Efficient Computations of Irredundant Triangular Decompositions with the RegularChains Library

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Abstract. We present new functionalities that we have added to the REGULARCHAINS library in Maple to efficiently compute irredundant triangular decompositions. We report on the implementation of different strategies. Our experiments show that, for difficult input systems, the computing time for removing redundant components can be reduced to a small portion of the total time needed for solving these systems.

Keywords: REGULARCHAINS, quasi-component, inclusion test, irredundant triangular decomposition.

1 Introduction

Efficient symbolic solving of parametric polynomial systems is an increasing need in robotics, geometric modeling, stability analysis of dynamical systems and other areas. Triangular decomposition provides a powerful tool for these systems. However, for parametric systems, and more generally for systems in positive dimension, these decompositions have to face the problem of *removing redundant components*. This problem is not limited to triangular decompositions and is also an important issue in other symbolic decomposition algorithms such as those of [9,10] and in numerical approaches [7].

We study and compare different criteria and algorithms for deciding whether a quasi-component is contained in another. Then, based on these tools, we obtain several algorithms for removing redundant components in a triangular decomposition. We report on the implementation of these different solutions within the REGULARCHAINS library [5].

We have performed extensive comparisons of these approaches using well-known problems in positive dimension [8]. Our experiments show that, the removal of the redundant components is never a bottleneck. Moreover, we have developed a heuristic inclusion test which provides very good running time performances and which fails very rarely in detecting an inclusion. We believe that we have obtained an efficient solution for computing irredundant triangular decompositions.

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2 Inclusion Test of Quasi-components

In this section we describe our strategies for the inclusion test of quasicomponents based on the Regular Chains library. We refer to [1,6,5] for the notion of a regular chain, its related concepts, such as initial, saturated ideals, quasi-components and the related operations.

Let $T, U \subset \mathbb{K}[X]$ be two regular chains. Let h_T and h_U be the respective products of their initials. We denote by $\operatorname{sat}(T)$ the saturated ideal of T. We discuss how to decide whether the quasi-component W(T) is contained in W(U) or not. An unproved algorithms for this inclusion test is stated in [4]; it appeared not to be satisfactory in practice, since it is relying on normalized regular chains, which tend to have much larger coefficients that non-normalized regular chains as verified experimentally in [2] and formally proved in [3].

Proposition 1. The inclusion $W(T) \subseteq W(U)$ holds if and only if the following both statements hold

- (C_1) for all $p \in U$ we have $p \in \sqrt{\operatorname{sat}(T)}$,
- (C_2) we have $W(T) \cap V(h_U) = \emptyset$.

If sat(T) is radical, then condition (C_1) can be replaced by:

 (C'_1) for all $p \in U$ we have $p \in \operatorname{sat}(T)$,

which is easier to check. Checking (C_2) can be approached in different ways, depending on the computational cost that one is willing to pay. The REGULARCHAINS library provides an operation Intersect(p,T) returning regular chains T_1, \ldots, T_e such that we have

$$V(p) \cap W(T) \subseteq W(T_1) \cup \cdots \cup W(T_e) \subseteq V(p) \cap \overline{W(T)}.$$

A call to Intersect can be seen as relatively cheap, since Intersect(p, T) exploits the fact that T is a regular chain. Checking

$$(C_h)$$
 Intersect $(h_U, T) = \emptyset$,

is a good criterion for (C_2) . However, when $\operatorname{Intersect}(h_U, T)$ does not return the empty list, we cannot conclude. To overcome this limitation, we rely on Proposition 2 and the operation Triangularize of the Regular Chains library. For a polynomial system, Triangularize (F) returns regular chains T_1, \ldots, T_e such that $V(F) = W(T_1) \cup \cdots \cup W(T_e)$.

Proposition 2. The inclusion $W(T) \subseteq W(U)$ holds if and only if the following both statements hold

- (C_1) for all $p \in U$ we have $p \in \sqrt{\operatorname{sat}(T)}$,
- (C_2') for all $S \in \text{Triangularize}(T \cup \{h_U\})$ we have $h_T \in \sqrt{\text{sat}(S)}$.

This provides an effective algorithm for testing the inclusion $W(T) \subseteq W(U)$. However, the cost for computing Triangularize $(T \cup \{h_U\})$ is clearly higher than that for Intersect (h_U, T) , since the former operation cannot take advantage of the fact T is a regular chain.

3 Removing Redundant Components

Let $F \subset \mathbb{K}[X]$ and let $T = T_1, \ldots, T_e$ be a triangular decomposition of V(F), that is, a set of regular chains such that we have $V(F) = W(T_1) \cup \cdots \cup W(T_e)$. We aim at removing every T_i such that there exists T_j , with $i \neq j$ and $W(T_i) \subseteq W(T_j)$. Based on the results of Section 2, we have developed the following strategies for testing the inclusion $W(T) \subseteq W(U)$.

heuristics-no-split: It checks whether (C_1') and (C_h) hold. If both hold, $W(T) \subseteq W(U)$ has been established, otherwise no conclusions can be made. heuristically-with-split: It tests the conditions (C_1) and (C_h) . Checking (C_1) is achieved by means of the operation Regularize [5,6]: for a polynomial p and a regular chain T, Regularize (p,T) returns regular chains T_1, \ldots, T_e such that we have

- $-W(T) \subseteq W(T_1) \cup \cdots \cup W(T_e) \subseteq \overline{W(T)},$
- for each $1 \leq i \leq e$ the polynomial p is either 0 or regular modulo $\operatorname{sat}(T_i)$. Therefore, Condition (C_1) holds iff for all T_i returned by Regularize(p,T) we have $p \not\equiv 0 \mod \operatorname{sat}(T_i)$.
- certified: It checks conditions (C_1) and (C'_2) . If both hold, then $W(T) \subseteq W(U)$ has been established. If at least one of the conditions (C_1) or (C'_2) does not hold, then the inclusion $W(T) \subseteq W(U)$ does not hold either.

The following polynomial systems are well-known systems which can be found at [8]. For each of them, the zero set has dimension at least one. Table 1 and Table 2 report the number of components and running time of different approaches for these input systems, based on which we make the following observations:

- 1. The heuristic removal without split performs very well. First, for all examples, except sys 8, it discovers all redundant components. Second, for all examples, except sys 8, its running time is a relatively small portion of the solving time (third column of Table 1).
- 2. Theoretically, the heuristic removal with split can eliminate more *redundancies* than the other strategies. Indeed, it can discover that a quasi-component

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		Triai	ngularize	Certified		
Sys	Name	(No:	removal)	Proposition 2		
		# RC	time(s)	# RC	time(s)	
1	genLinSyst-3-2	20	1.684	17	1.182	
2 3	Butcher	15	9.528	7	0.267	
3	MacLane	161	12.733	27	7.144	
4	neural	10	14.349	4	8.948	
5	Vermeer	6	27.870	5	58.396	
6	Liu-Lorenz	23	29.044	16	121.793	
7	chemical	7	71.364	5	7.727	
8	Pappus	393	37.122	120	141.702	
9	Liu-Lorenz-Li	22	1796.622	9	96.364	
10	KdV572c11s21	41	8898.024	7	6.980	

Table 1. Triangularize without removal, certified removal

	Heuristic		Certification		Heuristic		Certification	
	(C_1') and (C_h)				(C_1) and (C_h)			
Sys	(without split)		(Deterministic)		(with split)		(Deterministic)	
	# RC	time(s)	$\sharp \ \mathrm{RC}$	time(s)	$\sharp \; \mathrm{RC}$	time(s)	$\sharp \; \mathrm{RC}$	time(s)
1	17	0.382	17	1.240	17	0.270	17	1.214
2	7	0.178	7	0.259	7	0.147	7	0.325
3	27	3.437	27	8.470	27	3.358	27	8.239
4	4	1.881	4	8.353	4	6.429	4	14.045
5	5	0.771	5	60.108	8	54.455	8	109.928
6	16	1.937	16	123.052	18	96.492	18	203.937
7	5	0.243	5	7.828	5	5.180	5	12.842
8	124	42.817	120	135.780	124	48.756	120	148.341
9	9	8.186	9	101.668	10	105.598	10	217.837
10	7	4.878	7	6.688	7	5.881	7	7.424

Table 2. Heuristic removal, without and with split, followed by certification

is contained in the union of two others, meanwhile these three components are pairwise noninclusive.

- 3. In practice, the heuristic removal with split does not discover more irredundant components than the heuristic removal without split, except for systems 5 and 6. However, the running time overhead is large.
- 4. The direct deterministic removal is also quite expensive on several systems (5, 6, 8). Unfortunately, the heuristic removal without split, used as precleaning process does not really reduce the cost of a certified removal.

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