order in K; hence, $\operatorname{End}(\mathcal{E}) = \mathbb{Z}[\psi]$.

The safecurves specification [7] suggests that the discriminant of the CM field should have at least 100 bits; our \mathcal{E} easily meets this requirement, since D_K has 130 bits. We note that well-chosen GLS curves can also have large CM field discriminants, but GLV curves have tiny CM field discriminants by construction: for example, the endomorphism ring of the curve secp256k1 [12] (at the heart of the Bitcoin system) has discriminant -3.

Brainpool [11] requires the ideal class number of K to be larger than 10^6 ; this property is never satisfied by GLV curves, which have tiny class numbers (typically ≤ 2) by construction. But \mathcal{E} easily meets this requirement: the class number of End(\mathcal{E}) is

 $h(\text{End}(\mathcal{E})) = h(D_K) = 2^7 \cdot 31 \cdot 37517 \cdot 146099 \cdot 505117 \sim 10^{19}$.

3 Efficient Endomorphisms on $\mathcal{E}, \mathcal{E}'$, and the x-line

Theorem 1 of [32] defines an efficient endomorphism

$$\psi_{2,-1,s}: (x_W, y_W) \longmapsto \left(\frac{-x_W^p}{2} - \frac{9(1-si)}{x_W^p - 4}, \frac{y_W^p}{\sqrt{-2}} \left(\frac{-1}{2} + \frac{9(1-si)}{(x_W^p - 4)^2}\right)\right)$$

of degree 2p on the Weierstrass model $\mathcal{E}_{2,-1,s}$, with kernel $\langle (4,0) \rangle$. To avoid an ambiguity in the sign of the endomorphism, we must fix a choice of $\sqrt{-2}$ in \mathbb{F}_{p^2} . We choose the "small" root:

$$\sqrt{-2} := 2^{64} \cdot i \;. \tag{1}$$

Applying the isomorphisms δ and δ_1 , we define efficient \mathbb{F}_{p^2} -endomorphisms

$$\psi := (\delta_1 \delta)^{-1} \psi_{2,-1,s} \delta_1 \delta$$
 and $\psi' := \delta \psi \delta^{-1} = \delta_1^{-1} \psi_{2,-1,s} \delta_1 \delta_1$

of degree 2p on \mathcal{E} and \mathcal{E}' , respectively, each with kernel $\langle (0,0) \rangle$. More explicitly: if we let

$$\begin{split} n(x) &:= \frac{A^p}{A} \left(x^2 + Ax + 1 \right) \ , \quad d(x) := -2x \ , \quad s(x) := n(x)^p / d(x)^p \ , \\ r(x) &:= \frac{A^p}{A} (x^2 - 1) \ , \quad \text{and} \quad m(x) := n'(x) d(x) - n(x) d'(x) \ , \end{split}$$

then ψ and ψ' are defined (using the same value of $\sqrt{-2}$ fixed in Eq. (1)) by

$$\psi: (x,y) \longmapsto \left(s(x) \ , \ \frac{-12^v}{A^v \sqrt{-2}} \frac{y^p m(x)^p}{d(x)^{2p}} \right)$$

and

$$\psi': (x,y) \longmapsto \left(s(x) \ , \ \frac{-12^{2\nu}\sqrt{-2}}{A^{2\nu}} \frac{y^p r(x)^p}{d(x)^{2p}}\right) \ .$$

Actions of the Endomorphisms on Points. Theorem 1 of [32] tells us that

$$\psi^2 = -[2]\pi_{\mathcal{E}}$$
 and $(\psi')^2 = [2]\pi_{\mathcal{E}'}$, (2)

where $\pi_{\mathcal{E}}$ and $\pi_{\mathcal{E}'}$ are the p^2 -power Frobenius endomorphisms of \mathcal{E} and \mathcal{E}' , respectively, and

$$P(\psi) = P(\psi') = 0$$
, where $P(T) = T^2 - 4uT + 2p$.

If we restrict to the cryptographic subgroup $\mathcal{E}(\mathbb{F}_{p^2})[N]$, then ψ must act as multiplication by an integer eigenvalue λ , which is one of the two roots of P(T)modulo N. Similarly, ψ' acts on $\mathcal{E}'(\mathbb{F}_{p^2})[N']$ as multiplication by one of the roots λ' of P(T) modulo N'. The correct eigenvalues are

$$\lambda \equiv -\frac{v}{u} \pmod{N}$$
 and $\lambda' \equiv -\frac{2w}{u} \pmod{N'}$.

Equation (2) implies that $\lambda^2 \equiv -2 \pmod{N}$ and $\lambda'^2 \equiv 2 \pmod{N'}$. (Note that choosing the other square root of -2 in Eq. (1) negates $\psi, \psi', \lambda, \lambda'$, and u.)

To complete our picture of the action of ψ on $\mathcal{E}(\mathbb{F}_{p^2})$ and ψ' on $\mathcal{E}'(\mathbb{F}_{p^2})$, we describe its action on the points of order 2 and 4 listed above:

Pseudo-endomorphisms on the x-line. One advantage of the Montgomery model is that it allows a particularly efficient arithmetic using only the x-coordinate. Technically speaking, this corresponds to viewing the x-line \mathbb{P}^1 as the Kummer variety of \mathcal{E} : that is, $\mathbb{P}^1 \cong \mathcal{E}/\langle \pm 1 \rangle$.

The x-line is not a group: if P and Q are points on \mathcal{E} , then x(P) and x(Q) determine the pair $\{x(P \oplus Q), x(P \oplus Q)\}$, but not the individual elements $x(P \oplus Q)$ and $x(P \oplus Q)$. However, the x-line inherits part of the endomorphism structure of \mathcal{E} : every endomorphism ϕ of \mathcal{E} induces a pseudo-endomorphism² $\phi_x : x \mapsto \phi_x(x)$ of \mathbb{P}^1 , which determines ϕ up to sign; and if ϕ_1 and ϕ_2 are two endomorphisms of \mathcal{E} , then

$$(\phi_1)_x(\phi_2)_x = (\phi_2)_x(\phi_1)_x = (\phi_1\phi_2)_x = (\phi_2\phi_1)_x$$
.

Montgomery's explicit formulæ for pseudo-doubling (DBL), pseudo-addition (ADD), combined pseudo-doubling and pseudo-addition (DBLADD) on \mathbb{P}^1 are available in [6]. In addition to these, we need expressions for both ψ_x and $(\psi \pm 1)_x$ to initialise the addition chains in §5. Moving to projective coordinates: write

² "Pseudo-endomorphisms" are true endomorphisms of \mathbb{P}^1 . We use the term pseudoendomorphism to avoid confusion with endomorphisms of elliptic curves, and to reflect the use of terms like "pseudo-addition" for basic operations on the *x*-line.

x = X/Z and y = Y/Z. Then the negation map on \mathcal{E} is $[-1] : (X : Y : Z) \mapsto (X : -Y : Z)$, and the double cover $\mathcal{E} \to \mathcal{E}/\langle [\pm 1] \rangle \cong \mathbb{P}^1$ is $(X : Y : Z) \mapsto (X : Z)$. The pseudo-doubling on \mathbb{P}^1 is

$$[2]_x((X:Z)) = \left((X+Z)^2 (X-Z)^2 : (4XZ) \left((X-Z)^2 + \frac{A+2}{4} \cdot 4XZ \right) \right) .$$
(3)

Our endomorphism ψ induces the pseudo-endomorphism

$$\psi_x((X:Z)) = \left(A^p \left((X-Z)^2 - \frac{A+2}{2}(-2XZ)\right)^p : A(-2XZ)^p\right)$$

Composing ψ_x with itself, we confirm that $\psi_x \psi_x = -[2]_x (\pi_{\mathcal{E}})_x$.

Proposition 1. With the notation above, and with $\sqrt{-2}$ chosen as in Eq. (1),

$$(\psi \pm 1)_x(x) = (\psi' \pm 1)_x(x)$$

= $\frac{2s^2 n d^{4p} - x(xn)^p m^{2p} A^{p-1}}{2s(x-s)^2 d^{4p} A^{p-1}} \mp \frac{m^p (xn)^{(p+1)/2} \sqrt{-2}}{A^{(p-1)/2} (x-s)^2 d^{2p}}$. (4)

Proof. If P and Q are points on a Montgomery curve $By^2 = x(x^2 + Ax + 1)$, then

$$x(P \pm Q) = \frac{B(x(P)y(Q) \mp x(Q)y(P))^2}{x(P)x(Q)(x(P) - x(Q))^2}$$

Taking P = (x, y) to be a generic point on \mathcal{E} (where B = 1), setting $Q = \psi(P)$, and eliminating y using $y^2 = -\frac{A^p}{2A}dn$ yields the expression for $(\psi \pm 1)_x$ above. The same process for \mathcal{E}' (with $B = \frac{12}{A}$), eliminating y with $\frac{12}{A}y^2 = -\frac{A^p}{2A}dn$, yields the same expression for $(\psi' \pm 1)_x$.

Deriving explicit formulæ to compute the pseudo-endomorphism images in Eq. (4) is straightforward. We omit these formulæ here for space considerations, but they can be found in our code online. If $P \in \mathcal{E}$, then on input of x(P), the combined computation of the three projective elements $(X_{\lambda-1}: Z_{\lambda-1})$, $(X_{\lambda}: Z_{\lambda})$, $(X_{\lambda+1}: Z_{\lambda+1})$, which respectively correspond to the three affine elements $x([\lambda-1]P), x([\lambda]P), x([\lambda+1]P)$, incurs 15 multiplications, 129 squarings and 10 additions in \mathbb{F}_{p^2} . The bottleneck of this computation is raising dn to the power of $(p+1)/2 = 2^{126}$, which incurs 126 squarings. We note that squarings are significantly faster than multiplications in \mathbb{F}_{p^2} .

4 Scalar Decompositions

We want to evaluate scalar multiplications [m]P as $[a]P \oplus [b]\psi(P)$, where

$$m \equiv a + b\lambda \pmod{N}$$

and the multiscalar (a, b) has a significantly shorter bitlength³ than m. For our applications we impose two extra requirements on multiscalars (a, b), so as to add a measure of side-channel resistance:

³ The bitlength of a scalar m is $\lceil \log_2 |m| \rceil$; the bitlength of a multiscalar (a, b) is $\lceil \log_2 ||(a, b)||_{\infty} \rceil$.

- 1. both a and b must be **positive**, to avoid branching and to simplify our algorithms; and
- 2. the multiscalar (a, b) must have **constant bitlength** (independent of m as m varies over \mathbb{Z}), so that multiexponentiation can run in constant time.

In some protocols—notably Diffie–Hellman—we are not interested in the particular values of our random scalars, as long as those values remain secret. In this case, rather than starting with m in $\mathbb{Z}/N\mathbb{Z}$ (or $\mathbb{Z}/N'\mathbb{Z}$) and finding a short, positive, constant-bitlength decomposition of m, it would be easier to randomly sample some short, positive, constant-bitlength multiscalar (a, b) from scratch. The sample space must be chosen to ensure that the corresponding distribution of values $a+b\lambda$ in $\mathbb{Z}/N\mathbb{Z}$ does not make the discrete logarithm problem of finding $a + b\lambda$ appreciably easier than if we started with a random m.

Zero Decomposition Lattices. The problems of finding good decompositions and sampling good multiscalars are best addressed using the geometric structure of the spaces of decompositions for \mathcal{E} and \mathcal{E}' . The multiscalars (a, b) such that $a + b\lambda \equiv 0 \pmod{N}$ or $a + b\lambda' \equiv 0 \pmod{N'}$ form lattices

$$\mathcal{L} = \langle (N,0), (-\lambda,1) \rangle$$
 and $\mathcal{L}' = \langle (N',0), (-\lambda',1) \rangle$,

respectively, with $a + b\lambda \equiv c + d\lambda \pmod{N}$ if and only if (a, b) - (c, d) is in \mathcal{L} (similarly, $a + b\lambda' \equiv c + d\lambda' \pmod{N'}$ if and only if (a, b) - (c, d) is in \mathcal{L}').

The sets of decompositions of m for $\mathcal{E}(\mathbb{F}_p)[N]$ and $\mathcal{E}(\mathbb{F}_{p^2})[N']$ therefore form lattice cosets

$$(m,0) + \mathcal{L}$$
 and $(m,0) + \mathcal{L}'$,

respectively, so we can compute short decompositions of m for $\mathcal{E}(\mathbb{F}_p)[N]$ (resp. $\mathcal{E}(\mathbb{F}_{p^2})[N']$) by subtracting vectors near (m, 0) in \mathcal{L} (resp. \mathcal{L}') from (m, 0). To find these vectors, we need $\|\cdot\|_{\infty}$ -reduced⁴ bases for \mathcal{L} and \mathcal{L}' .

Proposition 2 (Definition of $\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}'_1, \mathbf{e}'_2$). Up to order and sign, the shortest possible bases for \mathcal{L} and \mathcal{L}' (with respect to $\|\cdot\|_{\infty}$) are given by

$$\mathcal{L} = \langle \mathbf{e}_1 := (v, u) , \mathbf{e}_2 := (-2u, v) \rangle \quad and$$
$$\mathcal{L}' = \langle \mathbf{e}'_1 := (u, w) , \mathbf{e}'_2 := (2u - 2w, 2w - u) \rangle.$$

Proof. The proof of [32, Prop. 2] constructs sublattices

$$\langle \tilde{\mathbf{e}}_1 := -2(v, u), \tilde{\mathbf{e}}_2 := -2(2u, v) \rangle \subset \mathcal{L}$$

and

$$\langle \tilde{\mathbf{e}}'_1 := 2(2w, -u), \tilde{\mathbf{e}}'_2 := 4(u, w) \rangle \subset \mathcal{L}'$$

with $[\mathcal{L}: \langle \tilde{\mathbf{e}}_1, \tilde{\mathbf{e}}_2 \rangle] = 4$ and $[\mathcal{L}': \langle \tilde{\mathbf{e}}'_1, \tilde{\mathbf{e}}'_2 \rangle] = 8$. We easily verify that $\mathbf{e}_1 = -\frac{1}{2}\tilde{\mathbf{e}}_2$ and $\mathbf{e}_2 = -\frac{1}{2}\tilde{\mathbf{e}}_1$ are both in \mathcal{L} ; then, since $\langle \tilde{\mathbf{e}}_1, \tilde{\mathbf{e}}_2 \rangle$ has index 4 in $\langle \mathbf{e}_1, \mathbf{e}_2 \rangle$, we

⁴ Reduced with respect to Kaib's generalized Gauss reduction algorithm [20] for $\|\cdot\|_{\infty}$.

must have $\mathcal{L} = \langle \mathbf{e}_1, \mathbf{e}_2 \rangle$. Similarly, both $\mathbf{e}'_1 = \frac{1}{4}\tilde{\mathbf{e}}'_2$ and $\mathbf{e}'_2 = \frac{1}{2}(\tilde{\mathbf{e}}'_2 - \tilde{\mathbf{e}}'_1)$ are in \mathcal{L}' , and thus form a basis for \mathcal{L}' . According to [20, Definition 3], an ordered lattice basis $[\mathbf{b}_1, \mathbf{b}_2]$ is $\|\cdot\|_{\infty}$ -reduced if

$$\|\mathbf{b}_1\|_{\infty} \le \|\mathbf{b}_2\|_{\infty} \le \|\mathbf{b}_1 - \mathbf{b}_2\|_{\infty} \le \|\mathbf{b}_1 + \mathbf{b}_2\|_{\infty}$$
.

This holds for $[\mathbf{b}_1, \mathbf{b}_2] = [\mathbf{e}_2, -\mathbf{e}_1]$ and $[\mathbf{e}'_1, \mathbf{e}'_2]$, so $\|\mathbf{e}_2\|_{\infty}$ and $\|\mathbf{e}_1\|_{\infty}$ (resp. $\|\mathbf{e}'_1\|_{\infty}$ and $\|\mathbf{e}'_2\|_{\infty}$) are the successive minima of \mathcal{L} (resp. \mathcal{L}') by [20, Theorem 5].⁵

In view of Proposition 2, the fundamental parallelograms of \mathcal{L} and \mathcal{L}' are the regions of the (a, b)-plane defined by

$$\mathcal{A} := \{ (a,b) \in \mathbb{R}^2 : 0 \le vb - ua < N, \ 0 \le 2ub + va < N \} \text{ and} \\ \mathcal{A}' := \{ (a,b) \in \mathbb{R}^2 : 0 \le ub - wa < N', \ 0 \le (2u - 2w)b - (2w - u)a < N' \} ,$$

respectively. Every integer m has precisely one decomposition for $\mathcal{E}(\mathbb{F}_{p^2})[N]$ (resp. $\mathcal{E}'(\mathbb{F}_{p^2})[N']$) in any translate of \mathcal{A} by \mathcal{L} (resp. \mathcal{A}' by \mathcal{L}').

Short, Constant-Bitlength Scalar Decompositions. Returning to the problem of finding short decompositions of m: let (α, β) be the (unique) solution in \mathbb{Q}^2 to the system $\alpha \mathbf{e}_1 + \beta \mathbf{e}_2 = (m, 0)$. Since $\mathbf{e}_1, \mathbf{e}_2$ is reduced, the closest vector to (m, 0) in \mathcal{L} is one of the four vectors $\lfloor \alpha \rfloor \mathbf{e}_1 + \lfloor \beta \rfloor \mathbf{e}_2, \lfloor \alpha \rfloor \mathbf{e}_1 + \lceil \beta \rceil \mathbf{e}_2, [\alpha] \mathbf{e}_1 + \lfloor \beta \rceil \mathbf{e}_2, \alpha \rceil \mathbf{e}_1 + \lfloor \beta \rceil \mathbf{e}_2$ or $\lceil \alpha \rceil \mathbf{e}_1 + \lceil \beta \rceil \mathbf{e}_2$ by [20, Theorem 19]. Following Babai [2], we subtract $\lfloor \alpha \rceil \mathbf{e}_1 + \lfloor \beta \rceil \mathbf{e}_2$ from (m, 0) to get a decomposition (\tilde{a}, \tilde{b}) of m; by the triangle inequality, $\|(\tilde{a}, \tilde{b})\|_{\infty} \leq \frac{1}{2}(\|\mathbf{e}_1\|_{\infty} + \|\mathbf{e}_2\|_{\infty})$. This decomposition is approximately the shortest possible, in the sense that the true shortest decomposition is at most $\pm \mathbf{e}_1 \pm \mathbf{e}_2$ away. Observe that $\|\mathbf{e}_1\|_{\infty} = \|\mathbf{e}_2\|_{\infty} = 2^{126} - 1$, so (\tilde{a}, \tilde{b}) has bitlength at most 126.

However, \tilde{a} or b may be negative (violating the positivity requirement), or have fewer than 126 bits (violating the constant bitlength requirement). Indeed, $m \mapsto (\tilde{a}, \tilde{b})$ maps \mathbb{Z} onto $(\mathcal{A} - \frac{1}{2}(\mathbf{e}_1 + \mathbf{e}_2)) \cap \mathbb{Z}^2$. This region of the (a, b)-plane, "centred" on (0, 0), contains multiscalars of every bitlength between 0 and 126 and the majority of them have at least one negative component. We can achieve positivity and constant bitlength by adding a carefully chosen offset vector from \mathcal{L} , translating $(\mathcal{A} - \frac{1}{2}(\mathbf{e}_1 + \mathbf{e}_2)) \cap \mathbb{Z}^2$ into a region of the (a, b)-plane where every multiscalar is positive and has the same bitlength. Adding $3\mathbf{e}_1$ or $3\mathbf{e}_2$ ensures that the first or second component always has precisely 128 bits, respectively; but adding $3(\mathbf{e}_1+\mathbf{e}_2)$ gives us a constant bitlength of 128 bits in both. Theorem 1 makes this all completely explicit.

Theorem 1. Given an integer m, let (a, b) be the multiscalar defined by

 $a:=m+\left(3-\lfloor\alpha\rceil\right)v-2\left(3-\lfloor\beta\rceil\right)u\qquad and\qquad b:=\left(3-\lfloor\alpha\rceil\right)u+\left(3-\lfloor\beta\rceil\right)v\ ,$

⁵ For the Euclidean norm, the bases $[\mathbf{e}_1, \mathbf{e}_2]$ and $[\mathbf{e}'_1, 2\mathbf{e}'_1 - \mathbf{e}'_2]$ are $\|\cdot\|_2$ -reduced, but $[\mathbf{e}'_1, \mathbf{e}'_2]$ is not.

where α and β are the rational numbers

$$\alpha := (v/N)m$$
 and $\beta := -(u/N)m$.

Then $2^{127} < a, b < 2^{128}$, and $m \equiv a + b\lambda \pmod{N}$. In particular, (a, b) is a positive decomposition of m, of bitlength exactly 128, for any m.

Proof. We have $m \equiv a + b\lambda \pmod{N}$ because $(a, b) = (\tilde{a}, \tilde{b}) + 3(\mathbf{e}_1 + \mathbf{e}_2) \equiv (m, 0) \pmod{\mathcal{L}}$, where (\tilde{a}, \tilde{b}) is the translate of (m, 0) by the Babai roundoff $\lfloor \alpha \rceil \mathbf{e}_1 + \lfloor \beta \rceil \mathbf{e}_2$ described above. Now (\tilde{a}, \tilde{b}) lies in $\mathcal{A} - \frac{1}{2}(\mathbf{e}_1 + \mathbf{e}_2)$, so (a, b) lies in $\mathcal{A} + \frac{5}{2}(\mathbf{e}_1, \mathbf{e}_2)$; our claim on the bitlength of (a, b) follows because the four "corners" of this domain all have 128-bit components.

Random Multiscalars. As we remarked above, in a pure Diffie-Hellman implementation it is more convenient to simply sample random multiscalars than to decompose randomly sampled scalars. Proposition 3 shows that random multiscalars of at most 127 bits correspond to reasonably well-distributed values in $\mathbb{Z}/N\mathbb{Z}$ and in $\mathbb{Z}/N'\mathbb{Z}$, in the sense that none of the values occur more than one more or one fewer times than the average, and the exceptional values are in $O(\sqrt{N})$. Such multiscalars can be trivially turned into constant-bitlength positive 128-bit multiscalars—compatible with our implementation—by (for example) completing a pair of 127-bit strings with a 1 in the 128-th bit position of each component.

Proposition 3. Let $\mathcal{B} = [0, p]^2$; we identify \mathcal{B} with the set of all pairs of strings of 127 bits.

- 1. The map $\mathcal{B} \to \mathbb{Z}/N\mathbb{Z}$ defined by $(a, b) \mapsto a + b\lambda \pmod{N}$ is 4-to-1, except for $4(p - 6u + 4) \approx 4\sqrt{2N}$ values in $\mathbb{Z}/N\mathbb{Z}$ with 5 preimages in \mathcal{B} , and $8(u^2 - 3u + 2) \approx \frac{1}{5}\sqrt{N}$ values in $\mathbb{Z}/N\mathbb{Z}$ with only 3 preimages in \mathcal{B} .
- 2. The map $\mathcal{B} \to \mathbb{Z}/N'\mathbb{Z}$ defined by $(a,b) \mapsto a + b\lambda' \pmod{N'}$ is 8-to-1, except for $8u^2 \approx \frac{2}{7}\sqrt{N'}$ values with 9 preimages in \mathcal{B} .

Proof (Sketch). For (1): the map $(a, b) \mapsto a + b\lambda \pmod{N}$ defines a bijection between each translate of $\mathcal{A} \cap \mathbb{Z}^2$ by \mathcal{L} and $\mathbb{Z}/N\mathbb{Z}$. Hence, every m in $\mathbb{Z}/N\mathbb{Z}$ has a unique preimage (a_0, b_0) in $\mathcal{A} \cap \mathbb{Z}^2$, so it suffices to count $((a_0, b_0) + \mathcal{L}) \cap \mathcal{B}$ for each (a_0, b_0) in $\mathcal{A} \cap \mathbb{Z}^2$. Cover \mathbb{Z}^2 with translates of \mathcal{A} by \mathcal{L} ; the only points in \mathbb{Z}^2 that are on the boundaries of tiles are the points in \mathcal{L} . Dissecting \mathcal{B} along the edges of translates of \mathcal{A} and reassembling the pieces, we see that 8v - 24u + 20 < 4p multiscalars in \mathcal{B} occur with multiplicity five, $8u^2 - 24u + 16 < p/9$ with multiplicity three, and every other multiscalar occurs with multiplicity four. There are therefore $4N + (8v - 24u + 20) - (8u^2 - 24u + 16) = (p+1)^2$ preimages in total, as expected. The proof of (2) is similar to (1), but counting $((a, b) + \mathcal{L}') \cap \mathcal{B}$ as (a, b) ranges over \mathcal{A}' . **Twist-Security with Endomorphisms.** We saw in §2 that DLPs on \mathcal{E} and its twist \mathcal{E}' have essentially the same difficulty, while Proposition 3 shows that the real DLP instances presented to an adversary by 127-bit multiscalar multiplications are not biased into a significantly more attackable range. But there is an additional subtlety when we consider the fault attacks considered in [3] and [13]: If we try to compute [m]P for P on \mathcal{E} , but an adversary sneaks in a point P' on the twist \mathcal{E}' instead, then in the classical context the adversary can derive m after solving the discrete logarithm $[m \mod N']P'$ in $\mathcal{E}'(\mathbb{F}_{p^2})$. But in the endomorphism context, we compute [m]P as $[a]P \oplus [b]\psi(P)$, and the attacker sees $[a+b\lambda']P'$, which is not $[m \mod N']P'$ (or even $[a+b\lambda \mod N']P'$); we should ensure that the values $(a+b\lambda' \mod N')$ are not concentrated in a small subset of $\mathbb{Z}/N'\mathbb{Z}$ when (a, b) is a decomposition for $\mathcal{E}(\mathbb{F}_{p^2})[N]$. This can be achieved by a similar argument to that of Proposition 3: the map $\mathbb{Z}/N\mathbb{Z} \to \mathbb{Z}/N'\mathbb{Z}$ defined by $m \mapsto (a, b) \mapsto a+b\lambda' \pmod{N'}$ is a good approximation of a 2-to-1 mapping.

5 Two-Dimensional Differential Addition Chains

Addition chains are used to compute scalar multiplications using a sequence of group operations (or pseudo-group operations). A one-dimensional addition chain computes [m]P for a given integer m and point P; a two-dimensional addition chain computes $[a]P \oplus [b]Q$ for a given multiscalar (a, b) and points P and Q. In a differential addition chain, the computation of any ADD, $P \oplus$ Q, is always preceded (at some earlier stage in the chain) by the computation of its associated difference $P \oplus Q$. The simplest differential addition chain is the original one-dimensional "Montgomery ladder" [23], which computes scalar multiplications [m]P for a single exponent m and point P. Every ADD in the Montgomery ladder is in the form $[i]P \oplus [i+1]P$, so every associated difference is equal to P. Several two-dimensional differential addition chains have been proposed, targeting multiexponentiations in elliptic curves and other primitives; we suggest [4] and [34] for overviews.

In any two-dimensional differential chain computing $[a]P \oplus [b]Q$ for general Pand Q, the input consists of the multiscalar (a, b) and the three points P, Q, and $P \oplus Q$. The initial difference $P \oplus Q$ (or equivalently, the initial sum $P \oplus Q$) is essential to kickstart the chain on P and Q, since otherwise (by definition) $P \oplus Q$ cannot appear in the chain. As we noted in §1, computing this initial difference is an inconvenient obstruction to pure x-coordinate multiexponentiations on general input: the pseudo-group operations ADD, DBL, and DBLADD can all be made to work on x-coordinates (the ADD and DBLADD operations make use of the associated differences available in a differential chain), but in general it is impossible to compute the initial difference $x(P \oplus Q)$ in terms of x(P) and x(Q).

For our application, we want to compute $x([a]P \oplus [b]\psi(P))$ given inputs (a, b)and x(P). Crucially, we can compute $x(P \ominus \psi(P))$ as $(\psi - 1)_x(x(P))$ using Proposition 1; this allows us to compute $x([a]P \oplus [b]\psi(P))$ using two-dimensional differential addition chains with input $(a, b), x(P), \psi_x(x(P))$, and $(\psi - 1)_x(x(P))$. We implemented one one-dimensional differential addition chain (LADDER) and three two-dimensional differential addition chains (PRAC, AK, and DJB). We briefly describe each chain, with its relative benefits and drawbacks, below.

(Montgomery) LADDER Chains. We implemented the full-length onedimensional Montgomery ladder as a reference, to assess the speedup that our techniques offer over conventional scalar multiplication (It is also used as a subroutine within our two-dimensional PRAC chain). LADDER can be made constant-time by adding a suitable multiple of N to the input scalar.

(Two-dimensional) PRAC Chains. Montgomery [24] proposed a number of algorithms for generating differential addition chains that are often much shorter than his eponymous ladder. His one-dimensional "PRAC" routine contains an easily-implemented two-dimensional subroutine, which computes the double-exponentiation $[a]P \oplus [b]Q$ very efficiently. The downside for our purposes is that the chain is not *uniform*: different inputs (a, b) give rise to different execution patterns, rendering the routine vulnerable to a number of side-channel attacks. Our implementation of this chain follows Algorithm 3.25 of $[34]^6$: given a multiscalar (a, b) and points P, Q, and P - Q, this algorithm computes $d = \gcd(a, b)$ and $R = [\frac{a}{d}]P \oplus [\frac{b}{d}]Q$. To finish computing $[a]P \oplus [b]Q$, we write $d = 2^i e$ with $i \ge q$ and e odd, then compute $S = [2^i]R$ with i consecutive DBLs, before finally computing [e]S with a one-dimensional LADDER chain⁷.

AK Chains. Azarderakhsh and Karabina [1] recently constructed a twodimensional differential addition chain which offers some middle ground in the trade-off between uniform execution and efficiency. While it is less efficient than PRAC, their chain has the advantage that all but one of the iterations consist of a single DBLADD; this uniformity may be enough to thwart some simple side-channel attacks. The single iteration which does *not* use a DBLADD requires a separate DBL and ADD, and this slightly slower step can appear at different stages of the algorithm. The location of this longer step could leak some information to a side-channel adversary under some circumstances, but we can protect against this by replacing all of the DBLADDs with separate DBL and ADDs, incurring a very minor performance penalty. A more serious drawback for this chain is its variable length: the total number of iterations depends on the input multiscalar. This destroys any hope of achieving a runtime that is independent of the input. Nevertheless, depending on the physical threat model, this chain may still be a suitable alternative. Our implementation of this chain follows Algorithm 1 in [1].

DJB **Chains.** Bernstein gives the fastest known two-dimensional differential chain that is both fixed length and uniform $[4, \S 4]$. This chain is slightly slower

⁶ We implemented the binary version of Montgomery's two-dimensional PRAC chain, neglecting the ternary steps in [24, Table 4] (see also [34, Table 3.1]). Including these ternary steps could be significantly faster than our implementation, though it would require fast explicit formulæ for tripling on Montgomery curves.

 $^{^7}$ In practice d is very small, so there is little benefit in using a more complicated chain for this final step.

than the PRAC and AK chains, but it offers stronger resistance against many side-channel attacks.⁸ If the multiscalar (a, b) has bitlength ℓ , then this chain requires precisely $\ell - 1$ iterations, each of which computes one ADD and one DBLADD. In our context, Theorem 1 allows us to fix the number of iterations at 127. The execution pattern of the multiexponentiation is therefore independent of the input, and will run in constant time.

Operation Counts. Table 1 profiles the number of high-level operations required by each of our addition chain implementations on \mathcal{E} . We used the decomposition in Theorem 1 to guarantee positive constant-bitlength multiscalars. In situations where side-channel resistance is not a priority, and the AK or PRAC chain is preferable, variable-length decompositions could be used: these would give lower operation counts and slightly faster average timings.

Table 1. Pseudo-group operation counts per scalar multiplication on the *x*-line for the 2-dimensional DJB, AK and PRAC chains (using endomorphism decompositions) and the 1-dimensional LADDER. The counts for LADDER and DJB are exact; those for PRAC and AK are averages, with corresponding standard deviations, over 10^6 random trials (random scalars and points). In addition to the operations listed here, each chain requires a final \mathbb{F}_{p^2} -inversion to convert the result into affine form.

chain	dim. endomorphisms		# DBL		#ADD		#DBLADD	
		$\psi_x, (\psi \pm 1)_x$	av.	std. dev.	av.	std. dev.	av.	std. dev.
LADDER	. 1	_	1				253	
Djb	2	affine	1		128		127	
Ак	2	affine	1		1		179.6	6.7
Prac	2	projective	0.2	0.4	113.8	11.6	73.4	11.1

The LADDER and DJB chains offer some slightly faster high-level operations. In these chains, the "difference elements" fed into the ADDs are fixed; if these points are affine, then this saves one \mathbb{F}_{p^2} -multiplication for each ADD. In LADDER, the difference is always the affine x(P), so these savings come for free. In DJB, the difference is always one of the four values x(P), $\psi_x(x(P))$, or $(\psi \pm 1)_x(x(P))$, so a shared inversion is used to convert $\psi_x(x(P))$ and $(\psi \pm 1)_x(x(P))$ from projective to affine coordinates. While this costs one \mathbb{F}_{p^2} -inversion and six- \mathbb{F}_{p^2} multiplications, it saves 253 \mathbb{F}_{p^2} -inversions inside the loop.

6 Timings

Table 2 lists cycle counts for our implementations run on an Intel Core i7-3520M (Ivy Bridge) processor at 2893.484 MHz with hyper-threading turned off, overclocking ("turbo-boost") disabled, and all-but-one of the cores switched off in

⁸ It would be interesting to implement our techniques with Bernstein's non-uniform two-dimensional *extended-gcd* differential addition chain [4], which can outperform PRAC (though it "takes more time to compute and is not easy to analyse").

Table 2. Performance timings for four different implementations of compact, xcoordinate-only scalar multiplications targeting the 128-bit security level. Timings are given for the one-dimensional Montgomery LADDER, as well as the two-dimensional chains (DJB, AK and PRAC) that benefit from the application of an endomorphism and subsequent short scalar decompositions.

addition chain	dimension	uniform?	constant time?	cycles
LADDER	1	1	\checkmark	159,000
Djb	2	1	\checkmark	148,000
Ак	2	1	×	133,000
Prac	2	×	×	109,000

BIOS. The implementations were compiled with gcc 4.6.3 with the -O2 flag set and tested on a 64-bit Linux environment. Cycles were counted using the SUPERCOP toolkit [8].

The most meaningful comparison that we can draw is with Bernstein's Curve25519 software. Like our software, Curve25519 works entirely on the x-line, from start to finish; using the uniform one-dimensional Montgomery ladder, it runs in constant time. Thus, fair performance comparisons can only be made between his implementation and the two of ours that are also both uniform and constant-time: LADDER and DJB. Benchmarked on our hardware with all settings as above, Curve25519 scalar multiplications ran in 182,000 cycles on average. Looking at Table 2, we see that using the one-dimensional LADDER on the x-line of \mathcal{E} gives a factor 1.14 speed up over Curve25519, while combining an endomorphism with the two-dimensional DJB chain on the x-line of \mathcal{E} gives a factor 1.23 speed up over Curve25519.

While there are several other implementations targeting the 128-bit security level that give faster performance numbers than ours, we reiterate that our aim was to push the boundary in the arena of x-coordinate-only implementations.

Hamburg [19] has also documented a fast software implementation employing x-coordinate-only Montgomery arithmetic. However, it is difficult to compare Hamburg's software with ours: his is not available to be benchmarked, and his figures were obtained on the Sandy Bridge architecture (and manually scaled back to compensate for turbo-boost being enabled). Nevertheless, Hamburg's own comparison with Curve25519 suggests that a fair comparison between our constant-time implementations and his would be close.

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A How Was This Curve Chosen?

The curve-twist pair implemented in this paper was chosen from the family of degree-2 \mathbb{Q} -curve reductions with efficient endomorphisms (over \mathbb{F}_{p^2}) described in [32]. These curves are equipped with efficient endomorphisms, and the arithmetic properties of the family are not incompatible with twist-security.

We fixed $p = 2^{127} - 1$, a Mersenne prime; this p facilitates very fast modular arithmetic. Next, we chose a tiny nonsquare to define $\mathbb{F}_{p^2} = \mathbb{F}_p(i)$ with $i^2 = -1$; this makes for slightly faster \mathbb{F}_{p^2} -arithmetic, and much simpler formulæ. The most secure group orders for a Montgomery curve-twist pair $(\mathcal{E}, \mathcal{E}')$ over \mathbb{F}_{p^2} have the form $(\#\mathcal{E}, \#\mathcal{E}') = (4N, 8N')$ (or (8N, 4N')) with N and N' prime. The cofactor of 4 is forced by the existence of a Montgomery model, and then $p^2 \equiv 1$ (mod 8) forces a cofactor of 8 on the twist. The family in [32, §5] is parametrised by a free parameter s; each choice of s in \mathbb{F}_p yields a curve over \mathbb{F}_{p^2} , each in a distinct $\overline{\mathbb{F}}_p$ -isomorphism class. If the curve corresponding to s in \mathbb{F}_p has a Montgomery model $\mathcal{E} : BY^2 = X(X^2 + AX + 1)$ over \mathbb{F}_{p^2} , then $8/A^2 = 1 + si$. If we write $A = A_0 + A_1i$ with A_0 and A_1 in \mathbb{F}_p , then

$$A_0^4 + 2A_0^2A_1^2 + A_1^4 + 8(A_1^2 - A_0^2) = 0.$$
(5)

To optimise performance, we searched for parameter values s in \mathbb{F}_p yielding Montgomery representations with "small" coefficients: that is, where A_0 and A_1 could be represented as small integers. But in view of Eq. (5), for any small value of A_1 there are at most four corresponding possibilities for A_0 , none of which have any reason to be small (and vice versa). Given the number of curves to be searched to find a twist-secure pair, we could not expect to find a twistsecure curve with both A_0 and A_1 small. Our \mathbb{F}_{p^2} -arithmetic placed no preference on which of these two coefficients should be small, so we flipped a coin and restricted our search to s yielding A_1 with integer representations less than 2^{32} (occupying only one word on 32- and 64-bit platforms). The constant appearing in Montgomery's formulæ [23, p. 261] is (A+2)/4, so we also required the integer representation of A_1 to be congruent to 2 modulo 4.

Our search prioritised A_1 values whose integer representations had low signed Hamming weight, in the hope that multiplication by A_1 might be faster when computed via sequence of additions and shifts. We did not find any curve-twist pairs with optimal cofactors and A_1 of weight 1, 2, or 3, but we found ten such pairs with A_1 of weight 4. Three of these pairs had an A_1 of precisely 32 bits; the curve-twist pair in §2 corresponds to the *smallest* such A_1 . Although the low signed Hamming weight of A_1 did not end up improving our implementation, the small size of A_1 yielded a minor but noticeable speedup.

The takeaway message is that the construction in [32, $\S5$] is flexible enough to find a vast number of twist-secure curves over any quadratic extension field, to which all of the techniques in this paper can be directly applied (or easily adapted), regardless of how the parameter search is designed. Such curve-twist pairs can be readily found in a *verifiably random* manner, following, for instance, the method described in [11, $\S5$].