

# Multi-feature Intensity Inhomogeneity Correction in MR Images

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**Abstract.** In MRI, image intensity inhomogeneity is an adverse phenomenon that increases inter-tissue overlapping and hampers quantitative analysis. This study provides a powerful fully automated intensity inhomogeneity correction method that makes no a priori assumptions on the image intensity distribution and is able to correct intensity inhomogeneity with high dynamics. Besides using intensity features, as in most of the existing methods, spatial image features are also incorporated into the correction algorithm. A force is computed in each image point so that distribution of multiple features will shrink in the direction of intensity feature. Extensive regularization of those forces produces smooth inhomogeneity correction estimate, which is gradually improved in an iterative correction framework. The method was tested on simulated and real MR images for which gold standard segmentations were available. The results showed that the method was successful on uniform as well as on low and highly dynamic intensity uniformity images.

## 1 Introduction

Image intensity inhomogeneity, also referred to as bias field, intensity nonuniformity or shading, is perceived as a smooth intensity variation across the image. In MRI, intensity inhomogeneity may be caused by a number of factors, such as poor radio frequency coil uniformity, static field inhomogeneity, radio frequency penetration, gradient-driven eddy currents, and overall patient anatomy and position [1, 2]. The problem is especially cumbersome because inhomogeneity depends on the measured object and therefore cannot be eliminated or reduced by scanner calibration. A common solution is to conduct retrospective inhomogeneity correction, which is a necessary pre-processing step in many automatic image analysis tasks, e.g. in segmentation or registration, and especially if quantitative analysis is the final goal.

The most intuitive approach for intensity inhomogeneity correction is image smoothing or homomorphic filtering [3, 4, 5]. These methods are based on the assumption that intensity inhomogeneity is a low frequency signal which can be suppressed by high pass filters. However, since the imaged objects themselves usually contain low frequencies, filtering methods often fail to produce meaningful correction. Iterative optimisation that maximises the frequency content of the distribution of tissue intensity has been proposed in [6]. Dawant *et al.* [7] manually selected some points inside white matter and estimated the bias field by fitting splines to the intensities of these points. Styner *et al.* [8] modelled each tissue simply by its

mean intensity value. A parametric bias field is fitted to the image in an iterative process, which requires initialisation in a form of class means and special masks that have to be defined for each type of images. Information minimisation technique [9] has proved to be very robust and accurate approach in which bias field is modelled by polynomials and applied to acquired image in an optimisation process. The method based on fuzzy C-means [10] minimises the sum of class membership function and the first and second order regularisation terms that ensure the smooth bias field. Ahmed *et al.* [11] used a fuzzy C-means algorithm and combined bias field with adaptive segmentation. Other segmentation-based methods use expectation-maximisation algorithm to compute the bias field from the residue image by either spatial filtering [12] or by weighted least-squares fit of the polynomial bias model [13]. These methods interleave classification and bias field estimation [12] and also the estimation of class-conditional intensity distribution [13] but require initialisation, which is not trivial and practical. Besides, the assumption on normality of intensity distribution of individual tissues may often not be valid, especially when correcting pathological data.

In this paper we propose a novel fully automated bias correction method that makes no assumption on the distribution of image intensities and provide non-parametric correction. As most of the existing methods, the method is based on intensity features but also additional spatial image features are incorporated to improve bias correction and to make it more dynamic.

## 2 Method

Corruption of intensity homogeneity in MR imaging is a multiplicative phenomenon that is most commonly described by the following model,

$$u(x) = v(x)s(x) + n(x), \quad (1)$$

in which the acquired image  $u(x)$  is a combination of the uncorrupted image  $v(x)$ , corrupted by the multiplicative bias field  $s(x)$ , and statistically independent noise  $n(x)$ . The problem of correction of intensity inhomogeneity is to estimate  $v(x)$ , given the acquired image  $u(x)$ .

The proposed method can be outlined in four steps:

- S1. Calculate probability distribution  $p(\cdot)$  of image features
- S2. Estimate the forces that will shrink  $p(\cdot)$  in the direction of intensity feature
- S3. Estimate the bias correction field
- S4. Perform partial correction and stop if predefined number of iterations is reached. Otherwise go to S1.

The above steps are described in more detail in the following sections.

## 2.1 Probability Distribution Calculation

Probability distribution of image features  $p(i,d)$  is determined by binning the intensities ( $i$ ) and the corresponding second spatial derivatives ( $d$ ) into a discrete two-dimensional feature space. Second derivatives are obtained by convoluting the original image by the Laplacian operator, which was implemented as a  $3 \times 3$  kernel and applied separately for each slice.

The purpose of using additional image features in a form of second derivatives is to additionally separate tissue clusters in the feature space [14]. This is especially important when image intensities are not enough discriminating features, i.e. when intensity distributions of distinct tissues overlap significantly. This adverse and unfortunately quite frequent phenomenon in MRI is the main source of error in segmentation and inhomogeneity correction methods.

## 2.2 Force Estimation

In order to obtain an estimation of forces  $F_x$  for each image point  $x$  that will shrink the probability distribution  $p(i,d)$  of an image  $u(x)$  in the direction of intensity feature  $i$ , we first define a global energy, say  $E$ , as a measure of probability distribution dispersion. For this purpose we use the Shannon entropy  $H$ ,

$$E = H(u(x)) = - \sum_{i,d} p(i,d) \log p(i,d). \quad (2)$$

The entropy  $H$  is usually computed as above by summation of the uncertainties  $\log p(i,d)$  in the feature space domain but since we are seeking a contribution of each image point  $x$  to the global entropy we will compute the entropy alternatively by summation of the uncertainties over the image domain  $x$  of a size  $X$ ,

$$E = H(u(x)) = - \frac{1}{X} \sum_x \log p(i(x), d(x)). \quad (3)$$

We can now derive point energy, say  $E_x$ , which is the contribution of each image point  $x$  to the global energy  $E$ ,

$$E_x = - \frac{1}{X} \log p(i(x), d(x)). \quad (4)$$

$E_x$  is, therefore, a contribution of image point  $x$  to the dispersion of probability distribution  $p(i,d)$ . Corresponding point force  $F_x$  that will shrink the probability distribution  $p(i,d)$  in the direction of intensity feature  $i$  can, thus, be obtained by deriving the point energy  $E_x$  over the intensities and changing the sign to plus,

$$F_x = \frac{1}{X} \frac{\partial}{\partial i} (\log p(i(x), d(x))). \quad (5)$$

Forces  $F_x$  are computed by a Sobel operator in the feature space for all feature pairs ( $i,d$ ) and then mapped to the points with corresponding features in the image space. The obtained forces can be viewed upon as votes for point intensity changes that would result in less disperse probability distribution.

### 2.3 Bias Correction Estimation

To control the speed of the iterative bias correction and to make it independent of the shape of feature probability distributions, point forces  $F_x$  are first normalized in magnitude. The normalized forces are then regularized in the image domain by a sufficiently wide Gaussian kernel  $g$ . This yields smooth field of normalized forces that is used to derive an estimation of multiplicative bias correction field  $s^{-1}(x)$ ,

$$s^{-1}(x) = 1 + \left( f \frac{F_x}{\mu(|F_x|)} \right) * g, \quad (6)$$

where  $\mu(|F_x|)$  denotes mean of absolute force,  $f$  a predefined magnitude of forces, and  $*$  a convolution. A degree of smoothness of bias correction field  $s^{-1}(x)$  is determined by the standard deviation  $\sigma_g$  of the Gaussian kernel  $g$ .

### 2.4 Partial Correction

Partial bias correction is performed in each iteration, say  $n^{\text{th}}$ , by applying bias correction field  $s^{-1}(x)$  to the input image  $u_n(x)$  so that mean intensity (brightness) and standard deviation (contrast) of the input image are preserved,

$$u_{n+1}(x) \leftarrow u_{\sigma}(x) + \mu(u_0(x)) - \mu(u_{\sigma}(x)), \quad u_{\sigma}(x) = u_n(x)s^{-1}(x) \frac{\sigma(u_0(x))}{\sigma(u_n(x)s^{-1}(x))}. \quad (7)$$

The size of partial correction depends on the predefined force magnitude  $f$  and the standard deviation  $\sigma_g$  that controls the regularization step, i.e. the smoothness of the bias correction field.

## 3 Results

Removal of background in MRI images is essential in nearly all methods because background represents air voxels that are not corrupted by the multiplicative bias field and would therefore hamper inhomogeneity correction of the neighbouring tissue voxels. To mask out dark air voxels we remove all voxels with intensities smaller than the predefined intensity threshold, which is the simplest and most commonly used approach [9, 6, 13].

To demonstrate and evaluate the performance of proposed method, we applied it to several simulated and real magnetic resonance images of the human brain.

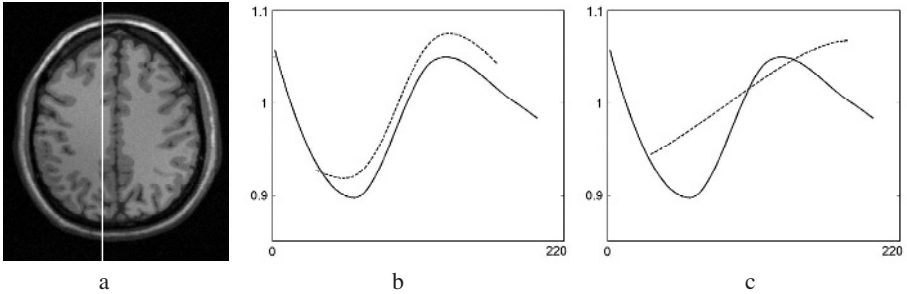
In the first set of images, variations of digital brain phantom acquired from Brainweb-MRI Simulator [15] were considered: six pairs of volumes with 3% Gaussian noise, including T1-, T2- and PD-modalities, normal and Multiple Sclerosis (MS) lesion cases. Each pair comprised shading free volume and its corrupted version with 40% intensity inhomogeneity. The resolutions were  $181 \times 217 \times 181$  voxels, sized  $1 \times 1 \times 1 \text{mm}^3$ .

In the second set of images, extra bias fields with higher degree of dynamics were added to the images from the first set. Bias fields were generated by cubic B-spline

interpolation between equally spaced nodes at every 50 voxels in each direction. Node values (multiplication factors) were randomly distributed on the interval between 0.8 and 1.2.

Third set consisted of six volumes, three of a normal volunteer (256×256×25 voxels 8bit) and three of a tumour patient (256×256×20 voxels, 8bit, slice thickness of 5mm, in plane resolution of 1×1mm). White and grey matter manual segmentations were available [16].

Volumes of the second set were used to show the capability of our method to successfully cope with bias fields, which have high degree of dynamics. Changing the size of the regularization kernel has a direct impact on the estimated fields. Reducing kernel size makes the fields more locally flexible, but loses a part of its regularization functionality. The effect of regularization kernel size on the shape of reconstructed bias field is shown in Fig. 1. Image (a) indicates the position of the bias field profiles shown on the images (b) and (c). Solid lines indicate generated bias field and broken lines the corresponding reconstruction after inhomogeneity correction. Standard deviations of the regularization kernels were set to 30 mm in case (b) and to 90 mm in case (c). In the first case high correlation between applied and reconstructed bias fields was found, while the in second case the correlation was poor due to too high regularization.



**Fig. 1.** Image (a) shows the profile position, (b) and (c) the applied (solid curve) and reconstructed bias field (broken curve) for the regularization of 30 and 90 mm, respectively

Quantitative evaluation was performed by computing the coefficient of joint variations ( $c_{jv}$ ) [9] between grey (GM) and white matter (WM) of the brain, which were segmented in all three sets of images.  $C_{jv}$  is computed from standard deviations ( $\sigma$ ) and mean values ( $\mu$ ) of the voxel intensities belonging to the two matters,

$$c_{jv}(GM, WM) = \frac{\sigma(GM) + \sigma(WM)}{|\mu(GM) - \mu(WM)|}. \quad (8)$$

The measure is independent of the changes in contrast and brightness and measures the intensity inhomogeneity in the sense of minimizing the intensity overlapping between two tissues.

In Table 1 the results of inhomogeneity correction in the first set of images are given. The four columns describe the volume properties (modality, bias field and pathology) and starting, final and ideal  $c_{jv}$  values. The method successfully corrected

the first six volumes and did not induce any artefacts into the second half of the inhomogeneity free volumes.

**Table 1.** Coefficient of joint variations of grey and white matter for the first dataset

Volume	$c_{jv\_start}[\%]$	$c_{jv\_end}[\%]$	$c_{jv\_ideal}[\%]$
T1 40%	69.3	51.7	51.6
T2 40%	106.4	83.4	83.2
PD 40%	163.0	62.8	64.9
T1 40% MS lesions	68.0	51.0	50.9
T2 40% MS lesions	123.8	74.5	74.9
PD 40% MS lesions	195.6	64.9	66.9
T1 0%	51.6	51.9	51.6
T2 0%	83.2	83.4	83.2
PD 0%	64.9	65.5	64.9
T1 0% MS lesions	50.9	51.2	50.9
T2 0% MS lesions	74.9	75.0	74.9
PD 0% MS lesions	66.9	67.7	66.9

**Table 2.** Coefficient of joint variations of grey and white matter for the second dataset

Volume (df – dynamic field)	$c_{jv\_start}[\%]$	$c_{jv\_end}[\%]$	$c_{jv\_ideal}[\%]$
T1 40% × df	86.8	51.7	51.6
T2 40% × df	107.7	84.5	83.2
PD 40% × df	228.5	64.7	64.9
T1 40% MS lesions × df	84.8	51.0	50.9
T2 40% MS lesions × df	128.1	75.8	74.9
PD 40% MS lesions × df	276.3	66.6	66.9
T1 0% × df	78.5	51.9	51.6
T2 0% × df	93.1	84.7	83.2
PD 0% × df	125.6	67.2	64.9
T1 0% MS lesions × df	76.6	51.2	50.9
T2 0% MS lesions × df	98.7	76.6	74.9
PD 0% MS lesions × df	141.8	69.4	66.9

The results of inhomogeneity correction in the second set of images are given in Table 2. The proposed method successfully corrected the inhomogeneities with high dynamics. Final  $c_{jv}$  values did not match the ideal ones as perfectly as in the first set, because the induced bias fields could not be exactly reconstructed by Gaussian convolution. Parameters were fixed for all experiments with  $f = 0.02$ ,  $\sigma_g = 30$  mm, number of iterations was 30. Size of the histogram was 256 ( $i$ ) by 400 ( $d$ ) bins.

Table 3 shows the results on real MR volumes of the third set. The volumes without intensity inhomogeneity were not known so that the extent of the achieved correction cannot be determined. The Last column states relative change of  $c_{jv}$  value, where it can be seen that improvement was achieved in all volumes.

**Table 3.** Coefficient of joint variations of grey and white matter for the real volumes

Volume	$cjv_{start}[\%]$	$cjv_{end}[\%]$	$cjv_{change}[\%]$
T1 normal	138.0	132.6	-3.9
T2 normal	90.7	89.0	-1.9
PD normal	77.8	70.4	-9.6
T1 tumour	175.7	169.4	-3.6
T2 tumour	169.3	159.6	-5.7
PD tumour	133.8	117.3	-12.4

## 4 Conclusion

The proposed fully automated bias correction method makes no assumption on the distribution of image intensities and provides non-parametric correction. No *a priori* knowledge such as digital brain atlases or reference points is needed. Spatial image features are incorporated in addition to commonly used intensity features, which give the method enough information to successfully correct even highly dynamic bias fields.

The method performed well on all tested images. The second set of images with artificially generated dynamic bias fields showed a possible advantage over many other methods that incorporate more rigid correction models. The performance of the proposed method depends on the overlap between the probability distributions of image features, which should be small. The proposed correction framework, however, enables straightforward incorporation of additional image features that could yield additional discriminative power and improve the correction performance on the images of poor quality.

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