

SDL and Petri Net Performance Analysis of Communicating Systems

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Abstract

The automated functional and performance analysis of communicating systems specified with some Formal Description Technique has long been the goal of protocol engineers. In this paper we give a description of a Petri net enhanced with queued places which enables one to automatically translate an SDL specification to a net for its direct functional and performance analysis.

In particular, the new type of Petri net allows one to describe the process queues and SAVE construct, the FIFO channel queue, as well as timeouts which previously evaded temporal analysis of systems specified in SDL. The new net is called SDL-net. We analyze the performance of a modified InRes protocol using SDL-net as the modelling paradigm.

Keywords

Specification language, performance analysis, correctness analysis, Petri net, Markov process, protocol

1 MOTIVATION

The automated functional and performance analysis of communication systems specified with some Formal Description Technique has long been the goal of protocol engineers as

one can tell from the literature[BB90, DB87, Kri86, KW92, vBV88]. Although progress has been made in the functional analysis, notably through the work of Holzmann[Hol91] and West[Wes89], automated performance analysis has been less successful.

In recent years various researchers[EK87, Gra90, Tau93] have translated SDL specifications to Petri nets. The purpose of these translations was to test the correctness of the SDL specification; performance analysis, which implies that both the specification and the Petri net model involved time, was not possible. The translation by Taubert[Tau93] was the only one that used timed Petri nets, but it used time only to derive a functionally more accurate model of the SDL model and not for performance measurement.

Two techniques are mainly used to determine the functional correctness of a Petri net model: *Invariant analysis* which is a structurally-based technique, and *Coverability Graph analysis* which explores all reachable states of the system. Since the state space analysis is directly possible on SDL specifications as well, our objective of translating an SDL specification to a Petri net is to use the well known theory of Place- and Transition-invariants and their relation to functional properties such as liveness and boundedness of the corresponding net.

Performance analysis is done by deriving a Markov chain from the timed Petri net model of the specification. Time-augmented Petri nets which allow such a Markovian analysis are amongst others, Stochastic Petri nets, Generalized Stochastic Petri nets and Queueing Petri nets[Bau93].

This document also describes a translation from SDL to a Petri net which we call an SDL-net. It differs from the earlier work cited, in that the primary objective is to analyse the performance of the system so described in SDL, while realising that the model needs to be functionally correct to be able to do the analysis. Correctness analysis is a natural consequence of the proposed method.

In the next section we discuss the aspects of an SDL specification of a distributed system which need to be accounted for in particular, if a model is to reflect the performance of the system in any degree of accuracy. Subsequent sections describe the elements of the SDL-net and the document concludes with an example of modelling the InRes protocol[Hog89] in this way.

2 TIME IN SDL

The most important message delays in any communication system are the times spent waiting in a channel or signal buffer before processing. These times are orders of magnitude larger than the time taken by the processor to process a message or to place a message in, or remove a message from a buffer. Concomitant with these delays are the timeouts, which may result in retransmissions which cause further delays due to congestion. A realistic model for performance analysis must therefore model these effects as best as possible.

In the following we assume that the reader is familiar with SDL and describe only those features which are essential for a performance analysis. In SDL, time delays can occur at two points:

- Channels may delay signals in order to model transmission times. They act as FIFO queues and “serve” signals in order of their arrival.
- SDL specifications clearly allow for timeouts. On sending a signal, a timer is set to

expire at some future time unless some other specified event occurs. When it expires, it inserts a timeout signal at the end of the input queue, cf. Sect. 3, where it is processed like an ordinary signal. The statement *reset* is used to stop a timer. In this case a possibly pending, timer signal is removed from the input queue.

An example of how the timer construct may be used is shown in Fig. 1. In the transition from the start state to State_A, we set the timer to expire in 5 time units. While process ONE is in State_A, it waits until it receives either signal s_1 or s_2 , or until the timer expires, in which case it would receive T. If either s_1 or s_2 arrives before the timer expires, the timer is reset before going to State_B or State_D respectively.

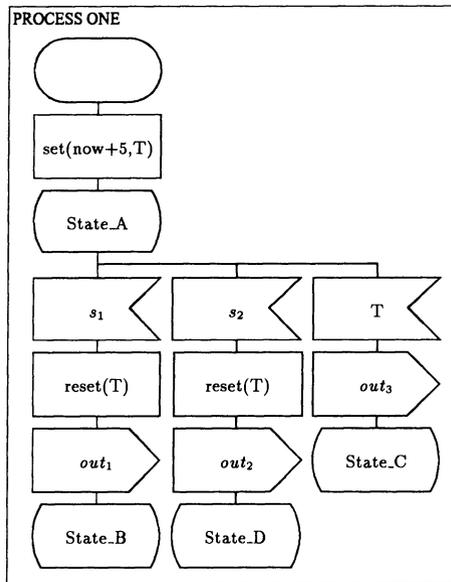


Figure 1 Timeout structure in SDL.

Timeout durations are considered to be deterministic, although in practice timers may not be of an exact fixed length, depending, for instance, on the interrupt mechanism of the system. In general, channel delays are however stochastic, since congestion along a channel may involve other processes and events outside the control of the SDL process itself. In the theory to follow, all time distributions are assumed to be Coxian, which allows one to approximate any distribution arbitrarily closely by a series of negative exponential stages.

Apart from modelling time, input queues in SDL, and their associated SAVE mechanism, are difficult to represent by conventional Petri net formalisms. The next section describes a novel way to model these.

3 THE INPUT QUEUE IN SDL

Each SDL process has a dedicated input queue where signals are queued in order of their arrival. The SAVE construct in SDL causes an exception to this FIFO scheduling strategy in that the SAVE construct allows the consumption of a signal to be delayed until one or more other signals, which arrive subsequently, have been consumed. In general an input queue operates as follows.

At every state, every signal is treated in one of the following ways:

- it is shown as an explicit input followed by a state transition,
- it is shown as a SAVE,
- it is covered by an implicit input followed by a null state transition.

An SDL process reviews signals in its input queue in the order of their arrival. An explicit, or implicit input-signal is removed from the queue and the corresponding transition executed. A signal shown in a SAVE construct is not removed and remains in its current position in the queue and the next signal in the queue is reviewed.

A single SAVE symbol can save a signal only while the process is at the state where the symbol appears, and saves it for the duration of the transition to the next state. At the next state, the symbol will be consumed via an explicit or implicit input, unless either the SAVE symbol with the signal name is repeated, or there happens to be another signal saved ahead of it in the implicit queue and available for consumption.

Several signals can be saved at each state. This can be represented by either having one SAVE construct for each signal, or by writing all the signal names in the SAVE construct. If several signals are to be saved, the semantics of the SAVE symbol implies that the order of their arrival is preserved.

An example of how the SAVE construct can be used is given in Fig. 2.

Assume that we have signals s_3, s_2, s_2, s_1 in that order of arrival. Assuming that we are in State_A, s_3 would be saved, s_2 would be explicitly consumed and the process would enter State_B. Now s_3 would be considered again, and explicitly consumed, leading to State_A. Next the second s_2 would be consumed explicitly, leading to State_B. In State_B, signal s_1 is not expected, so it is consumed implicitly, and the process remains in State_B.

In the following we describe a time-augmented Petri net for the analysis of SDL models. We call this new type of net an SDL-net.

4 SDL-NET

SDL-net is a subclass of Queueing Petri nets (QPNs) [Bau93] which are themselves Coloured Generalised Stochastic Petri nets (CGSPNs) with a new type of place, called a *queued place*. A queued place, illustrated in Fig. 3, consists of a *queue* and a *depository* for tokens which have completed their service at the queue. Tokens, when fired onto a queued place by any of its input transitions, join the queue depending upon the scheduling strategy of the queue. Tokens in a queue are not available for the transitions. After completion of its service, the token is placed onto the depository. Tokens on the depository are available to all output transitions of the queued place as in the case of an ordinary place. As in GSPNs, individual timed transitions which are enabled will race to fire after

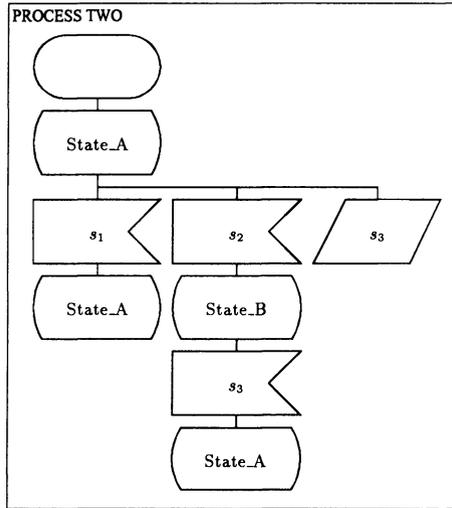


Figure 2 SAVE construct in SDL.

an exponentially distributed delay time. The firing of immediate transitions has priority over those of timed transitions.

The QPN formalism distinguishes between two types of queues: timed and immediate [Bau93]. Timed queued places act as described above. In immediate queued places the service in a queue takes place immediately. Immediate queued places make sense for specific scheduling strategies, like FIFO with blocking, where the queue only “serves” tokens when the corresponding depository is empty. We will use immediate queued places to model input queues of processes.

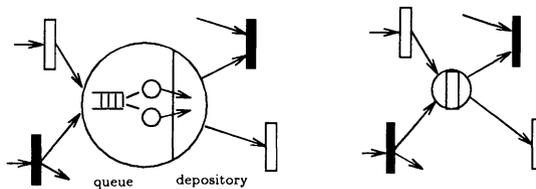


Figure 3 A (timed) queued place and its shorthand notation.

The general principle of queued places can be simplified to accurately model the SDL constructs described in Sects. 2 and 3. An immediate queued place called a *Save-place* is defined to model input queues and the associated SAVE construct in SDL, while a *Timeout-place* is defined to model the timeout mechanism in SDL – or any specification language, for that matter. Surely a Timeout-place is a timed queued place and allows for Coxian distributions in order to approximate deterministic timeouts.

Furthermore timed queued places with FIFO scheduling strategy and Coxian service distribution are used to model SDL's channel queues accurately.

4.1 Save-place

A Save-place is modelled by an immediate queued place with a modified FIFO strategy taking care of the SAVE construct.

A Save-place p has a colour set which consists of two complementary subsets $S(p)$ and $@S(p)$ such that any signal/colour $s \in S(p)$ which needs to be SAVED has a complementary colour $@s \in @S(p)$. In the sequel we drop the argument (p) in the notation since only a single place p is ever under consideration.

- A signal $s \in S$ joins a FIFO queue when fired onto the place.
- A signal $@s \in @S$ is however reserved when fired onto the place. These reserved signals only influence the scheduling of the FIFO-queue and are immediately available to the output transition set of the place. While a signal $@s \in @S$ is present, all signals of its complementary colour $s \in S$ are not served, i.e., they are held back in the FIFO queue according to the semantics of the SAVE construct.

The use of this construct is described by the example illustrated in Figs. 2 and 4 respectively.

In SDL-specifications signals in an input queue can be consumed explicitly, implicitly consumed or saved. Note from those figures that, in order to retain the advantage of Petri net analysis algorithms, we define a queueing specification to describe an input queue only to consider explicit consumption and save-operations. Consequently, tokens inside such a queued place are neither created nor destroyed; creation and destruction of tokens must be expressed by appropriate transition firings.

4.2 Timeout-place

The reader is referred to Sect. 2 and Figs. 1 and 5 for the following description of the Timeout-place. Each timer in the specification is represented by a Timeout-place (place P_T in Fig. 5). The colour set of P_T consists of the timer signal T and colour $\#T$ representing a complementary signal. The colour set of P_{IP} consists all possible input signals to process P . The colour set for all other places in this example is ω , meaning a token of arbitrary colour. It is not necessary that each timer should be represented by a unique Timeout-place. Here we will assume it to be the case, however, to simplify the discussion. The extension to the case where several timers are represented by a single Timeout-place with an appropriate colour set, is not very difficult.

- When the timer is set, a signal of colour T joins an Infinite Server queue where it is delayed for a colour dependent, randomly distributed time before being put on the depository. The distribution is Coxian with a number of exponentially distributed phases approximating a constant timeout length arbitrarily closely. Simultaneously a signal of colour ω is fired onto the place State.A.
- Should a signal of colour s_1 or s_2 arrive before the timer expires (i.e., before the signal T in place P_T is put in the depository) this signal, together with the signal ω will enable

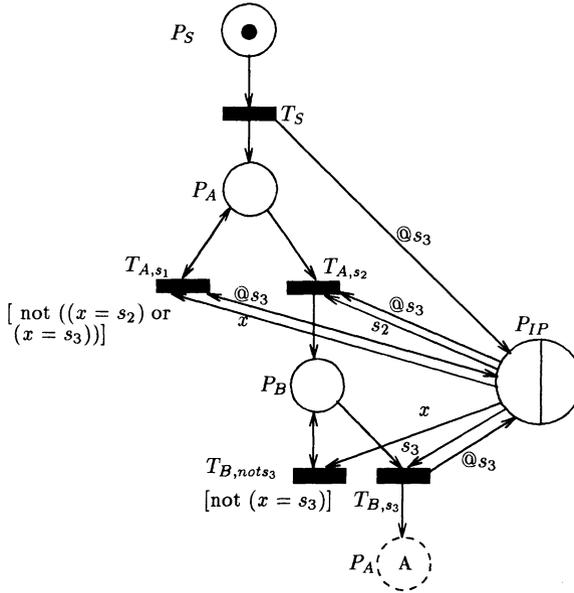


Figure 4 Equivalent representation in SDL-net using the Save-place.

the corresponding immediate transition T_{s_1} or T_{s_2} . This transition now fires a signal $\#T$ onto the Timeout-place. This resets the timer. If a token of a complementary colour $\#T$ is fired onto the Timeout-place the queue in this specific queued place immediately aborts the “service” of the signal T , and both T and $\#T$ are placed onto the depository. If there is no signal T in the queue only the token of colour $\#T$ is placed onto the depository.

- Should a signal of unexpected colour arrive, e.g. s_4 or s_5 , it is consumed by the transition with guard $[\text{not } ((x = s_1) \text{ or } (x = s_2) \text{ or } (x = s_3))]$. The Timeout-place is not affected.
- Alternatively, should the timer expire first, the signal T , together with signal ω at place State_A enables immediate transition T_{s_3} which fires, thus disabling transitions T_{s_1} and T_{s_2} .

In Fig. 5 the timer signal T has been handled separately and not been inserted into the input queue P_{IP} for reasons of simplicity. Otherwise further transitions have to be inserted to consume a single $\#T$ signal at the timed queued place P_T .

Note that a Timeout-place does not create or destroy tokens either, for the same reasons as those given in Sect. 4.1.

covered by transition invariants as well. The associated theory is well-known and will not be discussed here.

Coverability graph analysis, in turn, involves the enumeration of all reachable markings, followed by an analysis of the strongly connected components in the graph. If the net is bounded, the markings correspond to the states of the embedded Markov chain.

SDL-nets have been carefully defined to ensure that Save-places and Timeout-places conserve tokens. Consequently, invariant analysis can be performed for an SDL-net just as for a coloured Petri net by considering Save-places and Timeout-places as ordinary places marked with the colour set of the place, ignoring the queueing order of the signals.

For example, the mapping of SDL specifications to SDL-nets maps any SDL process to an identifiable subnet in the SDL-net. In such a subnet a single token circulates which denotes the state of the corresponding SDL-process. Consequently an expected result of the invariant analysis of the corresponding SDL-net is a place invariant with all weights equal to 1 for each such subnet.

It is furthermore very simple to test whether a system behaviour which is expected to be invariant, really is invariant. E.g., in a protocol specification a complete message transfer should end in the start state and thus should correspond to a transition invariant.

A more interesting result are the place invariants which cover Save-places since they give finite, upper limits for the number of tokens on such an Save-place. These limits translate directly to limits for the number of signals in an input buffer of an SDL process. Such places which are not covered by place invariants therefore suggest unbounded buffer occupancy. The main advantage of invariant analysis is that its complexity is independent of the size of the state space.

5.2 Performance analysis

There are two techniques for performance analysis of the communication system corresponding to the SDL-net model: Calculating the steady state probability distribution of the *embedded Markov Chain (MC)*, an exact analytical technique, and *simulation* which provides estimates by monitoring an animation of the SDL-net. In this section we focus on the Markov chain analysis of the SDL-net.

A state of the Markov chain is given by the markings of all ordinary places plus the state of queued places. Timeout-places, Save-places and FIFO channel queues belong to the set of queued places in an SDL-net. A state of a queued place is given by the marking of the depository and the state of the queue. Transitions from one state to another can be caused either by firing of a transition or service completion in a queued place. If the reachability graph of a given SDL-net is finite and contains a single strongly connected component, the corresponding Markov chain has a unique steady state distribution. Since SDL-nets are special cases of Queueing Petri nets the generation and numerical solution of the Markov chain is known[Bau93].

As an example of how performance measures of the original SDL specification can be obtained directly from the steady state distribution of an SDL-net, we consider the following:

Let RS denote the reachability set of a given SDL-net and let $\Pi = (\pi_1, \dots, \pi_{|RS|})$ be the steady state probability distribution of all states of SDL-net.

Let S_i be the set of states of the SDL-net corresponding to some SDL-process i in the SDL-specification. S_i corresponds to a set of places P_i of the SDL-net, where the

sum of the tokens over P_i of all reachable markings of the SDL-net is 1. Such an S_i can be determined by finding a place invariant as mentioned in Sect. 5.1. The probability distribution $P_i[m]$ over S_i can then be obtained by summing the probability distribution of the individual states in the set as follows: Let f_p be a function on the reachability set RS of a given SDL-net with steady state distribution π . Let $f_p(m) = 1$ iff m is a marking such that a token is on a place $p \in P_i$ which corresponds to a state $s \in S_i$ and $f_p(m) = 0$ otherwise.

The probability $P_i[s]$ of SDL-process i being in state $s \in S_i$ is then given by

$$P_i[s] = \sum_{m \in RS} \pi_m * f_p(m).$$

Performed for all states of all SDL-processes it can be seen on which signals processes wait most for and which part of the system slows down the rest. If several places correspond to a state, function f_p is modified appropriately.

In the same manner a performance measure for the mean, $E[x_i]$ of the number of signals x_i in the input queue of SDL-process i can be defined. Let $q_i : RS \rightarrow \mathbb{N}_0$ be the number of tokens (signals) in the queue of the Save-place of S_i , then

$$E[x_i] = \sum_{m \in RS} \pi_m * q_i(m).$$

Furthermore, let EN_j be the subset of RS in which a transition t_j with firing rate λ_j is enabled. Then, the probability r_j that t_j occurs in unit time is given by

$$r_j = \sum_{m \in EN_j} \pi_m \frac{\lambda_j}{(-q_{mm})},$$

where $-q_{mm}$ is the sum of transition rates out of marking m .

It should be clear that several other measures can be also derived, such as the mean number of retransmissions, which is given by the ratio of probabilities for service completion on the corresponding Timeout-place and for service completion of a final acknowledgement signal on the Save-place.

6 EXAMPLE

In this section we describe a typical application of an SDL-net by modelling the InRes [BHS91, Hog89] protocol described briefly in the next section.

6.1 The InRes Protocol

The InRes protocol is a simple communication protocol that describes the half-duplex communication between an *Initiator* and a *Responder*. The service is connection-orientated.

Based on work done by [TF93], a User process for the *Initiator* and a User process for the *Responder* were introduced to exercise the protocol for our analysis.

During the connection setup phase, the *Initiator* attempts to establish a connection. If

this takes too long, the *Initiator* times out and repeats the connection request. This may be done a specified number of times, after which the *Initiator* disconnects.

Upon receipt of a Connection Request signal (**ICONreq**), the *Responder* sends a Connection Indication signal to its User process. The *Responder* User may either send a Disconnect Request or it may send a Connection Indication in response. The *Responder* now sends either a DR or a CC signal to the *Initiator* which sends a **IDISind** or **ICONconf** to its User. In the latter case the *Initiator* User may now transmit data, which is acknowledged using a single bit window. Data signals are transmitted until either the *Initiator* has too many timeouts on a data signal and disconnects, or until the *Responder* User replies to a data signal with a Disconnect Request.

In order to speed up the computation without detracting from the value of the experiment for the purpose of illustrating the feasibility of the paradigm, the data-transfer phase was not modelled in its full complexity. We introduced capacities for all queues, since otherwise timer expirings always lead to an unlimited number of signals in the queues. This is a principal problem of timeout modelling in protocols, which is avoided by queue capacities. E.g., the resultant SDL-net corresponding to the *Initiator* process contains a queued place **InitiatorQ** modelling the process' input queue and a complementary place **InitiatorQCap** whose initial marking determines the capacity of the input queue. The states of the *Initiator* process are modelled by three places: **IDisconnected**, **IWait** and **IConnected**. Since the initial state of the *Initiator* process is **Disconnected**, a token will be in the place **IDisconnected** initially. This token will move between the places that represent SDL states whenever a transition fires, modelling the way that SDL processes execute. The SDL-net also comprises a Timeout-place **Timeout1**, when a Connection Confirm **CC** signal does not arrive in time, as well as a Timeout-place **Timeout2**, discussed in the next section.

6.2 Correctness Analysis

Analysis of the model was done using a modified version of QPN-Tool [BK94]. A reachability tree analysis on the SDL-net of the full InRes model revealed a deadlock in the protocol. This occurred when the *Initiator* process entered the **IConnected** state while its *User* process is waiting for a connection confirm (**ICONconf**) signal. This state corresponded with the deadlock state described in [TF93]. The suggested change was to introduce a new timeout in the *Initiator* process. This new timeout is represented by the Timeout-place **Timeout2** in the SDL-net. It was also suggested that the **IDATreq** signal be saved in states **IWait** and **IDisconnected**. These changes were introduced into the SDL-net described here.

After capacities were added to the process input queues, place invariant analysis revealed that the model was bounded. Invariant analysis also confirmed that each process is a state machine, in that it is in one state only at any one time.

6.3 Performance Analysis

Performance analysis of the reduced InRes protocol was done by solving the Markov chain with approximately 208 000 states of the corresponding SDL-net model.

Although many experiments are possible, the intention here is to illustrate some results obtained with the use of the model which are difficult to obtain using simulation.

As described in Sect. 6.1 the *Initiator* process has three states: *IDisconnected*, *IWait* and *IConnected*. *IDATreq* signals in the *InitiatorQ* are saved while the process is in either state *IDisconnected* or *IWait* and therefore remain in the *InitiatorQ*. Once, on reception of the *CC* signal, the process goes to state *IConnected*, *IDATreq* signals spend no time in the *InitiatorQ* since they are consumed immediately. Suppose the mean return delay on the channel is 22 time units.

Careful thought will reveal that there are two reasons why the *Initiator* does not reach state *IConnected* where it removes *IDATreq* signals from the *InitiatorQ* :

- If the value for *ITimeout1* is too short in comparison to the mean channel delay, the *Initiator* process attempts more, unnecessary re-connects (rather than wait for the *CC* signal to arrive) than if the timeout value were longer. This is true for a good quality channel.
- For a bad quality channel, however, these frequent attempts to reconnect are advantageous because more *CC* are lost and by asking for a reconnect the *Initiator* gets it into the *IConnected* state more frequently. In this case *IDATreq* signals spend less time in the *InitiatorQ*.

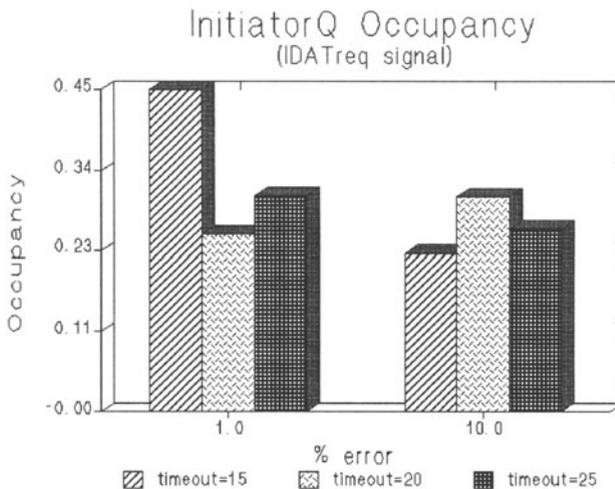


Figure 6 Channel buffer occupancy as a function of loss rate and timeout setting.

These effects are illustrated in Fig. 6 which shows the average population of the *InitiatorQ* by *IDATreq* signals for timeouts of 15, 20 and 25 time units respectively and channel error rates of 1% and 10% on a channel with a mean return delay of 22 time units.

These examples serve to illustrate typical performance measures that one may derive from an analysis of an SDL-net model of a protocol, thereby enabling the protocol engineer to design his implementation for maximum efficiency.

7 CONCLUSIONS

The report describes an approach to the combined functional and quantitative analysis (performance evaluation) of protocols and concurrent communication systems specified in SDL with the use of a new Petri net called SDL-net which offers the following advantages:

- A close correspondence of SDL states and the markings of the SDL-net. Thus the parameters for the SDL-net can be directly extracted from the parameters of the SDL model. E.g., signal delay times and timeout intervals determine the service parameters of the Save-place and Timeout-place on a one-to-one basis. Furthermore this also simplifies the interpretation of the results obtained during the analysis of the SDL-net in terms of the original SDL model.
- The structure of the SDL-net is such that it guarantees the applicability of Petri net analysis algorithms. Signals are not destroyed or created in Save-places and Timeout-places, so that very efficient invariant techniques can be used.
- The SDL specification can be translated mechanically to the corresponding SDL-net and the entire analysis process automated.

It would seem from the experience of applying the methodology to the analysis of the InRes protocol that it provides for realistic models to assist the protocol system engineer in his task of designing efficient and correct systems.

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