

LOCAL BIFURCATION FOR THE FITZHUGH-NAGUMO SYSTEM

Carmen Rocsoreanu

Dept. of Math., University of Craiova, A.I. Cuza 13, Romania

carmenr@central.ucv.ro

Mihaela Sterpu

Dept. of Math., University of Craiova, A.I. Cuza 13, Romania

mihaelas@central.ucv.ro

Abstract The 2-D FitzHugh-Nagumo (F-N) system depending on three real parameters a, b , and c is considered. It models the electrical potential of the nodal system in the heart. All local bifurcations of equilibria are emphasized in three qualitatively distinct situations concerning the parameter c ($0 < c < 1, c = 1, c > 1$). We found codimension-one bifurcations (saddle-node, Hopf), codimension two bifurcations (Bogdanov-Takens, Bautin, cusp, double-zero with order two symmetry) and a codimension three bifurcation (degenerated Bogdanov-Takens of order two). In addition, some non-generic codimension two bifurcations generated by the coexistence of two codimension one bifurcations are shown. In our study we used the normal form theory [3], [6] and the center manifold theory [2].

Keywords: bifurcation, FitzHugh-Nagumo, normal form, center manifold.

Introduction

Starting with the Hodgkin-Huxley model [5] for nerve axon which consists of a Cauchy problem for a system of four first order ordinary differential equations (ODE), FitzHugh [4] constructed a two dimensional model, describing physiological phenomena that take place in the sinusal node of the heart. This node produces the initiation of the electrical impulse, so it has the role of pace-maker.

The model considered by FitzHugh [4] is the Cauchy problem for the system of ODE's

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$$\begin{cases} \frac{dx}{dt} = c \left(x + y + z - \frac{x^3}{3} \right), \\ \frac{dy}{dt} = -\frac{1}{c}(x - a + by), \end{cases} \quad (1)$$

where x is the electrical potential of the cell membrane, y is an auxiliary variable depending on the refractory period, the parameters a and b are related to the number of channels of the cell membrane which are opened to the Na^+ and K^+ ions, z is the injected current and $c \neq 0$ is the relaxation parameter.

For $a = b = z = 0$, the well-known Van der Pol system is obtained.

FitzHugh analyzed this model for some particular values of the parameters a , b , c and variable z , emphasizing the periods of the cardiac cycle.

In this paper we synthesize our results on local bifurcation around equilibria of the F-N model, for all values of the parameters. The system (1) is reduced to the form

$$\begin{cases} \dot{x} = c \left(x + \bar{y} - \frac{x^3}{3} \right), \\ \dot{\bar{y}} = -\frac{1}{c}(x - \bar{a} + b\bar{y}), \end{cases} \quad (2)$$

where $\bar{y} = y + z$, $\bar{a} = a + bz$. We rename the variables x , \bar{y} as x_1 and x_2 , and the parameter \bar{a} as a , so system (2) becomes

$$\begin{cases} \dot{x}_1 = c(x_1 + x_2 - x_1^3/3), \\ \dot{x}_2 = -\frac{1}{c}(x_1 + bx_2 - a), \end{cases} \quad (3)$$

As the system (3) is invariant with respect to the transformations $(x_1, x_2, a) \rightarrow (-x_1, -x_2, -a)$ and $(x_1, x_2, t, c) \rightarrow (x_1, x_2, -t, -c)$, it is sufficient to investigate the case $c > 0$, $a \geq 0$.

Since its derivation, the F-N system was widely investigated. In more particular or general settings it is a subject of many recent articles. The system has been analyzed within a particular parameter region relevant to physiology [4] and for full parameter space with emphasis on the periodic solutions [1]. A complete study on the phase dynamics and bifurcation of this model for $c > 1 + \sqrt{3}$ can be found in [7]. In [10], [12] codimension-one, -two, -three local bifurcations for the entire parameter space are determined.

1. Equilibria and linear stability

Denote by $D = \{ \mu = (b, a, c) \in \mathbf{R}^3, c \neq 0 \}$. For $\mu \in D$, denote by S_μ the set of equilibria of system (3) corresponding to μ . This set is defined by the equations

$$\begin{cases} x_1 + x_2 - \frac{1}{3}x_1^3 = 0, \\ x_1 + bx_2 - a = 0. \end{cases} \quad (4)$$

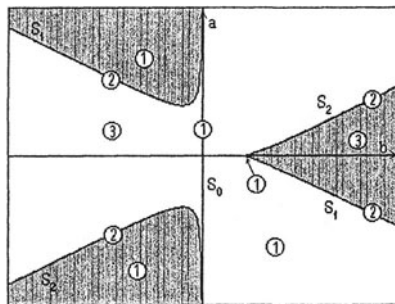


Figure 1. Section in static bifurcation values set with a $c = const.$ plane.

Let $f : \mathbf{R} \rightarrow \mathbf{R}$ be the function defined by $f(x_1) = x_1^3/3 - x_1$.

Remark 1. The correspondence $(x_1, x_2) \rightarrow (x_1, f(x_1))$ in \mathbf{S}_μ is bijective [7]. Therefore, the static bifurcation diagram of (3) is the set

$$\Sigma = \{(\mu, x_1), \mu \in D, \mathbf{x} = (x_1, x_2) \in \mathbf{S}_\mu\} \subset \mathbf{R}^4.$$

For $b = 0$, the system (4) possesses a unique solution, $x_1 = a, x_2 = a^3/3 - a$.

For $b \neq 0$, the abscissa x_1 of an equilibrium satisfies the following equation

$$x_1^3 - 3x_1(1 - \frac{1}{b}) - \frac{3a}{b} = 0. \tag{5}$$

Denote by $\Delta = 4(1 - \frac{1}{b})^3 - \frac{9a^2}{b^2}$ the discriminant of (5). Equation (5) possesses (i) three distinct real solutions $\xi_1 < \xi_2 < \xi_3$ if $\Delta > 0$, (ii) two distinct real solutions (one of them being double) if $\Delta = 0$, (iii) a unique real solution ξ_0 otherwise. The solution ξ_0 is triple for $b = 1, a = 0$ and single otherwise.

In the parameter space D , consider the surfaces

$$S_{1,2} : a = \pm \frac{2b}{3}(1 - \frac{1}{b})^{3/2}, b \in (-\infty, 0) \cup [1, \infty) \tag{6}$$

of parameters to which a double solution of equation (5) corresponds, and $S_0 : b = 0$. The static bifurcation diagram for the F-N system (3) consists of $S_1 \cup S_2 \cup S_0$. A section with a $c = const.$ plane in the static bifurcation diagram is represented in Figure 1., where the number of equilibria corresponding to each strata is shown.

Remark 2. For $\mu \in S_1 \cup S_2$ we have $\xi_1 = -2\sqrt{1 - \frac{1}{b}}, \xi_2 = \xi_3 = \sqrt{1 - \frac{1}{b}}$, for $b < 0$, and $\xi_1 = \xi_2 = -\sqrt{1 - \frac{1}{b}}, \xi_3 = 2\sqrt{1 - \frac{1}{b}}$, for $b \geq 1$.

Consider a parameter $\mu \in D$ and $\bar{x} = (\xi, f(\xi)) \in S_\mu$. The matrix associated with the linearized system around \bar{x} reads

$$M_\mu(\bar{x}) = \begin{pmatrix} c(1 - \xi^2) & c \\ -\frac{1}{c} & -\frac{b}{c} \end{pmatrix}, \tag{7}$$

and the characteristic equation is

$$\lambda^2 - \lambda \left[c(1 - \xi^2) - \frac{b}{c} \right] - b(1 - \xi^2) + 1 = 0. \tag{8}$$

Denote by λ_1, λ_2 the corresponding eigenvalues.

The topological type of the hyperbolic equilibria is given by the signature of the determinant $\det M_\mu(\bar{x}) = 1 - b(1 - \xi^2)$ and of the trace $tr M_\mu(\bar{x}) = c(1 - \xi^2) - b/c$. Consider the sets Γ_1 and Γ_2 from the (b, a, c, x_1) space, defined by

$$\Gamma_1 = \{(\mu, x_1), |x_1| = \Gamma_1(b, c), a \geq 0, c > 0, b \leq c^2\}, \tag{9}$$

and

$$\Gamma_2 = \{(\mu, x_1), |x_1| = \Gamma_2(b), a \geq 0, c > 0, b \in (-\infty, 0) \cup [1, \infty)\}, \tag{10}$$

where $\Gamma_1(b, c) = \sqrt{1 - b/c^2}$ and $\Gamma_2(b) = \sqrt{1 - 1/b}$. With these notations we have $\det M_\mu(\bar{x}) = 0$ if and only if $(\mu, \xi) \in \Gamma_2$ and $tr M_\mu(\bar{x}) = 0$ if and only if $(\mu, \xi) \in \Gamma_1$.

In the non-hyperbolic case, if $\text{Re}(\lambda_1)$ and/or $\text{Re}(\lambda_2)$ vanish, nonlinear terms are to be considered in order to determine the topological type of \bar{x} .

Sections in the sets Γ_1 and Γ_2 with a plane $c = \text{const.}$, $a = \text{const.}$ are given in Figures 2, 3, 4, for a $c < 1$, $c = 1$, and $c > 1$, respectively. The distinction was made by the number of intersections $\Gamma_1 \cap \Gamma_2$ in such a plane. Namely, for $c < 1$, $\Gamma_1 \cap \Gamma_2$ consists of two points (denoted by Q_1, Q_4), for $c = 1$, of three points (denoted by Q_1, Q_4, Q) and for $c > 1$ of four points ($Q_{1,2,3,4}$). In Figures 2, 3, 4, we have $tr M_\mu(\bar{x}) > 0$ and $\det M_\mu(\bar{x}) > 0$ in region I, $\det M_\mu(\bar{x}) < 0$ in region II, and $tr M_\mu(\bar{x}) < 0$ and $\det M_\mu(\bar{x}) > 0$ in region III. Consequently, this corresponds to the regions where the sign of $\text{Re} \lambda_{1,2}$ is preserved.

Remark 3. In Fig. 2, equilibria $\bar{x} = (\xi, f(\xi)) \in S_\mu$ with $(\mu, \xi) \in \Gamma_1$ situated between Q_1 and Q_4 have $\text{Re} \lambda_1 = \text{Re} \lambda_2 = 0$, $\lambda_{1,2} \in \mathbf{C} - \mathbf{R}$, so these equilibria are candidates for Hopf bifurcation. The same conclusion is valid for points situated between Q_1 and Q or Q_4 and Q on Γ_1 in Fig. 3, and for points between Q_1 and Q_2 or Q_3 and Q_4 on Γ_1 in Fig. 4.

Remark 4. In Figures 2, 3, 4, for equilibria $\bar{x} = (\xi, f(\xi)) \in S_\mu$ with $(\mu, \xi) \in \Gamma_2$ we have $\det M_\mu(\bar{x}) = 0$, hence at least one of the eigenvalues $\lambda_{1,2}$ is zero. Such equilibria are candidates for saddle-node bifurcation.

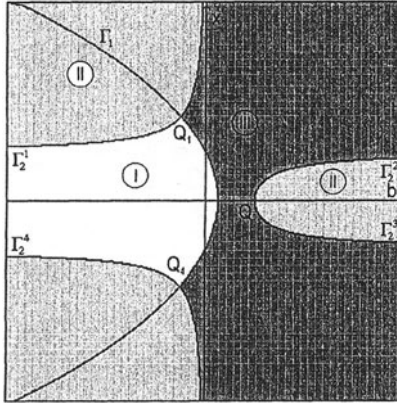


Figure 2. The regions in the (b, x_1) plane where the sign of $\text{Re } \lambda_{1,2}$ is preserved, if $c \in (0, 1)$: (I) $\text{Re } \lambda_1 > 0, \text{Re } \lambda_2 > 0$; (II) $\text{Re } \lambda_1 < 0, \text{Re } \lambda_2 > 0$, (III) $\text{Re } \lambda_1 < 0, \text{Re } \lambda_2 < 0$.

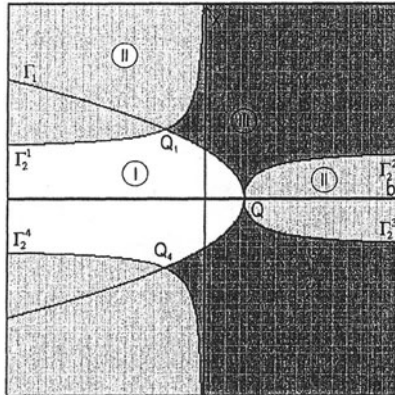


Figure 3. The regions in the (b, x_1) plane where the sign of $\text{Re } \lambda_{1,2}$ is preserved, if $c = 1$: (I) $\text{Re } \lambda_1 > 0, \text{Re } \lambda_2 > 0$; (II) $\text{Re } \lambda_1 < 0, \text{Re } \lambda_2 > 0$, (III) $\text{Re } \lambda_1 < 0, \text{Re } \lambda_2 < 0$.

Remark 5. Equilibria $\bar{x} = (\xi, f(\xi)) \in S_\mu$ with $(\mu, \xi) \in Q_i, i = 1, 4$, have $\lambda_1 = \lambda_2 = 0$, so they are candidates for a double zero bifurcation.

The projection of the set $\Sigma \cap \Gamma_1$ on the (b, a, c) space is the set $H_1 \cup H_2$, where

$$H_{1,2} : a = \pm \frac{1}{3c^3} (3c^2 - b^2 - 2bc^2) \sqrt{c^2 - b}. \tag{11}$$

Only the branches of Γ_1 with $b \in (-c, c)$ for $c > 1$ or $b \in (-c, c^2]$ for $c \leq 1$ separates regions with different signs of $\text{Re } \lambda_{1,2}$, so only these branches will be considered in the following.

The projection of $\Sigma \cap \Gamma_2$ on the (b, a, c) space is the set $S_1 \cup S_2$, given by (7).

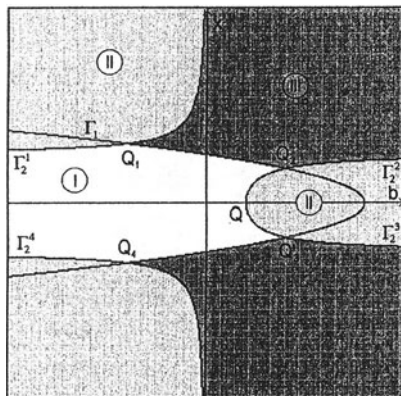


Figure 4. The regions in the (b, x_1) plane where the sign of $\text{Re } \lambda_{1,2}$ is preserved, if $c > 1$: (I) $\text{Re } \lambda_1 > 0, \text{Re } \lambda_2 > 0$; (II) $\text{Re } \lambda_1 < 0, \text{Re } \lambda_2 > 0$, (III) $\text{Re } \lambda_1 < 0, \text{Re } \lambda_2 < 0$.

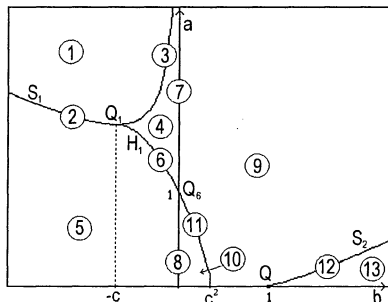


Figure 5. Section in the surfaces $H_{1,2} \cup S_{1,2}$ with a $c = \text{const.}$ plane, $c \in (0, 1)$.

The intersection of $H_1 \cup H_2$ with a $c = \text{const.}$ plane depends significantly on c . We found three typical cases, corresponding to $c < 1$, $c = 1$, $c > 1$, respectively. They are qualitatively illustrated in Figures 5, 6, 7. The curves of intersection of the surfaces H_1, H_2, S_1, S_2 with a $c = \text{const.}$ plane where denoted in the same way as the corresponding surfaces. In every plane $c = \text{const.}$, at the intersection points Q_i , $i = 1, 4$, the curves $H_1 \cup H_2$ and $S_1 \cup S_2$ cuts tangentially. Consider also the points $Q_6 = H_1 \cap S_0$ and, for $c > 1$, $Q_0 = H_1 \cap H_2$, $Q_5 = H_1 \cap S_2$.

Taking into account the sign of $\text{Re } \lambda_{1,2}$ established in Figures 2, 3, 4, in Figures 5, 6, 7 the type of hyperbolic equilibria is emphasized. Thus, we have:

- for (b, a) situated in region 1: a saddle \times ;
- for (b, a) situated in region 4: two saddles and an attractor \times, \bullet, \times ;
- for (b, a) situated in region 5: two saddles and a repulsor \times, \circ, \times ;
- for (b, a) situated in region 7, 9: an attractor \bullet ;

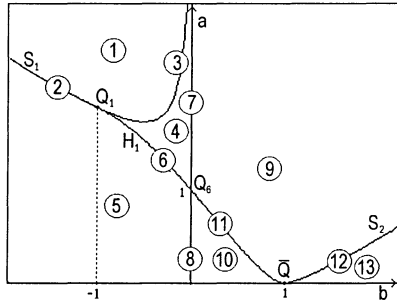


Figure 6. Section in the surfaces $H_{1,2} \cup S_{1,2}$ with a $c = const.$ plane, $c = 1$.

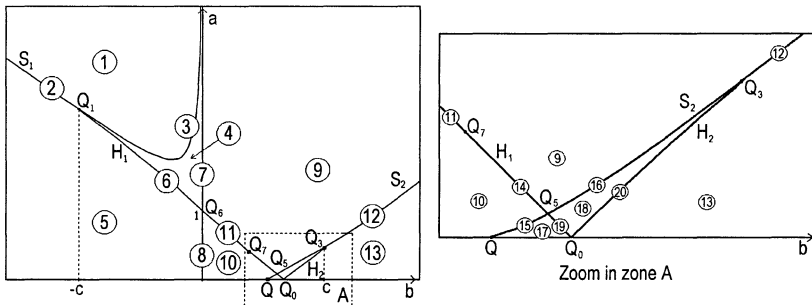


Figure 7. Section in the surfaces $H_{1,2} \cup S_{1,2}$ with a $c = const.$ plane, $c > 1$.

- for (b, a) situated in region 8, 10: a repulsor \circ ;
- for (b, a) situated in region 13: two attractors and a saddle \bullet, \times, \bullet ;
- for (b, a) situated in region 17: two repulsors and a saddle \circ, \times, \circ ;
- for (b, a) situated in region 18: a repulsor, a saddle and an attractor \circ, \times, \bullet .

In these regions the system possesses only hyperbolic equilibria. We also found the topological type (hyperbolic or not) for the other regions. Namely, we have:

- for (b, a) situated in the regions 2, 3 or at Q_1 : a saddle and a non-hyperbolic equilibrium \times, \square ;
- for (b, a) situated at Q_5 : two non-hyperbolic equilibria \square, \square ;
- for (b, a) situated in region 6: two saddles and a non-hyperbolic equilibrium \times, \square, \times ;
- for (b, a) situated in regions 11, 14, at Q_6 or at Q : a non-hyperbolic equilibrium \square ;
- for (b, a) situated in region 15: a non-hyperbolic equilibrium and a repulsor \square, \circ ;

- for (b, a) situated in regions 12, 16 or at Q_3 : a non-hyperbolic equilibrium and an attractor \square, \bullet ;
- for (b, a) situated at Q_0 : two non-hyperbolic equilibria and a saddle \square, \times, \square ;
- for (b, a) situated in region 19: a repulsor, a saddle and a non-hyperbolic equilibrium \circ, \times, \square ;
- for (b, a) situated in region 20: a non-hyperbolic equilibrium, a saddle and an attractor \square, \times, \bullet .

The topological type of the non-hyperbolic equilibria is established in Section 2.

2. Local bifurcation

For each non-hyperbolic equilibria we found the topological normal form. This allowed us to establish the topological type of non-hyperbolic equilibria and the local bifurcation generated by their presence.

2.1. Saddle-node bifurcation

Consider $\mu \in S_1 \cup S_2 - \{(b, a, c), b = \pm c\}$ and $\bar{x} = (\xi, f(\xi)) \in S_\mu$ with $\xi^2 = 1 - \frac{1}{b}$. Thus, for the equilibrium \bar{x} we have $\lambda_1 = \frac{c^2 - b^2}{bc} \neq 0$ and $\lambda_2 = 0$

First, assume $b \neq 1$. Hence $\xi \neq 0$. Using certain changes of coordinates [7], [11], system (3) is topologically equivalent with the following system

$$\begin{cases} \dot{y}_1 = \lambda_1 y_1 + \frac{2c^2 \xi}{\lambda_1} y_1 y_2 + O(|\mathbf{y}|^3), \\ \dot{y}_2 = -\frac{\xi b^2}{\lambda_1} y_2^2 + O(|\mathbf{y}|^3), \end{cases} \quad (12)$$

which is the normal form for a non-degenerated saddle-node equilibrium. The bifurcation corresponding to such parameters is a codimension-one saddle-node bifurcation. The local dynamics around such an equilibrium is deduced using the center manifold theorem. As the center manifold for system (12) is given by $y_1 = 0$, up to third order terms, the flow on the center manifold is determined by

$$\dot{y}_2 = -\frac{\xi b^2}{\lambda_1} y_2^2 + O(|y_2|^3).$$

Thus, for $b \in (-\infty, -c) \cup (\min\{1, c\}, c)$ the equilibrium \bar{x} possesses three repulsive directions and an attractive one, while for $b \in (-c, 0) \cup (\max\{1, c\}, \infty)$ the equilibrium \bar{x} possesses three attractive directions and a repulsive one.

If $b = 1$ then $a = 0$ and $\xi = 0$ is the abscissa of the triple equilibrium. In this case, if $c \neq 1$ we have $\lambda_1 \neq 0$. Using appropriate transformations

[7], [12], system (3) is written as

$$\begin{cases} \dot{y}_1 = \lambda_1 y_1 - \frac{c^2}{\lambda_1} y_1 y_2^2 + O(|\mathbf{y}|^4), \\ \dot{y}_2 = \frac{1}{3\lambda_1} y_2^3 + O(|\mathbf{y}|^4), \end{cases} \tag{13}$$

which represents the topological normal form for a simple degenerated saddle-node equilibrium. The bifurcation corresponding to these parameters is a cusp bifurcation.

The flow on the center manifold $y_1 = 0$ is given by [10]

$$\dot{y}_2 = \frac{1}{3\lambda_1} y_2^3 + O(|\mathbf{y}|^4).$$

Therefore, the equilibrium $\bar{\mathbf{x}}$ is a weakly attractive degenerated saddle-node if $c < 1$ and a weakly repulsive degenerated saddle-node if $c > 1$.

2.2. Hopf bifurcation

Consider $\mu \in H_1 \cup H_2$ such that $b \in (-c, c^2]$ as $c < 1$ and $b \in (-c, c)$ as $c \geq 1$. In these cases the F-N system possesses an equilibrium $\bar{\mathbf{x}} = (\xi, f(\xi)) \in S_\mu$ with $\xi^2 = 1 - \frac{b}{c^2}$, for which $\lambda_{1,2} \in \mathbf{C} - \mathbf{R}$ and $\text{Re}\lambda_1 = \text{Re}\lambda_2 = 0$.

Using a sequence of transformations and making the computations in the complex field [7], system (3) is reduced, around a point \mathbf{x} near the equilibrium $\bar{\mathbf{x}}$, to its normal form:

$$\frac{dw}{d\theta} = (\gamma(\alpha) + i)w + l_1(\alpha)w^2\bar{w} + l_2(\alpha)w^3\bar{w}^2 + O(|w|^6), \tag{14}$$

where $l_1(\alpha)$ and $l_2(\alpha)$ are the first and the second Liapunov coefficients, respectively, and were computed in [7], [9]. For $\alpha = \mu$ and $\mathbf{x} = \bar{\mathbf{x}}$ we have $l_1 = \frac{-b^2 + 2bc^2 - c^2}{2c\sqrt{1 - \frac{b^2}{c^2}}}$ and $l_2 = \frac{10b^2(b - c^2)}{144c\sqrt{1 - \frac{b^2}{c^2}}}$ if $l_1 = 0$ [11].

Note that $l_1 = 0$ iff $b = b^* = c^2 - c\sqrt{c^2 - 1}$. Consequently, (i) if $c \leq 1$, or $c > 1$ and $b \neq b^*$, then $l_1 \neq 0$, hence $\bar{\mathbf{x}}$ is a non-degenerated Hopf equilibrium and a codimension-one Hopf bifurcation takes place; (ii) if $c > 1$ and $b = b^*$ then $l_1 = 0$ and $l_2 \neq 0$, hence $\bar{\mathbf{x}}$ is a degenerated Hopf equilibrium of order two.

Denote by $Q_7(b^*, a^*, c)$ the corresponding point of H_1 . In the last case, a Bautin bifurcation takes place and from the point Q_7 emerge the curves of non-hyperbolic limit cycle bifurcation values, which is approximated asymptotically, near Q_7 , by the curve Ba defined by the equation

$$l_2 l_1^2 + 4 \frac{\text{Re}\lambda}{\text{Im}\lambda} = 0$$

deduced in [7], [9].

2.3. Bogdanov-Takens bifurcation

Consider $\mu \in (H_1 \cup H_2) \cap (\dot{S}_1 \cap S_2)$, with $|b| = c$, and $\bar{x} = (\xi, f(\xi)) \in S_\mu$ with $\xi^2 = 1 - \frac{1}{b}$. The corresponding points in Figures 4, 5, 6 are denoted by Q_{1-4} . In this case $\lambda_1 = \lambda_2 = 0$.

Using appropriate transformations, the normal form of (3) at the point μ reads

$$\begin{cases} \dot{y}_1 = y_2, \\ \dot{y}_2 = -b\xi y_1^2 - 2c\xi y_1 y_2 - \frac{b}{3}y_1^3 - cy_1^2 y_2. \end{cases} \tag{15}$$

If $b \neq 1$, then $\xi \neq 0$, hence \bar{x} is a non-degenerated Bogdanov-Takens equilibrium. Around such an equilibrium, system (3) is topologically equivalent with the following

$$\begin{cases} \dot{y}_1 = y_2, \\ \dot{y}_2 = \beta_1 + s\beta_2 y_2 + y_1^2 - y_1 y_2, \end{cases} \tag{16}$$

where the coefficients $\beta_1 = -\frac{16c^4 \bar{\xi}}{b^3} [a + (b-1)\bar{\xi} - b\bar{\xi}^3/3]$, $\beta_2 = 2(c^2/b^2 - 1)$ are given in [11] and $s = -1$ at Q_1, Q_4 , and $s = 1$ at Q_2, Q_3 , while $\bar{\xi} = s\sqrt{(1 - 1/b)}$. Consequently, the F-N system (3) exhibits at Q_{1-4} codimension-two Bogdanov-Takens bifurcations. In addition, in every plane $c = const.$, at the points Q_i emerge the curves HL_i corresponding to homoclinic bifurcation values [8], [11]. The equations for $HL_{1,3}$ are approximated by

$$HL_{\pm} : a = \frac{1.47(1 - b^2/c^2)^2 - 2(b-1)^2}{3b\bar{\xi}}.$$

If $b = 1$, then $\xi = 0$ and \bar{x} is a degenerated Bogdanov-Takens equilibrium of order two. Around this equilibrium, system (3) is topologically equivalent with the following

$$\begin{cases} \dot{x}_1 = x_2, \\ \dot{x}_2 = \varepsilon_1 + \varepsilon_2 x_1 + \varepsilon_3 x_2 - x_1^3 - x_1^2 x_2, \end{cases} \tag{17}$$

where

$$\varepsilon_1 = \frac{9\sqrt{3}c^3 a}{b^2\sqrt{b}}, \varepsilon_2 = \frac{9c^2(b-1)}{b^2}, \varepsilon_3 = \frac{3(c^2-b)}{b}. \tag{18}$$

Consequently, a codimension three bifurcation takes place around this point.

2.4. Double-zero with symmetry of order two bifurcation

In the following we restrict to the case $a = 0$. Consider $\mu = (1, 0, 1)$. Then the F-N system (3) possesses a triple equilibrium $\bar{x} = (0, 0)$.

Around (μ, \bar{x}) , with μ situated in the $a = 0$ plane, system (3) is topologically equivalent with the following [13]

$$\begin{cases} \dot{y}_1 = y_2, \\ \dot{y}_2 = \varepsilon_2 y_1 + \varepsilon_3 y_2 - y_1^3 - y_1^2 y_2, \end{cases} \quad (19)$$

which is a normal form for a double zero with symmetry of order two bifurcation. Denote by $\bar{Q}(1, 1)$ the point corresponding to μ in the $a = 0$ plane. Consequently, from \bar{Q} the following bifurcation curves emerge [11]:

- $HL = \left\{ (b, c), b > 1, \frac{3}{5b^2} [7c^2b - 12c^2 + 5b^2] + O(\varepsilon_2^{3/2}) = 0 \right\}$, corresponding to double homoclinic bifurcation values,

- $B = \left\{ (b, c), b > 1, \frac{3}{b^2} [(c_0 - 1)c^2b - c_0c^2 + b^2] + O(\varepsilon_2^{3/2}) = 0 \right\}$, where $c_0 \approx 0.752$, corresponding to non-hyperbolic limit cycle bifurcation values,

- $H = \left\{ (b, c), b > 1, 2c^2b - 3c^2 + b^2 = 0 \right\}$, corresponding to two simultaneously Hopf bifurcation values,

- $R^+ = \left\{ (b, c), b = 1, c^2 - b > 0 \right\}$, $R^- = \left\{ (b, c), b = 1, c^2 - b < 0 \right\}$, corresponding to cusp bifurcation values,

- $H' = \left\{ (b, c), b < 1, c^2 - b = 0 \right\}$, corresponding to Hopf bifurcation values.

3. Concluding remarks

The analysis in Section 2 allowed us to completely determine the topological type of non-hyperbolic equilibria emphasized in Section 1.

Thus, the non-hyperbolic equilibria corresponding to parameter values situated on $S_1 \cup S_2$, in regions 2, 15, 16 in Figures 5, 6, 7, are partially repulsive saddle-nodes, while for parameter values situated in regions 3, 12, they are partially attractive saddle-nodes.

The non-hyperbolic equilibria corresponding to parameter values situated on $H_1 \cup H_2$, in regions 6, 11 or at Q_6 in Figures 5, 6, 7, are slowly attractive Hopf equilibria, while for parameter values situated in regions 14, 18, 20, they are slowly repulsive Hopf equilibria.

The non-hyperbolic equilibria corresponding to parameter values situated at Q_1 or Q_3 are non-degenerated Bogdanov-Takens equilibria, while for parameter values situated at Q_7 correspond degenerated Hopf (Bautin) equilibria.

In addition, non-generic codimension-two bifurcations take place at Q_5 and Q_0 due to the coexistence of two different non-hyperbolic equilibria, namely a partially repulsive saddle-node and a slowly repulsive Hopf equilibrium at Q_5 , and two slowly repulsive Hopf equilibria at Q_0 .

Finally, the non-hyperbolic equilibria corresponding to parameter values situated at Q are degenerated saddle-node (cusp) equilibria, which are slowly attractive for $c < 1$ and slowly repulsive for $c > 1$. For $c = 1$, the point $Q = \bar{Q}$ corresponds to degenerated Bogdanov-Takens of order two equilibrium, consequently to a codimension-three bifurcation. This is the unique generic codimension-three local bifurcation exhibited by the FitzHugh-Nagumo model (3).

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